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NAMT

93-026

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Motion by Mean Curvature, I:  
Convergence**

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**Research Report No. 93-NA-026**

**August 1993**

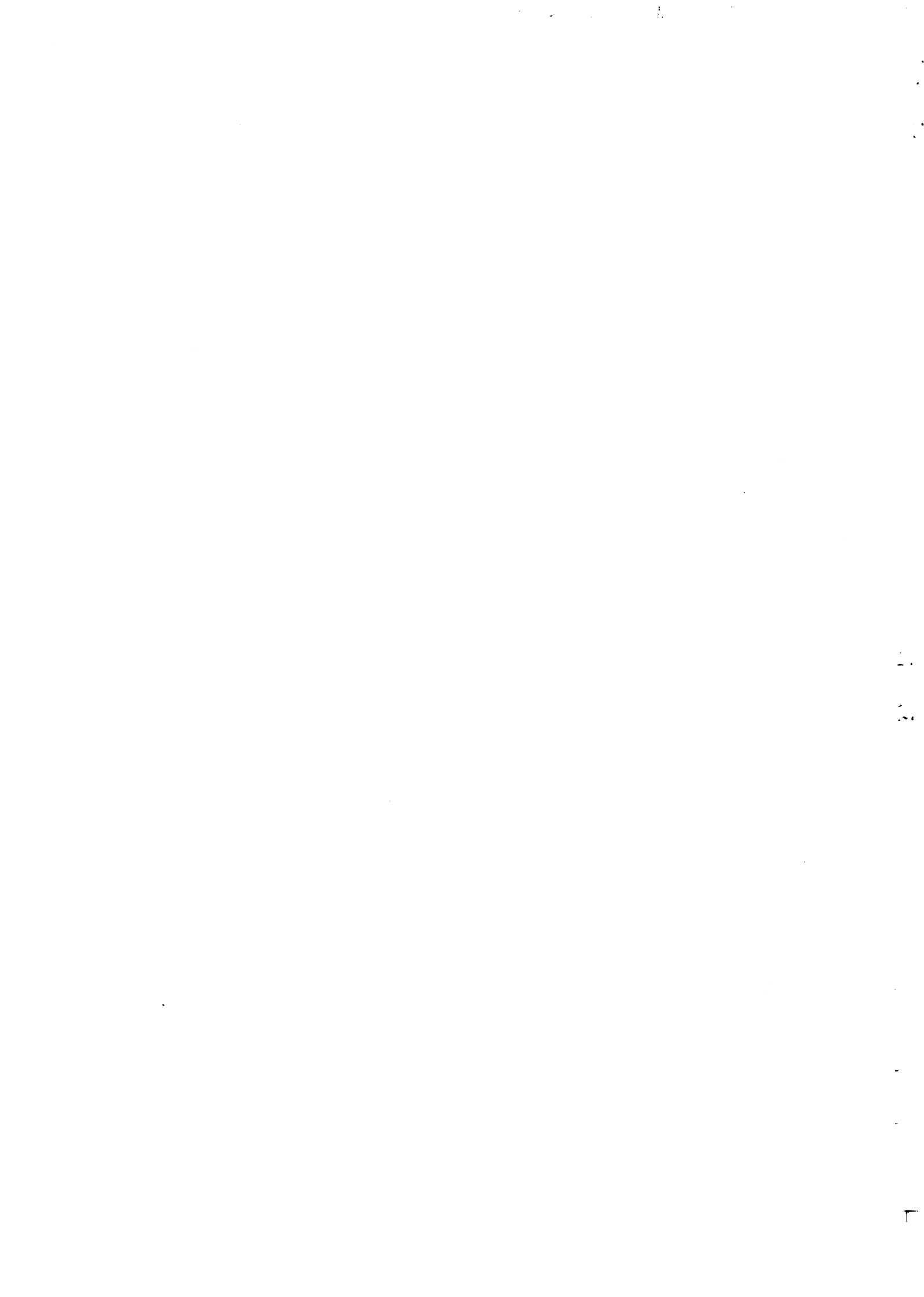
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**Ginzburg-Landau equation and motion by mean  
curvature, I: convergence.**

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**<sup>1</sup>Partially supported by the NSF grant DMS-9200801 and by the Army Research  
Office through the Center for Nonlinear Analysis**

## Abstract

In this paper we study the asymptotic behavior ( $\epsilon \rightarrow 0$ ) of the Ginzburg Landau equation:

$$u_t^\epsilon - \Delta u^\epsilon + \frac{1}{\epsilon^2} f(u^\epsilon) = 0,$$

where the unknown  $u^\epsilon$  is a real-valued function of  $[0, \infty) \times \mathcal{R}^d$ , and the given nonlinear function  $f(u) = 2u(u^2 - 1)$  is the derivative of a potential  $W(u) = (u^2 - 1)^2/2$  with two minima of equal depth. We prove that there are a subsequence  $\epsilon_n$  and two disjoint, open subsets  $\mathcal{P}, \mathcal{N}$  of  $(0, \infty) \times \mathcal{R}^d$  satisfying

$$u^{\epsilon_n} \rightarrow 1_{\mathcal{P}} - 1_{\mathcal{N}}, \quad \text{as } n \rightarrow \infty,$$

uniformly in  $\mathcal{P}$  and  $\mathcal{N}$  (here  $1_A$  is the indicator of the set  $A$ ). Furthermore the Hausdorff dimension of the interface

$$\Gamma = \text{complement of } (\mathcal{P} \cup \mathcal{N}) \subset (0, \infty) \times \mathcal{R}^d$$

is equal to  $d$  and it is a weak solution of the mean curvature flow as defined in [13, 93]. If this weak solution is unique, or equivalently if the level set solution of the mean curvature flow is "thin", then the convergence is on the whole sequence.

We also show that  $u^{\epsilon_n}$  has an expansion of the form

$$u^{\epsilon_n}(t, x) = q\left(\frac{d(t, x) + O(\epsilon_n)}{\epsilon_n}\right),$$

where  $q(r) = \tanh(r)$  is the travelling wave associated to the cubic nonlinearity  $f$ ,  $O(\epsilon) \rightarrow 0$  as  $\epsilon \rightarrow 0$ , and  $d(t, x)$  is the signed distance of  $x$  to the  $t$ -section of  $\Gamma$ .

We prove these results under fairly general assumptions on the initial data,  $u_0$ . In particular we do *not* assume that  $u^\epsilon(0, x) = q(d(0, x)/\epsilon)$ , nor that we assume that the initial energy,  $\mathcal{E}^\epsilon(u^\epsilon(0, \cdot))$ , is uniformly bounded in  $\epsilon$ .

Main tools of our analysis are viscosity solutions of parabolic equations, weak viscosity limit of Barles-Perthame, weak solutions of mean curvature flow and their properties obtained in [13] and Ilmanen's generalization of Huisken's monotonicity formula.

**Key Words:** phase transitions, viscosity solutions, weak viscosity limits, monotonicity formula, Ginzburg-Landau equation, mean curvature flow.

**AMS Classifications:** 35A05, 35K57



# 1 Introduction.

The equation

$$(1.1) \quad u_t^\epsilon - \Delta u^\epsilon + \frac{1}{\epsilon^2} f(u^\epsilon) = 0, \quad \text{in } (0, \infty) \times \mathcal{R}^d,$$

with

$$f(u) = 2u(u^2 - 1) = W'(u), \quad W(u) = (u^2 - 1)^2/2.$$

is the gradient flow of the energy functional

$$\mathcal{E}^\epsilon(u^\epsilon(t, \cdot)) = \int_{\mathcal{R}^d} \left[ \frac{\epsilon}{2} |Du^\epsilon(t, x)|^2 + \frac{1}{\epsilon} W(u^\epsilon(t, x)) \right] dx,$$

since

$$\mathcal{E}^\epsilon(u^\epsilon(t, \cdot)) = \mathcal{E}^\epsilon(u^\epsilon(0, \cdot)) - \epsilon \int_{\mathcal{R}^d} \int_0^t [u_t^\epsilon(s, x)]^2 ds dx.$$

The term  $W/\epsilon$  forces the solution  $u^\epsilon$  to take the values  $\pm 1$ . Indeed Bronsard and Kohn [19] proved that if  $\mathcal{E}^\epsilon(u^\epsilon(0, \cdot))$  is uniformly bounded in  $\epsilon$ , then  $u^\epsilon$  converges to a function  $u$  in  $L^1_{loc}$  and  $|u| = 1$  (also see section 5 in [44].) Thus the asymptotic behavior of  $u^\epsilon$  is determined by the interface  $\Gamma$  that separates the two regions  $\mathcal{P}$  and  $\mathcal{N}$  on which  $u^\epsilon$  converges  $+1$  and  $-1$ , respectively. In the limit the interface  $\Gamma$  moves by mean curvature. The precise formulation and the proof of this statement was the content of several papers [13, 28, 44, 63, 69, 77, 87], and in this paper we will prove a convergence result that is global in time, for general initial data with no assumption on the limiting geometric flow.

We continue with a description of earlier work on this problem. In 1979, Allen and Cahn proposed equation (1.1) as a model for the motion of a curved antiphase boundary [1]. In their paper Allen and Cahn also gave a short, formal argument indicating that in the limit, the interfacial velocity  $V$ , is proportional to its mean curvature,  $K$ :

$$V = K.$$

This geometric equation was proposed earlier by Mullins to model an idealized grain boundary movement [79]. For a detailed account of these models we refer the reader to the recent articles of Gurtin [58, 59] and the monographs of Fife [45] and Gurtin [60].

First justification of the convergence to the mean curvature flow was apparently given by Rubinstein, Sternberg and Keller in 1988 [87]. By an asymptotic expansion Rubinstein, Sternberg and Keller formally justified this convergence result not only for (1.1) but also for systems of equations in any space dimension. Independently, Caginalp and Fife [26] obtained the same expansion for a two dimensional phase field model which is very similar to (1.1). Since then the formal expansion techniques have been extended to several other problems, including systems of equations for which the limit is a harmonic map [88], problems with boundary conditions and non-local terms [89, 88, 84].

Later deMottoni and Schatzman [77] used the asymptotic expansion technique together with hard error estimates to prove the following result:

“Suppose that the initial data  $u_0^e$  is positive inside a smooth  $d - 1$  dimensional hypersurface  $\Gamma_0$  and negative outside of  $\Gamma_0$ . Further assume that there is a classical solution  $\Gamma_t$  of the mean curvature flow on  $t \leq T$ . Then  $u^e$  converges to +1 inside  $\Gamma_t$  and to -1 outside of  $\Gamma_t$  on  $t \leq T$ .”

The precise result requires additional technical assumptions on the regularity and the behavior of the initial data around the initial interface  $\Gamma_0$ . Independently, Chen proved the same result [28]. Chen’s method was to cleverly use appropriate sub and supersolutions of (1.1). In addition to the convergence result, deMottoni-Schatzman and Chen also analyzed the formation of the initial interface [28, 78]. Since in two space dimensions ( $d = 2$ ), there is a unique classical solution of the mean curvature flow [7, 8, 52, 56], deMottoni-Schatzman and Chen result completely describes the asymptotics of  $u^e$ . However when  $d > 2$ , the mean curvature flow develops singularities even if the initial surface  $\Gamma_0$  is smooth [57]. Hence for  $d > 2$ , the results of deMottoni-Schatzman and Chen describe only the short time behavior of  $u^e$ .

It is clear that the global-in-time, asymptotic analysis of  $u^e$  requires a weak notion of mean curvature flow. The first weak formulation of the mean curvature flow was given by Brakke using the theory of geometric measure theory [17]. Then DeGiorgi and Bronsard-Kohn proposed to use the Ginzburg-Landau equation to define a weak solution of the mean curvature flow [19], [38]. By using energy estimates, Bronsard and Kohn also proved a convergence result for radially symmetric  $u^e$ . Their approach was influenced by the  $\Gamma$ -convergence results of Modica-Mortola [76], Modica [75], Fonseca-Tartar [49], and Sternberg [95].

More recently an alternate weak formulation was proposed independently by Evans-Spruck [40] and in more generality by Chen-Giga-Goto [31]. Their formulation which is based on an idea of Ohta-Jasnow-Kawasaki [83], Sethian [91] and Osher-Sethian [82], is to view the surface moving by mean curvature as the level set of a function defined on the whole ambient space and to derive a differential equation for this function. This level set equation is degenerate

parabolic; and Evans-Spruck and Chen-Giga-Goto overcame this difficulty by using the theory of viscosity solutions of nonlinear second order partial differential equations [35, 33, 34, 68]. The level set approach was used earlier by Barles [9] to study a first order problem arising in flame propagation and was further developed by Evans-Spruck [41, 42, 43], Chen-Giga-Goto [32], Giga-Goto [53], Giga-Goto-Ishii-Sato [54], Soner [93], Barles-Soner-Souganidis [13], Ishii-Souganidis [67] and Ilmanen [64, 65]. In particular an intrinsic definition that will be used in this paper was obtained in [93]. The regularity and the other properties of the solutions and the connection between the level set solutions and Brakke's solutions were discussed in [64, 41, 42, 43]. Motions in bounded domains were studied by Sternberg-Ziemer [96], Katsoulakis-Kossioris-Reitich [69], Giga-Sato [55]. Katsoulakis-Kossioris-Reitich also obtained a convergence result for solutions of (1.1) in a bounded domain with Neumann boundary condition.

Very recently, an interesting computational algorithm for tracking the fronts moving by generalized mean curvature was proposed by Bence-Merriman-Osher [14] and the convergence of this algorithm was proved independently by Barles-Georgelin [11] and by Evans [39]. Also Gurtin-Soner-Souganidis [61] and Ohnuma-Sato [81] used the level-set approach to study a class of singular anisotropic equations. Anisotropic motions with crystalline energies introduce further difficulties. We refer the reader to the excellent survey of Taylor-Cahn-Handwerker [103] and recent articles Almgren-Taylor-Wang [5], Almgren-Taylor [4] for more information on anisotropic motions and the use of varifolds in studying them.

Equipped with the level set formulation for the mean curvature equation, Evans-Soner-Souganidis [44] proved the first global in time, multi-dimensional convergence result for (1.1). Hence the level set solution of the mean curvature flow and the solution proposed by DeGiorgi [38] and Bronsard-Kohn are the same. The convergence result of [44] was extended by Barles-Soner-Souganidis [13] to include a class of equations that are more general than (1.1). Barles-Soner-Souganidis also extended the previous work of Gärtner [51] and Barles-Bronsard-Souganidis [10] related to a different scaling in (1.1). Recently Katsoulakis and Souganidis [70] used these results to characterize the generalized mean curvature flow as the hydrodynamic limit of an infinite particle system, generalizing a previous result of Bonaventura [16]. For more information on the derivation of the mean curvature flow from certain other spin systems, we refer the reader to a recent article of DeMasi-Orlandi-Presutti-Triolo [74] and the references therein.

More precisely Evans-Soner-Souganidis proved the following. Let  $u^\epsilon$  be the unique solution of (1.1) with initial data  $u^\epsilon(0, x) = \tanh(d(x, \Gamma_0)/\epsilon)$ , where  $\Gamma_0$  is the boundary of a bounded region and  $d(x, \Gamma_0)$  is the signed distance of  $x$  to  $\Gamma_0$ . Let  $\varphi(t, x)$  be the solution of the level set equation with initial data

$\varphi(0, x) = d(x, \Gamma_0)$ . (Recall that the zero level set  $\{x : \varphi(t, x) = 0\}$  is defined by Evans-Spruck and Chen-Giga-Goto as the level set solution of the mean curvature flow.) Then  $u^\epsilon$  converges to +1 on  $\{\varphi > 0\}$  and to -1 on  $\{\varphi < 0\}$ . Hence the interface is included in the zero level set of  $\varphi$  or equivalently in the level set solution of the mean curvature flow. Moreover the interface is equal to the zero level set when it is "thin". However, when the set  $\{\varphi = 0\}$  is not "thin", the above result does not yield more information about the interface  $\Gamma$  or the limit of  $u^\epsilon$  in the region  $\{\varphi = 0\}$  (see Section 5 in [44]).

Using mainly geometric measure theory, Ilmanen [63] obtained a different convergence result for  $u^\epsilon$  that does not require the level-set to be "thin". Ilmanen proved that there are a subsequence  $\epsilon_n$  and a closed bounded set  $\Gamma \subset (0, \infty) \times \mathcal{R}^d$  satisfying, a.  $u^\epsilon$  converges to +1 or -1 locally uniformly on the complement of  $\Gamma$ , b.  $\Gamma$  is a Brakke solution of the mean curvature equation. Moreover  $\Gamma$  has Hausdorff dimension  $d$ . Ilmanen's elegant proof is quite different than those given in [13, 44], an important tool being his extension of the monotonicity formula of Huisken: Huisken [62] proved his formula for smooth solutions of the mean curvature flow and Ilmanen extended Huisken's formula to solutions of (1.1). A statement of Ilmanen's monotonicity formula for the solutions of (1.1) is given in Section 5, below. To further understand the asymptotic behavior of the solutions in the region  $\{\varphi = 0\}$ , Dang-Fife-Peletier [37] studied the stability properties of (1.1) in the plane. They considered solutions with initial interface close to the union of two axis. Since the level set solution of the mean curvature flow starting from this initial interface is "fat", the evolution of the interface is expected to be very sensitive to perturbations of the initial data. Schatzman [90] and Dang, Fife and Peletier [37] proved this instability.

Ilmanen proved his result under the assumption that  $u^\epsilon(0, x) = q(z^\epsilon(0, x)/\epsilon)$  for some function  $z^\epsilon$  satisfying  $|Dz^\epsilon(0, x)| < 1$ . In particular this assumption implies that the initial energy is uniformly bounded in  $\epsilon$ . In this paper we remove both of these assumptions. Moreover, we do not assume that the initial energy is uniformly bounded in  $\epsilon$ . Our proof combines Ilmanen's monotonicity formula with weak viscosity limits of Barles-Perthame [12]. In addition to the convergence result, this combination also allows us to obtain an asymptotic expansion of  $u^\epsilon$  of the form,

$$u^\epsilon(t, x) = q\left(\frac{d(t, x) + O(\epsilon)}{\epsilon}\right),$$

on a subsequence of  $\epsilon$ . Here  $d(t, x)$  is the signed distance of  $x$  to the  $t$ -section of the interface  $\Gamma$ .

The analysis of a model very similar to (1.1) was carried out by Chen-Elliot [30], Blowey-Elliot [15] and Nocketto-Paolini-Verdi [80]. The bi-stable potential  $W$  that they considered is equal to infinity outside the interval  $[-1, 1]$  and it is concave, quadratic inside this interval: the Euler equation related to this energy

functional is the “double obstacle problem”. Solutions of this problem take on the values  $\pm 1$  on two different regions and in the interface they solve a linear equation. Sharp error estimates for this model and numerical approximations of the mean curvature flow were obtained in [15, 30, 80]. Also Caginalp and Socolovsky [27] used (1.1) to numerically approximate the mean curvature flow.

In this paper, we will not survey the literature on systems of equations generalizing (1.1). A brief discussion of the connection between these equations and the harmonic maps is given in [63]. For information on problems with more than two phases and “triple junctions”, we refer the reader to Taylor [101, 102], Bronsard-Reitich [20], Sternberg-Ziemer [97] and the references therein. Reader interested in “slow motion” or in the Cahn-Hilliard equation should consult Alikakos-Bates-Fusco [3], Bronsard-Kohn [18], and Pego [85].

We complete our historical remarks with a very brief survey of convergence results for the phase field model for solid-liquid phase transitions in a pure material. This model was proposed by Langer [71], Fix [47], Caginalp [21, 22] and Collins-Levine [36] and more recently modified versions of the phase field equations have been derived by Penrose-Fife [86] and Fried-Gurtin [50]. Mathematically, the phase field model consists of two equations. One of these equations is very similar to (1.1) and the other is a heat equation with a source term. A rigorous asymptotic analysis of the phase field model have been proved to be difficult. Formal expansions were obtained by Caginalp-Fife [26] and Caginalp [23]. More recently Stoth [98, 99] carried out an analysis of the one dimensional and the radially symmetric problems and Caginalp-Chen [24] studied a version of the phase field model in an annular domain, with radial symmetry and special boundary conditions. For a generalized Stefan model of solidification with melting temperature proportional to curvature, Luckhaus [73] and Almgren-Wang [6] proved the convergence of a “time-step energy minimization” method. Also computational studies of the limiting equations were carried out by Strain [100] and Sethian-Strain [92]. However the convergence analysis of the multi-dimensional phase field model still remains open and further understanding of the Ginzburg-Landau equation (1.1) may prove to be useful in this direction.

After the completion of this work, Caginalp and Chen [25] announced a convergence result. They proved that the phase-field model converges to the mean curvature equation coupled with a heat equation, provided that the limiting geometric system has a smooth solution. Their result is closely related to a recent convergence result of Alikakos-Bates and Chen [2]. Alikakos-Bates and Chen proved the convergence of the Cahn-Hilliard equation to the Hele-Shaw model. Both [25] and [2] use a recent spectral estimate of Chen [29].

We continue with a brief outline of our proof.

**Outline of our proof.** We always assume that  $|u^\epsilon(0, x)| \leq 1$ . Then  $|u^\epsilon(t, x)| < 1$  for every  $(t, x) \in (0, \infty) \times \mathcal{R}^d$ . Let  $g = \tanh$ . We now introduce a new function  $z^\epsilon$  by,

$$u^\epsilon(t, x) = g\left(\frac{z^\epsilon(t, x)}{\epsilon}\right).$$

Using (1.1) we obtain,

$$(1.2) \quad z_t^\epsilon - \Delta z^\epsilon + \frac{2u^\epsilon}{\epsilon} [|Dz^\epsilon|^2 - 1] = 0.$$

Formally the above equation suggests that in the limit  $|Dz^\epsilon| = 1$ . However the only statement one can prove is the following. Let

$$\begin{aligned} z^*(t, x) &= \limsup_{\epsilon \rightarrow 0, (s, y) \rightarrow (t, x)} z^\epsilon(s, y), \\ z_*(t, x) &= \liminf_{\epsilon \rightarrow 0, (s, y) \rightarrow (t, x)} z^\epsilon(s, y) \\ \mathcal{P}_u &= \{(t, x) : \liminf u^\epsilon(t, x) > 0\}, \\ \mathcal{N}_u &= \{(t, x) : \limsup u^\epsilon(t, x) < 0\}, \end{aligned}$$

and

$$T_{est} = \inf\{T \in [0, \infty] : |z^*(t, x)|, |z_*(t, x)| < \infty, \forall (t, x) \in (0, T) \times \mathcal{R}^d\}.$$

Then  $z^*$ ,  $z_*$  are Lipschitz continuous in the  $x$ -variable with a Lipschitz constant one and satisfy the following in the viscosity sense (see Lemma 4.1, below),

$$(1.3) \quad -|Dz^*| + 1 \leq 0, \text{ in } \mathcal{N}_u \cap (0, T_{est}) \times \mathcal{R}^d,$$

$$(1.4) \quad |Dz_*| - 1 \geq 0, \text{ in } \mathcal{P}_u \cap (0, T_{est}) \times \mathcal{R}^d,$$

In general  $z^*$  and  $z_*$  are not continuous in the  $t$ -variable and therefore we do not expect them to be equal to each other. However, if  $z^*$  and  $z_*$  are upper and lower semicontinuous envelopes of the same function  $z$ , respectively, then by (1.3), (1.4) and the fact that  $z^*$ ,  $z_*$  are Lipschitz continuous with Lipschitz constant one, we can show that  $z$  is equal to the signed distance function to the interface. So it is clear that to establish this connection between  $z^*$  and  $z_*$  is an important step in the convergence analysis of  $u^\epsilon$ . But since we have not made any assumption on the initial data, the behavior of  $u^\epsilon$  on different subsequences

may be quite different and consequently  $z^*$  and  $z_*$  may not be related in any way. To establish a connection between  $z^*$  and  $z_*$ , we introduce the measure

$$\mu^\epsilon(A; t) = \int_A \left[ \frac{\epsilon}{2} |Dz^\epsilon(t, x)|^2 + \frac{1}{\epsilon} W(z^\epsilon(t, x)) \right] dx.$$

Then following Ilmanen [63], we construct a subsequence  $\epsilon_n$  and a measure  $\mu$  such that  $\mu^{\epsilon_n}(\cdot; t)$  converges to  $\mu(\cdot; t)$  for each  $t$ . This construction assumes (2.6). The precise statement of this result and a sketch of its proof are given in Section 2, below.

Now let  $\Gamma$  be the support of  $\mu$  and redefine  $z_*$  and  $z^*$  by using the subsequence  $\epsilon_n$  instead of the whole sequence  $\epsilon$ . Then the monotonicity formula of Ilmanen and a gradient estimate (Proposition 4.1, below) imply that on the complement of  $\Gamma$ ,  $z^\epsilon$  converges to  $+1$  or  $-1$  locally uniformly. It turns out that this result and (1.3), (1.4) are enough to make the connection between  $z_*$  and  $z^*$ . Indeed in Section 6 we show that  $z^*$  is equal to the upper semicontinuous envelope of  $d$  and  $z_*$  is equal to the lower semicontinuous envelope of  $d$ , where as before  $d(t, x)$  is the signed distance of  $x$  to the  $t$ -section of  $\Gamma$ . Once this result is established, then it is easy to show that  $\mathcal{P}_u$ ,  $\mathcal{N}_u$  and  $\Gamma$  are disjoint subsets of  $(0, \infty) \times \mathcal{R}^d$  and their union is the whole space. Moreover  $z^{\epsilon_n}$  converges to  $+1$  uniformly on compact subsets of  $\mathcal{P}_u$  and to  $-1$  uniformly on compact subsets of  $\mathcal{N}_u$ .

The above convergence result enables us to prove two important properties of the interface  $\Gamma$ . First we observe that the monotonicity result yields the "clearing-out" lemma (Theorem 5.1, below) and the "clearing-out" lemma implies that the Hausdorff dimension of the interface  $\Gamma$  is  $d$ . Recall that  $\Gamma$  is a subset of  $(0, \infty) \times \mathcal{R}^d$  and therefore the interface  $\Gamma$  is a "sharp". Moreover  $\Gamma$  is a weak solution of the mean curvature flow. This fact follows from (1.2) and the techniques developed by Barles, Souganidis and the author in [13]. To give the basic idea let us assume that  $|Dz^\epsilon(0, x)| \leq 1$ . Then by maximum principle and (1.2),  $|Dz^\epsilon(t, x)| < 1$ , for every  $(t, x)$  in  $(0, \infty) \times \mathcal{R}^d$ . We let  $\epsilon_n$  go to zero in (1.2) to obtain,

$$\begin{aligned} d_t - \Delta d &\geq 0 \text{ on } \mathcal{P}_u, \\ d_t - \Delta d &\leq 0 \text{ on } \mathcal{N}_u, \end{aligned}$$

of course in the viscosity sense. Since  $d$  is a distance function the above inequalities immediately imply that  $\Gamma$  is a weak solution of the mean curvature in the sense defined in [93]. The general initial condition case requires more analysis. In particular, we use the gradient estimate (Proposition 4.1, below) and the techniques developed in [13].

Organization of the paper is as follows. In section 2, we recall several known results about (1.1). The main results of this paper are stated in Section 3. In Section 4, we define and study the functions  $z^*$  and  $z_*$ . In particular we state a gradient estimate for  $z^*$ . The proof of this gradient estimate is given in the Appendix. Section 5 recalls the monotonicity result of Ilmanen and a corollary to this monotonicity result is also proved in this section. Finally proofs of the main results are completed in Section 6. In the Appendix 1, we state a result of deMottoni-Schatzman and Chen and then prove a corollary that is used in the earlier sections. The gradient estimate for  $z^*$  is proved in Appendix 2.

#### **Acknowledgments.**

I would like to acknowledge several very helpful discussions with Guy Barles, Tom Ilmanen and Takis Souganidis and I wish to thank Tom Ilmanen for sending me a preliminary copy of his manuscript [63] which influenced this work greatly. I also thank Mort Gurtin for bringing several references to my attention.



## 2 Preliminaries.

Let

$$(2.1) \quad f(u) = 2u(u^2 - 1) = W'(u), \quad W(u) = (u^2 - 1)^2/2.$$

Consider the scalar Ginzburg-Landau equation,

$$(2.2) \quad u_t^\epsilon(t, x) - \Delta u^\epsilon(t, x) + \frac{1}{\epsilon^2} f(u^\epsilon(t, x)) = 0, \quad (t, x) \in (0, \infty) \times \mathcal{R}^d,$$

with initial data

$$(2.3) \quad u^\epsilon(0, x) = u_0^\epsilon(x), \quad x \in \mathcal{R}^d.$$

We will always assume that  $u_0^\epsilon \leq 1$  and continuous on  $\mathcal{R}^d$ . Then the standard parabolic theory implies that there is a unique, bounded, real-valued

$$u^\epsilon \in C^\infty((0, \infty) \times \mathcal{R}^d) \cap C([0, \infty) \times \mathcal{R}^d)$$

satisfying (2.2) and (2.3).

Equation (2.2) is the gradient flow of the energy functional

$$(2.4) \quad \mathcal{E}^\epsilon(\psi) = \int_{\mathcal{R}^d} \left[ \frac{\epsilon}{2} |D\psi(x)|^2 + \frac{1}{\epsilon} W(\psi(x)) \right] dx.$$

Indeed by simple integration by parts and approximation arguments we can show that

$$\mathcal{E}^\epsilon(u^\epsilon(t, \cdot)) = \mathcal{E}^\epsilon(u_0^\epsilon) - \epsilon \int_{\mathcal{R}^d} \int_0^t [u_t^\epsilon(s, x)]^2 ds dx.$$

Since the above identity will not be used in this paper, we leave its derivation to the reader. For  $t > 0$  define a measure on Borel subsets of  $\mathcal{R}^d$  by

$$(2.5) \quad \mu^\epsilon(A; t) = \int_A \left[ \frac{\epsilon}{2} |Du^\epsilon(t, x)|^2 + \frac{1}{\epsilon} W(u^\epsilon(t, x)) \right] dx.$$

In view of the energy identity, if  $\mathcal{E}^\epsilon(u_0^\epsilon)$  is uniformly bounded in  $\epsilon$ , then  $\mu^\epsilon(\mathcal{R}^d; t)$  is uniformly bounded in  $\epsilon$  and  $t$ . Then we can use well known compactness of Radon measures to extract a weak\* convergent subsequence. In this paper however, we do not assume that initial energy is uniformly bounded. Instead we assume that for every  $\delta > 0$  there are positive constants  $K_\delta$  and  $\eta$  satisfying,

$$(2.6) \quad \sup \left\{ \int |\psi(x)| \mu^\epsilon(dx; t) : \epsilon \in (0, 1), t \in [\delta, 1/\delta] \right\} \\ \leq K_\delta \sup \{ |\psi(x)| e^{\eta|x|} : x \in \mathcal{R}^d \},$$

for every continuous function  $\psi$ . The above condition is satisfied if  $\mathcal{E}^\epsilon(u_0^\epsilon)$  is uniformly bounded in  $\epsilon$ , but also holds under more general hypotheses. For example, (2.6) is satisfied under the hypotheses of [28, 78], i.e., if the initial condition is three times continuously differentiable, has nonzero gradient on its zero set and its zero level set is bounded, then (2.6) holds. A proof of this fact and other sufficient conditions for (2.6) is the subject of the sequel of this paper [94].

Let  $\psi(x)$  be a compactly supported, smooth, non-negative real-valued function. Then following Ilmanen [63] we obtain,

$$\begin{aligned}
(2.7) \quad & \frac{d}{dt} \int \psi(x) \mu^\epsilon(dx; t) = -\epsilon \int \psi(x) \left( -\Delta u^\epsilon(t, x) + \frac{1}{\epsilon^2} f(u^\epsilon(t, x)) \right)^2 dx \\
& + \epsilon \int D\psi(x) \cdot Du^\epsilon(t, x) \left( -\Delta u^\epsilon(t, x) + \frac{1}{\epsilon^2} f(u^\epsilon(t, x)) \right) dx \\
& \leq -\epsilon \int \psi(x) \left( -\Delta u^\epsilon(t, x) + \frac{1}{\epsilon^2} f(u^\epsilon(t, x)) - \frac{D\psi(x) \cdot Du^\epsilon(t, x)}{2\psi(x)} \right)^2 dx \\
& + \epsilon \int |Du^\epsilon(t, x)|^2 \frac{|D\psi(x)|^2}{4\psi(x)} dx \\
& \leq C_1(\psi) \mu^\epsilon(\{\psi > 0\}; t),
\end{aligned}$$

for some constant  $C_1(\psi)$  depending only on  $\psi$ . Since  $\psi$  is compactly supported, (2.6) implies that for  $t > \delta$   $\mu^\epsilon(\{\psi > 0\}; t)$  is bounded by some constant  $C_{2,\delta}(\psi)$  depending on  $\psi$  but not on  $\epsilon$ . Therefore the map

$$t \rightarrow \int \psi(x) \mu^\epsilon(dx; t) - C_1(\psi) C_{2,\delta}(\psi) t$$

is nondecreasing on  $t > \delta$ .

Now using the weak\* compactness of Radon measures, (2.6) and the above monotonicity property in a diagonal argument we construct a subsequence  $\epsilon_n \rightarrow 0$  and a Radon measure  $\mu$  satisfying

$$(2.8) \quad \lim_{n \rightarrow \infty} \int_{\mathcal{R}^d} \psi(x) \mu^{\epsilon_n}(dx; t) = \int_{\mathcal{R}^d} \psi(x) \mu(dx; t),$$

for every  $t > 0$  and a compactly supported smooth function  $\psi$ . The above argument originates in Brakke [17] and for the details of this argument we refer to Section 5.4 in Ilmanen [63]. The density arguments together with (2.6) show that (2.8) actually holds for all continuous  $\psi(x)$  that decay faster than  $e^{-\eta|x|}$  as  $|x|$  tends to infinity (here the constant  $\eta$  is as in (2.6)). Finally, let

$$(2.9) \quad \Gamma = \text{support } \mu.$$

We will show in addition to several other properties of  $\Gamma$  that it has Hausdorff dimension  $d$  and that it is the “sharp interface” separating the two regions on which  $u^{\epsilon_n}$  converge  $-1$  and  $1$ , see Section 3 below.

Using (2.6) together with (2.7) and the techniques of Bronsard and Kohn [19], we show that there are a further subsequence, denoted by  $\epsilon_n$  again, and a function  $u$  satisfying,  $|u| = 1$  and

$$(2.10) \quad u^{\epsilon_n} \rightarrow u, \quad n \rightarrow \infty,$$

locally in  $L^1((0, \infty) \times \mathcal{R}^d)$ . Under the assumption that the initial energy is uniformly bounded in  $\epsilon$ , the above argument is given in detail in [19] (also see section 5 in [44]). Since in this paper we assume only (2.6), we need to localize the argument of Bronsard and Kohn by using (2.7). Details of this routine localization argument is left to the reader. In the remainder of this paper, we only study the properties of the sequence  $u^{\epsilon_n}$ . So we introduce the notation,

$$u^n = u^{\epsilon_n}, \quad \mu^n = \mu^{\epsilon_n}.$$

Another important object in our analysis is the travelling wave associated to the cubic nonlinearity  $f$ . Using the explicit form of  $f$ , we can easily show that

$$q(r) = \tanh(r), \quad r \in \mathcal{R}$$

is the unique solution of the equation

$$(2.11) \quad q''(r) = f(q(r)), \quad \forall r \in \mathcal{R},$$

with boundary conditions  $q(\pm\infty) = \pm 1$  and  $q(0) = 0$ . Clearly the map

$$q : \mathcal{R} \rightarrow (-1, 1)$$

is one-to-one and onto. Therefore if  $|u^n(t, x)| < 1$ , then we can define a real-valued function  $z^n$  satisfying

$$(2.12) \quad u^n(t, x) = q\left(\frac{z^n(t, x)}{\epsilon_n}\right).$$

### 3 Main Results.

Let  $u^\epsilon$  be a smooth, bounded solution of (2.1), (2.2), the sequence  $\epsilon_n$  be as in Section 2 satisfying (2.8), (2.10) and  $u^n = u^{\epsilon_n}$ . In addition to (2.6), we will always assume that

$$(3.1) \quad |u_0^\epsilon(x)| \leq 1, \quad \forall x \in \mathcal{R}^d,$$

then by maximum principle  $|u^n(t, x)| < 1$  for every  $(t, x) \in (0, \infty) \times \mathcal{R}^d$  and therefore  $z^n(t, x)$  is defined everywhere. Let us recall that sufficient conditions for (2.6) are obtained in [94]. In particular (2.6) holds if  $\mathcal{E}^\epsilon(u_0^\epsilon)$  is uniformly bounded in  $\epsilon$ .

Now we are ready to state the main results of this paper. Proofs of these results will be given in the subsequent sections.

**Theorem 3.1** *Assume (2.6) and (3.1). Let  $\Gamma$  be as in (2.9). Then there are open disjoint subsets  $\mathcal{P}$  and  $\mathcal{N}$  of  $(0, \infty) \times \mathcal{R}^d$  satisfying,*

$$(3.2) \quad \Gamma \cup \mathcal{P} \cup \mathcal{N} = (0, \infty) \times \mathcal{R}^d, \quad \Gamma \cap \mathcal{P} = \Gamma \cap \mathcal{N} = \emptyset.$$

Moreover,

$$(3.3) \quad u^n \rightarrow +1 \quad \text{uniformly in } \mathcal{P},$$

$$(3.4) \quad u^n \rightarrow -1 \quad \text{uniformly in } \mathcal{N}.$$

Let  $\Gamma_t$  be the  $t$ -section of  $\Gamma$  and  $d(t, x)$  be the signed-distance between  $x$  and  $\Gamma_t$ , i.e.,

$$(3.5) \quad d(t, x) = \begin{cases} \text{dist}(x, \Gamma_t), & (t, x) \in \mathcal{P} \\ -\text{dist}(x, \Gamma_t), & (t, x) \in \mathcal{N} \\ 0, & (t, x) \in \Gamma, \end{cases}$$

if  $\Gamma_t$  is empty, we define  $\text{dist}(x, \Gamma_t) = \infty$  for all  $x$ . Set

$$t_{\text{ext}} = \inf\{t \in [0, \infty] : \Gamma \subset [0, t] \times \mathcal{R}^d\}.$$

Let  $\psi(t, x)$  be a real-valued function. Then the *upper semicontinuous envelope* of  $\psi$  is the smallest upper semi continuous function that is greater than or equal to  $\psi$  and it is denoted by  $\psi^*(t, x)$ . Similarly the *lower semicontinuous envelope* of  $\psi$  is the largest lower semi continuous function that is less than or equal to  $\psi$  and it is denoted by  $\psi_*(t, x)$ .

**Theorem 3.2** Assume (2.6) and (3.1). Then the Hausdorff dimension of  $\Gamma$  is equal to  $d$ . Moreover in  $(0, t_{est}) \times \mathcal{R}^d$ ,  $\Gamma$  is a weak solution of the mean curvature equation in the sense defined in [93], i.e.,

$$(3.6) \quad \frac{\partial}{\partial t}[d \wedge 0] - F^*(D[d \wedge 0], D^2[d \wedge 0]) \leq 0,$$

$$(3.7) \quad \frac{\partial}{\partial t}[d \vee 0] - F_*(D[d \vee 0], D^2[d \vee 0]) \geq 0,$$

where the above inequalities are understood in the viscosity sense in  $(0, t_{est}) \times \mathcal{R}^d$ , and  $d \wedge 0 = \min\{d, 0\}$ ,  $d \vee 0 = \max\{d, 0\}$  and for a symmetric matrix  $H$  and a nonzero vector  $p \in \mathcal{R}^d$ ,

$$F(p, H) = \text{trace}[I - \frac{p \otimes p}{|p|^2}]H.$$

Our final result is a refinement of (3.3) and (3.4).

**Theorem 3.3** Assume (2.6) and (3.1). Then, for every  $(t, x) \in (0, t_{est}) \times \mathcal{R}^d$  we have,

$$(3.8) \quad \limsup_{n \rightarrow \infty, (s, y) \rightarrow (t, x)} z^n(s, y) = d^*(t, x),$$

$$(3.9) \quad \liminf_{n \rightarrow \infty, (s, y) \rightarrow (t, x)} z^n(s, y) = d_*(t, x),$$

where  $z^n$  is as in (2.12),  $d^*$  is the upper semi-continuous envelope of  $d$ , and  $d_*$  is the lower semi-continuous envelope of  $d$ . On  $(t_{est}, \infty) \times \mathcal{R}^d$  we have either one of the following,

$$(t_{est}, \infty) \times \mathcal{R}^d \subset \mathcal{P}, \quad z^* = z_* = +\infty,$$

or

$$(t_{est}, \infty) \times \mathcal{R}^d \subset \mathcal{N}, \quad z^* = z_* = -\infty.$$

In general, the distance function  $d$  is not continuous in the  $t$ -variable. However, when  $d$  is continuous at a point  $(t_0, x_0)$ , then (3.8) and (3.9) imply that  $z^n$  converges to  $d$  uniformly in a bounded neighborhood of  $(t_0, x_0)$ . In this neighborhood we have the following expansion,

$$z^n(t, x) = q\left(\frac{d(t, x) + O(\epsilon_n)}{\epsilon_n}\right).$$

## 4 Weak viscosity limits.

Recall that since  $|u_0^\epsilon| < 1$ ,  $|u^\epsilon(t, x)| < 1$  for all  $(t, x)$  and therefore  $z^\epsilon(t, x)$  is defined everywhere and solves the following parabolic equation in  $(0, \infty) \times \mathcal{R}^d$ ,

$$(4.1) \quad z_t^\epsilon - \Delta z^\epsilon + \frac{2u^\epsilon}{\epsilon} [|Dz^\epsilon|^2 - 1] = 0.$$

Set

$$w^\epsilon = |Dz^\epsilon(t, x)|^2, \quad w^n = w^{\epsilon_n} = |Dz^n(t, x)|^2,$$

where  $\epsilon_n$  is the sequence chosen in Section 2 and  $D$  denote the differentiation with respect to the spatial variable  $x$  alone. By differentiating (4.1) we obtain,

$$(4.2) \quad w_t^\epsilon + \mathcal{L}_i^\epsilon w^\epsilon + R^\epsilon(t, x, w^n) = -2 \|D^2 z^\epsilon\|^2 \text{ in } (0, \infty) \times \mathcal{R}^d,$$

where for a real number  $r$ ,  $(t, x) \in [0, \infty) \times \mathcal{R}^d$  and a smooth function  $\varphi \in C^2(\mathcal{R}^d)$ ,

$$\begin{aligned} \mathcal{L}_i^\epsilon \varphi(x) &= -\Delta \varphi(x) + \frac{4u^\epsilon(t, x)}{\epsilon} Dz^\epsilon(t, x) \cdot D\varphi(x), \\ R^\epsilon(t, x, r) &= \frac{4}{\epsilon^2} q' \left( \frac{z^\epsilon(t, x)}{\epsilon} \right) r(r-1), \end{aligned}$$

where as before  $q = \tanh$ . Observe that if  $|Dz^\epsilon(0, x)| \leq 1$  for every  $x$ , then by maximum principle  $|Dz^\epsilon(t, x)| \leq 1$  for every  $(t, x)$ . This fact was used in an essential way in [63] (see Section 4.1 in [63]). In this paper we make no such assumption on the initial data. Instead we have the following gradient estimate.

**Proposition 4.1** *Assume (3.1). Then there exists  $0 < \epsilon_0 < 1$  such that for every  $\epsilon \leq \epsilon_0$  we have,*

$$(4.3) \quad w^\epsilon(t, x) = |Dz^\epsilon(t, x)|^2 \leq 1 + \frac{2}{\ln(1/\epsilon)} \frac{(z^\epsilon(t, x))^2 + 1}{t},$$

for every  $(t, x) \in (0, \infty) \times \mathcal{R}^d$ .

We prove (3.5) by maximum principle and appropriate of supersolutions. Since this proof is somehow tangential to the main thrust of this paper, we postpone it to Appendix 2. We should also note that a “scale-invariant” version of (4.3) is also discussed in Appendix 2, Remark 8.1.

Although the proof of (4.3) is not important in the subsequent sections, (4.3) itself is an essential tool in our analysis. Note that after letting  $\epsilon$  go to zero in (4.3), we see that the right hand side of tends to one provided that  $t$  is

positive and  $z^\epsilon$  is uniformly bounded in  $\epsilon$ . Hence at least formally, in the limit as  $\epsilon$  tends to zero we recover the estimate " $|Dz^\epsilon| \leq 1$ ".

By a simple application of the Gronwall's inequality, we obtain the following corollary:

**Corollary 4.1** *Assume (3.1). Let  $\epsilon_0$  be as in Proposition 4.1. Then for every positive  $t$ , there exists a constant  $K^\epsilon(t)$  such that,*

$$(4.4) \quad |z^\epsilon(t, x) - z^\epsilon(t, y)| \leq [e^{K^\epsilon(t)|x-y|} - 1][\min\{|z^\epsilon(t, x)|, |z^\epsilon(t, y)|\}] + \frac{1 + K^\epsilon(t)}{K^\epsilon(t)},$$

where

$$K^\epsilon(t) = \sqrt{2}[t \ln(1/\epsilon)]^{-1/2}.$$

Now following Barles and Perthame [12] (also see Chapter 7 in [48]), we define two possibly extended-valued functions  $z^*$  and  $z_*$  by,

$$(4.5) \quad \begin{aligned} z^*(t, x) &= \limsup_{n \rightarrow \infty, (s, y) \rightarrow (t, x)} z^n(s, y), \\ z_*(t, x) &= \liminf_{n \rightarrow \infty, (s, y) \rightarrow (t, x)} z^n(s, y). \end{aligned}$$

We also define,

$$(4.6) \quad \begin{aligned} \mathcal{P} &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : z_*(t, x) > 0\}, \\ \hat{\mathcal{P}} &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : z_*(t, x) \geq 0\}, \\ \mathcal{N} &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : z^*(t, x) < 0\}, \\ \hat{\mathcal{N}} &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : z^*(t, x) \leq 0\}, \\ \mathcal{P}_u &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : \liminf u^n(t, x) > 0\}, \\ \mathcal{N}_u &= \{(t, x) \in (0, \infty) \times \mathcal{R}^d : \limsup u^n(t, x) < 0\}, \end{aligned}$$

and

$$T_{est} = \inf\{T \in [0, \infty] : |z^*(t, x)|, |z_*(t, x)| < \infty, \forall (t, x) \in (0, T) \times \mathcal{R}^d\}.$$

Clearly  $u^n$  satisfies (3.3) and (3.4), and in particular  $\mathcal{P} \subset \mathcal{P}_u$ ,  $\mathcal{N} \subset \mathcal{N}_u$ . One of the main objects of the rest of this paper is to show that the complement of  $\mathcal{P} \cup \mathcal{N}$  is equal to  $\Gamma$ . We will prove this fact by carefully analyzing the properties of  $z^*$  and  $z_*$ . First observe that, by passing to the limit  $\epsilon_n \rightarrow 0$  in (4.4) we obtain,

$$(4.7) \quad \begin{aligned} |z^*(t, x) - z^*(t, y)| &\leq |x - y|, \quad t \in (0, T_{est}), x, y \in \mathcal{R}^d, \\ |z_*(t, x) - z_*(t, y)| &\leq |x - y|, \quad t \in (0, T_{est}), x, y \in \mathcal{R}^d. \end{aligned}$$

However  $z^*$  and  $z_*$  may fail to be continuous in the  $t$ -variable. But  $z^*$  is upper semi continuous and  $z_*$  is lower semi continuous. Next we multiply (4.1) by  $\epsilon$  and then pass to the limit in the viscosity sense to obtain the following result.

**Lemma 4.1** *Assume (3.1). Then  $z_*$  and  $z^*$  satisfy the following differential inequalities in the viscosity sense,*

$$(4.8) \quad -|Dz^*| + 1 \leq 0, \text{ in } \mathcal{N}_u,$$

$$(4.9) \quad |Dz_*| - 1 \geq 0, \text{ in } \mathcal{P}_u.$$

**Proof:** Let  $\psi$  be a smooth function and  $(t, x) \in \mathcal{N}_u$  be a strict local maximizer of the difference  $z^* - \psi$  on  $(0, \infty) \times \mathcal{R}^d$ . Since  $(t, x) \in \mathcal{N}_u$ ,  $z^*(t, x) \leq 0$  and since  $z^* - \psi$  has a local maximum at  $(t, x)$ ,  $z^*(t, x) > \infty$ . Hence  $z^*(t, x)$  is finite and there are a subsequence  $n_k$  and local maximizers  $(t_k, x_k)$  of the difference  $z^{n_k} - \psi$  converging to  $(t, x)$  as  $k$  tends to  $\infty$ . By calculus at  $(t_k, x_k)$  we have,

$$D\psi = Dz^{n_k}, \quad \psi_t = (z^{n_k})_t, \quad D^2\psi \leq D^2z^{n_k}.$$

We use the above in (4.1) to obtain the following at  $(t_k, x_k)$ ,

$$\psi_t - \Delta\psi + \frac{2u^{n_k}}{\epsilon_{n_k}}[|D\psi|^2 - 1] \leq 0.$$

Now if  $(t, x) \in \mathcal{N}_u$ , then  $u^{n_k}(t_k, x_k) < 0$  for sufficiently large  $k$ . Then the above inequality implies that at  $(t_k, x_k)$ ,

$$-|D\psi|^2 + 1 \leq \frac{\epsilon_{n_k}}{2u^{n_k}}[\psi_t - \Delta\psi].$$

Let  $k$  go to infinity in the above inequality to obtain,

$$-|D\psi(t, x)|^2 + 1 \leq 0.$$

This completes the proof of (4.8). The other inequality (4.9) is proved exactly the same way.  $\blacksquare$

Recall that  $\mathcal{P} \subset \mathcal{P}_u$ ,  $\mathcal{N} \subset \mathcal{N}_u$ . Also the distance function is a unique viscosity solution of the Eikonal equation  $|Dd| = 1$ . These observations and



comparison results for viscosity sub and supersolutions of the Eikonal equation [66], yield the following result.

**Proposition 4.2** *Assume (3.1). Then*

$$(4.10) \quad \mathcal{N}_u = \mathcal{N}, \quad \mathcal{P}_u = \mathcal{P}.$$

Moreover,

$$(4.11) \quad \begin{aligned} z^*(t, x) &\leq -\text{dist}(x, \mathcal{N}_t^c), \quad (t, x) \in \mathcal{N}, \\ z^*(t, x) &= -\text{dist}(x, \mathcal{N}_t^c), \quad (t, x) \in \mathcal{N} \cap (0, T_{\text{ext}}) \times \mathcal{R}^d, \\ z^*(t, x) &\leq \text{dist}(x, \mathcal{N}_t), \quad (t, x) \in \mathcal{N}^c \cap (0, T_{\text{ext}}) \times \mathcal{R}^d, \end{aligned}$$

and

$$(4.12) \quad \begin{aligned} z_*(t, x) &\geq \text{dist}(x, \mathcal{P}_t^c), \quad (t, x) \in \mathcal{P}, \\ z_*(t, x) &= \text{dist}(x, \mathcal{P}_t^c), \quad (t, x) \in \mathcal{P} \cap (0, T_{\text{ext}}) \times \mathcal{R}^d, \\ z_*(t, x) &\geq -\text{dist}(x, \hat{\mathcal{P}}_t), \quad (t, x) \in \mathcal{P}^c \cap (0, T_{\text{ext}}) \times \mathcal{R}^d, \end{aligned}$$

where  $A^c$  denote the complement of  $A$  and  $A_t \subset \mathcal{R}^d$  denote the  $t$ -section of  $A \subset [0, \infty) \times \mathcal{R}^d$ .

**Proof:** The only subtle point in the proof of (4.11) and (4.12) is the fact that (4.8) and (4.9) hold only in open subsets of  $(0, \infty) \times \mathcal{R}^d$  but not necessarily at every  $t$ . Set

$$\hat{d}(t, x) = \text{dist}(x, (\mathcal{P}_u)_t^c).$$

Let  $(t_0, x_0)$  be in  $\mathcal{P}_u$  with  $t_0 < T_{\text{ext}}$ .

**case a:**  $\hat{d}(t_0, x_0) < \infty$ . Then  $\hat{d}(t, x) > 0$  in a neighborhood of  $(t_0, x_0)$  and for every  $\delta > 0$ , there is  $r(\delta) > 0$  satisfying,

$$Q_\delta = \{(t, x) : |x - x_0| < \hat{d}(t_0, x_0) - \delta, |t - t_0| < r(\delta)\} \subset \mathcal{P}_u.$$

For  $\gamma > 0$ , set

$$v(t, x) = \hat{d}(t_0, x_0) - \delta - |x - x_0| - \gamma[r(\delta) - |t - t_0|]^{-2}, \quad (t, x) \in Q_\delta.$$

Then by (4.9)

$$|Dz_*| \geq 1, \text{ and } |Dv| = 1 \text{ in } Q_\delta.$$

Recall that  $D$  denote the differentiation with respect to  $x$ -variable only and the above inequalities hold in the viscosity sense. We also have  $z_* \geq v$  on the boundary of  $Q_\delta$  and  $v$  is continuous in  $Q_\delta$ . Hence by a comparison result for viscosity sub and supersolutions (see for example [12, 66, 34]) we have  $z_* \geq v$  in  $Q_\delta$  for every positive  $\delta$  and  $\gamma$ . Let  $\delta$  and  $\gamma$  go to zero to conclude that  $z_*(t_0, x_0) \geq \hat{d}(t_0, x_0)$ .

case b:  $\hat{d}(t_0, x_0) = \infty$ . Then for every  $N$ , there is  $r_N > 0$  such that,

$$Q_N = \{(t, x) : |x - x_0| < N, |t - t_0| < r_N\} \subset \mathcal{P}_u.$$

Set

$$v_N(t, x) = N - |x - x_0| - \gamma[r_N - |t - t_0|]^{-2}, \quad (t, x) \in Q_N.$$

Now proceed as in the previous case to show that  $z_*(t_0, x_0) \geq v_N(t_0, x_0) = N$  for every  $N$ . Hence

$$z_*(t_0, x_0) = \hat{d}(t_0, x_0) = \infty.$$

Hence we have proved that

$$z_*(t, x) \geq \hat{d}(t, x) = \text{dist}(x, (\mathcal{P}_u)_t^c), \quad \forall (t, x) \in \mathcal{P}_u.$$

Now suppose that  $(t, x) \in \mathcal{P}_u$ . Then  $\hat{d}(t, x) > 0$ . Therefore  $z_*(t, x) > 0$ , and  $(t, x) \in \mathcal{P}$ . Since by construction  $\mathcal{P}$  is a subset of  $\mathcal{P}_u$ , we conclude that they are equal to each other. In summary, we have proved that

$$\mathcal{P} = \mathcal{P}_u, \quad z_*(t, x) \geq \text{dist}(x, \mathcal{P}_t^c), \quad \forall (t, x) \in \mathcal{P}.$$

Moreover on  $(0, T_{\text{exit}}) \times \mathcal{R}^d$ , by (4.7) we have,

$$\begin{aligned} z_*(t, x) &\leq \text{dist}(x, \mathcal{P}_t^c), \quad \forall (t, x) \in \mathcal{P} \cap (0, T_{\text{exit}}) \times \mathcal{R}^d, \\ z_*(t, x) &\geq -\text{dist}(x, \hat{\mathcal{P}}_t), \quad \forall (t, x) \in \mathcal{P}^c \cap (0, T_{\text{exit}}) \times \mathcal{R}^d. \end{aligned}$$

Combining above inequalities to obtain (4.12). The second part of (4.10) and (4.11) are proved similarly. ■

**Remark 4.1.** Suppose that there are a subsequence  $n_k$  and an open subset  $Q$  of  $(0, \infty) \times \mathcal{R}^d$  such that as  $k$  tends to infinity,  $u^{n_k} \rightarrow +1$  uniformly on compact subsets of  $Q$ . Then by restricting the arguments of Lemma 4.1 and Proposition 4.2 to the subsequence  $n_k$ , we can show that

$$\liminf_{k \rightarrow \infty, (s,y) \rightarrow (t,x)} z^{n_k}(s,y) \geq \text{dist}(x, Q_t),$$

for all  $(s, x) \in Q$ . Clearly a similar result holds if  $u^{n_k} \rightarrow -1$  uniformly on compact subsets of an open set  $Q$ .

## 5 Monotonicity Formula.

In this section we recall a remarkable monotonicity formula derived by Ilmanen [63]. Ilmanen's formula is an extension of the Huisken's monotonicity formula for smooth manifolds moving by their mean curvature [62]. In our analysis the monotonicity formula is essential in connecting the subsequences on which  $z_*(t, x)$  and  $z^*(t, x)$  are achieved. Following the notation and the terminology of Section 3 in [63], we fix a 'blow-up' point  $(y, s)$  and set

$$(5.1) \quad \rho(t, x; y, s) = \frac{1}{(4\pi(s-t))^{(d-1)/2}} \exp\left(-\frac{|x-y|^2}{4(s-t)}\right), \quad x \in \mathcal{R}^d, t < s.$$

For  $t < s$ , Ilmanen proved the following (see Section 3.3 in [63]).

$$(5.2) \quad \frac{d}{dt} \int \rho(t, x; y, s) \mu^\epsilon(dx; t) \leq \frac{1}{2(s-t)} \int \rho(x, t; y, s) \xi^\epsilon(dx; t),$$

where

$$(5.3) \quad \begin{aligned} \xi^\epsilon(A; t) &= \int_A \left[ \frac{\epsilon}{2} |Du^\epsilon(t, x)|^2 - \frac{1}{\epsilon} W(u^\epsilon(t, x)) \right] dx, \\ &= \int_A \left[ \frac{1}{2\epsilon} \left( q' \left( \frac{z^\epsilon(t, x)}{\epsilon} \right) \right)^2 \left[ |Dz^\epsilon(t, x)|^2 - 1 \right] \right] dx. \end{aligned}$$

In the above derivation we used the identity  $(q')^2 = 2W(q)$ . Set

$$\alpha^\epsilon(t; s, y) = \int \rho(t, x; y, s) \mu^\epsilon(dx; t).$$

Observe that if  $|Dz^\epsilon(t, x)|^2 \leq 1$ , then  $\xi$  is negative and therefore  $\alpha^\epsilon(t; s, y)$  is nonincreasing in  $t$ . In general the gradient estimate (4.3) yields the following analogue of this monotonicity result. Let  $\epsilon_0$  be as in Proposition 4.2.

**Corollary 5.1** *Assume (3.1). Then for all  $(s, y) \in (0, \infty) \times \mathcal{R}^d$ ,  $0 < \epsilon \leq \epsilon_0$  and  $0 < \delta \leq t \leq \tau < s$ , we have,*

$$(5.4) \quad \begin{aligned} \alpha^\epsilon(\tau; s, y) &\leq \alpha^\epsilon(t; s, y) \left( \frac{s-t}{s-\tau} \right)^{K(\epsilon, \delta)} \\ &+ 4\epsilon\sqrt{\pi} K(\epsilon, \delta) \int_t^\tau \left( \frac{s-\tau}{s-r} \right)^{K(\epsilon, \delta)} \frac{dr}{\sqrt{s-r}}, \end{aligned}$$

where

$$K(\epsilon, \delta) = [\delta \ln(1/\epsilon)]^{-1}.$$

In particular, for every  $0 < t \leq r < s$ , we have,

$$\int \rho(r, x; y, s) \mu(dx; r) \leq \int \rho(t, x; y, s) \mu(dx; t),$$

where  $\mu$  is the limit of  $\mu^n$  (see (2.8)).

**Proof:** Ilmanen's monotonicity formula (5.2), (5.3) and the gradient estimate (4.3) imply that,

$$\begin{aligned} \frac{d}{dt} \alpha^\epsilon(t; s, y) &\leq \frac{1}{2(s-t)} \int \rho(t, x; s, y) \frac{1}{2\epsilon} (q'(\frac{z^\epsilon(t, x)}{\epsilon}))^2 [|Dz^\epsilon(t, x)|^2 - 1] dx, \\ &\leq [\ln(1/\epsilon)t(s-t)]^{-1} \int \rho(t, x; s, y) \frac{1}{2\epsilon} (q'(\frac{z^\epsilon(t, x)}{\epsilon}))^2 [(z^\epsilon(t, x))^2 + 1] dx. \end{aligned}$$

Observe that

$$[\frac{1}{2\epsilon} (q'(\frac{z^\epsilon(t, x)}{\epsilon}))^2] dx \leq \mu^\epsilon(t, dx),$$

and

$$|q'(r)r| \leq 4 \forall r \Rightarrow (q'(\frac{z^\epsilon}{\epsilon}))^2 (z^\epsilon)^2 \leq 4\epsilon^2.$$

Hence we have

$$\frac{d}{dt} \alpha^\epsilon(t; s, y) \leq [\ln(1/\epsilon)t(s-t)]^{-1} \int \rho(t, x; s, y) [\mu^\epsilon(dx, t) + 2\epsilon dx].$$

Since  $\int \rho(t, x; s, y) dx = \sqrt{4\pi(s-t)}$  and  $t \geq \delta$ ,

$$\frac{d}{dt} \alpha^\epsilon(t; s, y) \leq [\ln(1/\epsilon)\delta(s-t)]^{-1} [\alpha^\epsilon(t; s, y) + 4\epsilon\sqrt{\pi(s-t)}].$$

Finally an application of Gronwald's inequality yields (5.4). ■

We are ready to prove a slight extension of the "clearing-out" lemma proved by Ilmanen [63]. Our proof follows very closely Section 6.1 in [63].

**Theorem 5.1 (Ilmanen)** *Assume (3.1) and (2.6). Let  $\mu$  be the limit of  $\mu^n$  (c.f. (2.8)). Then for every  $\delta > 0$  there exists  $\eta(\delta) > 0$  such that if*

$$(5.5) \quad \int \rho(t, x; s_0, y_0) \mu(dx; t) \leq \eta(\delta),$$

for some  $(s_0, y_0)$  and  $t$  satisfying  $\delta \leq t < s_0 \leq t + 1 < 1/\delta$ , then there is a neighborhood  $O$  of  $(s_0, y_0)$  such that,

$$(5.6) \quad z_+(s, y) > 0, \quad \forall (s, y) \in O, \quad \text{or} \quad z^-(s, y) < 0, \quad \forall (s, y) \in O,$$

and  $v^n \rightarrow \pm 1$  uniformly in this neighborhood. In particular, if (5.5) holds then

$$(s_0, y_0) \in \mathcal{P} \cup \mathcal{N},$$

and

$$(s_0, y_0) \notin \overline{\{(t, x) : x \in \text{support } \mu(\cdot; t)\}}.$$

**Proof:** Assume  $t \in [\delta, 1/\delta]$ . All the constants in this proof depend on  $\delta$ , but we suppress this dependence.

1. Suppose that

$$\alpha(t; s_0, y_0) = \int \rho(t, x; s_0, y_0) \mu(dx; t) \leq \eta,$$

for some  $\eta$  that will be chosen later in this proof. Set  $\alpha^n = \alpha^{e_n}$ . Then by the continuity of  $\rho$ , assumption (2.6) and the convergence of  $\mu^n(\cdot; t)$  for every  $t$  (c.f. (2.8)), there are an integer  $n_0$  and a neighborhood  $U$  of  $(s_0, y_0)$  satisfying,

$$\alpha^n(t; s, y) \leq 2\eta, \quad (s, y) \in U, n > n_0.$$

Here  $U$  and  $n_0$  may depend on  $\eta$  and  $t, s_0, y_0$ .

2. Use (5.4) with  $r = s - \epsilon_n^2$  to construct a constant  $k_1$  (independent of  $\eta$  and  $n$ ) and  $n(\eta) \geq n_0$  satisfying,

$$\alpha^n(s - \epsilon_n^2; s, y) \leq k_1 \eta, \quad \forall (s, y) \in U, n > n(\eta).$$

Let  $B_{\epsilon_n}(y)$  be the sphere centered at  $y$  with radius  $\epsilon_n$ . Then, we have,

$$(5.7) \quad \begin{aligned} \mu^n(B_{\epsilon_n}(y); s - \epsilon_n^2) &\leq \left[ \min_{s \in B_{\epsilon_n}(y)} \{\rho(s - \epsilon_n^2, x; s, y)\} \right]^{-1} \alpha^n(s - \epsilon_n^2; s, y) \\ &\leq k_2 \eta \epsilon_n^{d-1}, \quad \forall (s, y) \in U, n > n(\eta). \end{aligned}$$

Observe that the constant  $k_2$  is independent of  $\eta$ .

Now define,

$$\beta = \liminf_{n \rightarrow \infty} \inf_{(s,y) \in U} |u^n(s - \epsilon_n^2, y)|$$

Let  $c$  be any number sufficiently close to one, say  $(7/8)$ . In the next step we will show that for a carefully chosen value of  $\eta$ ,  $\beta \geq c = (7/8)$ .

3. Suppose that  $\beta < (7/8)$ . Then there are a subsequence  $n_k$  and  $(s_k, y_k) \in U$  satisfying,

$$\begin{aligned} |u^{n_k}(s_k - \epsilon_{n_k}^2, y_k)| &< (7/8) \\ \Rightarrow |z^{n_k}(s_k - \epsilon_{n_k}^2, y_k)| &< \epsilon_{n_k} q^{-1}(7/8), \end{aligned}$$

for every  $k$ . Using (4.4) we conclude that there is  $k_0$ , independent of  $\eta$ , such that for  $k \geq k_0$  we have,

$$|z^{n_k}(s_k - \epsilon_{n_k}^2, x)| < \epsilon_{n_k} [q^{-1}(7/8) + 2], \quad \forall x \in B_{\epsilon_{n_k}}(y_k).$$

Consequently  $W(u^{n_k}(s_k - \epsilon_{n_k}^2, x)) > W(q[q^{-1}(7/8) + 2])$ , and

$$\begin{aligned} \mu^{n_k}(B_{\epsilon_{n_k}}(y_k); s - \epsilon_{n_k}^2) &> \int_{B_{\epsilon_{n_k}}(y_k)} \frac{W(u^{n_k}(s_k - \epsilon_{n_k}^2, x))}{\epsilon_{n_k}} dx \\ (5.8) \qquad \qquad \qquad &> \omega_d W(q[q^{-1}(7/8) + 2]) (\epsilon_{n_k})^{d-1}, \end{aligned}$$

where  $\omega_d$  is the volume of the  $d$  dimensional unit sphere. Now choose

$$\eta = \omega_d W(q[q^{-1}(7/8) + 2]) / k_2,$$

where  $k_2$  is as in Step 2. With this choice of  $\eta$ , (5.8) contradicts (5.7) for sufficiently large  $k$ . Hence  $\beta \geq (7/8)$ .

4. Since  $\beta \geq (7/8)$  and  $u^n$  is continuous, for a sufficiently large  $n$  we have either  $u^n(s - \epsilon_n^2, y) \geq (3/4)$  for all  $(s, y) \in U$  or  $u^n(s - \epsilon_n^2, y) \leq -(3/4)$  for all  $(s, y) \in U$ . We also know that the sequence  $u^n$  is convergent (c.f. (2.10)). Hence we conclude that, we have either  $u^n(s - \epsilon_n^2, y) \geq (3/4)$  for all sufficiently large  $n$  and  $(s, y) \in U$  or  $u^n(s - \epsilon_n^2, y) \leq -(3/4)$  for all sufficiently large  $n$  and  $(s, y) \in U$ . Without loss of generality suppose that we have the first case. Then by a result of deMottoni-Schachtman [78] or Chen [28] (see Corollary 7.1, below), we conclude that  $u^n$  converges to one uniformly on  $U$ . Hence

$$U \subset \mathcal{P}_u = \mathcal{P},$$

and by (4.11),

$$z_*(s, y) > 0, \forall (s, y) \in U.$$

The other conclusions of the theorem easily follows from (5.6). ■



## 6 Conclusion.

In this section we complete the proofs of Theorems 3.1, 3.2 and 3.3.

**Proof of Theorem 3.1** Let  $\mathcal{P}$  and  $\mathcal{N}$  be as in (4.6). Then clearly they are disjoint.

1. Suppose that  $(s_0, y_0) \notin \Gamma$  and  $s_0 > 0$ . Since  $\rho(t, x; s_0, y_0)$  decays exponentially as  $|x|$  tends to infinity, (2.8) holds with  $\psi(x) = \rho(t, x; s_0, y_0)$  for every  $t < s_0$ . Moreover  $\rho(t, x; s_0, y_0)$  tends to zero exponentially fast as  $t$  tends to  $s_0$ , for all  $x \neq y_0$ . Using these facts and (2.6), it is easy to show that (5.5) is satisfied at every  $t$  sufficiently close to  $s_0$ . Hence by Theorem 5.1, (5.6) holds and consequently

$$(s_0, y_0) \in \mathcal{P} \cup \mathcal{N}.$$

2. Suppose that  $(s_0, y_0) \in \mathcal{P}$  and  $s_0 > 0$ . Then there are  $\delta > 0$ ,  $\alpha > 0$  and  $n_0 > 0$  satisfying,

$$(6.1) \quad z^n(s, y) > \alpha, \quad \forall |s - s_0|, |y - y_0| \leq \delta, \quad n > n_0.$$

Definition of  $\mu^n$  and the gradient estimate (4.3) imply that for sufficiently large  $n$  and  $|s - s_0| \leq \delta$ ,

$$\begin{aligned} \mu^n(B_\delta(y_0); s) &= \int_{B_\delta(y_0)} \frac{1}{2\epsilon_n} (q'(\frac{z^n(t, x)}{\epsilon_n}))^2 [|Dz^n(t, x)|^2 + 1] dx \\ &\leq \int_{B_\delta(y_0)} \frac{1}{2\epsilon_n} (q'(\frac{z^n(t, x)}{\epsilon_n}))^2 [|z^n(t, x)|^2 + 3] dx. \end{aligned}$$

Let  $\alpha$  be as in (6.1). Then for sufficiently small  $\epsilon$ , the function

$$z \rightarrow (q'(\frac{z}{\epsilon}))^2 [z^2 + 3]$$

is decreasing on  $z > \alpha$ . Therefore, for  $|s - s_0| < \delta$ ,

$$\lim_{n \rightarrow \infty} \mu^n(B_\delta(y_0); s) \leq \lim_{n \rightarrow \infty} \int_{B_\delta(y_0)} \frac{1}{2\epsilon_n} (q'(\frac{\alpha}{\epsilon_n}))^2 [\alpha^2 + 3] dx = 0.$$

Hence  $(s_0, y_0) \notin \Gamma$ .

3. Suppose that  $(s_0, y_0) \in \mathcal{P}$  and  $s_0 > 0$ . Then the same argument as in the previous step yields that  $(s_0, y_0) \notin \Gamma$ . ■

We need the following result in the proof of Theorem 3.3. Recall that  $B_\delta(x)$  is the  $d$  dimensional sphere centered at  $x$  with radius  $\delta$ .

**Lemma 6.1** *Assume (3.1) and (2.6).*

**a)** *Suppose that  $z^*(t, x) > 0$  at some  $(t, x) \in (0, \infty) \times \mathcal{R}^d$ . Then there is a positive constant  $\delta$  satisfying,*

$$z_*(s, y) \geq \delta, \quad \forall (s, y) \in (t, t + \delta] \times B_\delta(x).$$

**b)** *Suppose that  $z_*(t, x) < 0$  at some  $(t, x) \in (0, \infty) \times \mathcal{R}^d$ . Then there is a positive constant  $\delta$  satisfying,*

$$z^*(s, y) \leq -\delta, \quad \forall (s, y) \in (t, t + \delta] \times B_\delta(x).$$

**Proof:** We will prove only part a. Proof of part b is similar.

1. Since  $z^*(t, x) = \gamma > 0$ , the definition  $z^*$  implies that there are a subsequence  $n_k$  and  $(t_k, x_k) \rightarrow (s, x)$  satisfying,

$$z^{n_k}(t_k, x_k) \geq \gamma/2.$$

Since  $x_k \rightarrow x$ , in view of (4.4) there is a neighborhood  $U$  of  $x$  such that for sufficiently large  $k$ ,

$$z^{n_k}(t_k, y) \geq \gamma/4 \quad \forall y \in U.$$

Hence for sufficiently large  $k$ ,

$$u^{n_k}(t_k, y) \geq q(\gamma/4\epsilon) \quad \forall y \in U.$$

2. By deMottoni-Schatzman and Chen result [28, 78] (see Corollary 7.1, below), there is  $\delta > 0$  such that  $u^{n_k} \rightarrow +1$  uniformly on every compact subset of  $(t, t + \delta] \times B_{3\delta}(x)$ . Since this convergence is only on a subsequence, we can not yet use (4.12). But by Remark 4.1 we have,

$$\liminf_{k \rightarrow \infty, (s', y') \rightarrow (s, y)} z^{n_k}(s', y') \geq \delta,$$

for all  $(s, y) \in (t, t + \delta] \times B_{2\delta}(x)$ .

3. Arguing as in Step 2 of the previous proof, for  $s \in (t, t + \delta]$  we obtain,

$$\lim_{n \rightarrow \infty} \mu^{n_s}(B_{2\delta}(x); s) \leq \lim_{n \rightarrow \infty} \int_{B_{2\delta}(x)} \frac{1}{2\epsilon_{n_s}} (g'(\frac{\delta}{\epsilon_{n_s}}))^2 [\delta^2 + 3] dx = 0.$$

Recall that  $\mu$  is the limit of  $\mu^n$  (c.f. (2.8)). Hence  $\mu(B_{2\delta}(x); s) = 0$  for all  $s \in (t, t + \delta]$  or equivalently

$$(t, t + \delta] \times B_{2\delta}(x) \cap \Gamma = \emptyset.$$

Then by Theorem 3.1,

$$(t, t + \delta] \times B_{2\delta}(x) \subset \mathcal{P} \cup \mathcal{N}.$$

Since  $u^n$  is convergent in  $L^1$  (c.f. (2.10)) and  $u^{n_s}$  converges to one uniformly in  $(t, t + \delta] \times B_{2\delta}(x)$ , we conclude that

$$(t, t + \delta] \times B_{2\delta}(x) \subset \mathcal{P}.$$

We complete the proof of part a by using (4.12) in  $(t, t + \delta] \times B_\delta(x)$ . ■

We continue with the proof of Theorem 3.3. The above lemma essentially shows that the boundaries of the sets  $\mathcal{P} = \{z_* > 0\}$  and  $\mathcal{N} = \{z^* < 0\}$  in  $(0, \infty) \times \mathcal{R}^d$  are equal. This observation and Proposition 4.2 will be used to complete the proof of Theorem 3.3.

**Proof of Theorem 3.3.**

1. Suppose that  $z_*(t, x) > 0$  and  $t < T_{est}$ . Then by Proposition 4.2, (4.12),

$$z_*(t, x) = \text{dist}(x, \mathcal{P}_t^c).$$

Moreover by (3.2) we have  $\mathcal{P}_t^c = \Gamma_t \cup \mathcal{N}_t$ . Hence  $\text{dist}(x, \mathcal{P}_t^c) \leq d(t, x)$ . Let  $y \in \mathcal{P}_t^c$  be such that,  $\text{dist}(x, \mathcal{P}_t^c) = |x - y|$ . Since  $z_*$  is Lipschitz continuous in the  $x$ -variable,  $z_*(t, y) = 0$ . Recall that  $y \in \mathcal{P}_t^c = \Gamma_t \cup \mathcal{N}_t$  and  $z^*(t, x) \geq z_*(t, x) = 0$ . Therefore  $y \in \Gamma_t$  and consequently,

$$\begin{aligned} d(t, x) &\leq |x - y| = \text{dist}(x, \mathcal{P}_t^c) \leq d(t, x) \\ &\Rightarrow z_*(t, x) = d(t, x). \end{aligned}$$

Also  $(t, x) \in \mathcal{P}$  and therefore in a neighborhood of  $(t, x)$  we have  $d = g$ , where  $g(t, x)$  is the distance between  $x$  and the  $t$ -section of the closed set  $\Gamma \cup \mathcal{N}$ . Then

it is elementary to show that  $g$  is lower semi continuous and since  $d = g$  in a neighborhood of  $(t, x)$  we have,

$$d_*(t, x) = g_*(t, x) = g(t, x) = d(t, x).$$

Hence we have proved (3.9) when  $z_*(t, x) > 0$  and  $t < T_{est}$ . Similarly we can show that,

$$d^*(t, x) = d(t, x) = z^*(t, x),$$

provided that  $z^*(t, x) < 0$  and  $t < T_{est}$ .

2. Suppose that  $z_*(t, x) = 0$  and  $t < T_{est}$ . Since  $0 = z_*(t, x) \leq z^*(t, x)$ ,  $(t, x)$  is not in  $\mathcal{P} \cup \mathcal{N}$ . Therefore by (3.2)  $x \in \Gamma_t$  and  $d(t, x) = 0$ . We now claim that  $d(t, x) = d_*(t, x)$ . Indeed if there is a sequence  $(t_k, x_k) \rightarrow (t, x)$  satisfying

$$\liminf_{k \rightarrow \infty} d(t_k, x_k) < 0.$$

Then by the previous step and (4.11),  $z^*(t_k, x_k) = d(t_k, x_k)$  for all  $k$ . Hence

$$z_*(t, x) \leq \liminf_{k \rightarrow \infty} z^*(t_k, x_k) = \liminf_{k \rightarrow \infty} d(t_k, x_k) < 0.$$

But this contradicts with the hypotheses of this step;  $z_*(t, x) = 0$ . Therefore  $d(t, x) = d_*(t, x) = 0$ , whenever  $z_*(t, x) = 0$ . Combining with the first step we conclude that,

$$(6.2) \quad z_*(t, x) = d(t, x) = d_*(t, x), \quad \forall (t, x) \text{ satisfying } z_*(t, x) \geq 0.$$

3. We proceed as in the previous step to obtain,

$$(6.3) \quad z^*(t, x) = d(t, x) = d^*(t, x), \quad \forall (t, x) \text{ satisfying } z^*(t, x) \leq 0.$$

4. Suppose that  $z_*(t, x) < 0$  and  $t < T_{est}$ . Set

$$\hat{d}(t, x) = \liminf_{(s, y) \rightarrow (t, x), s > t} d(s, y), \quad \gamma = \text{dist}(x, \hat{\mathcal{P}}_t),$$

where  $\hat{\mathcal{P}}$  is as in (4.6). For  $\epsilon > 0$ , we use Lemma 6.1b together with a compactness argument to construct  $\delta > 0$  satisfying,

$$(6.4) \quad (t, t + \delta] \times B_{\gamma - \epsilon}(x) \subset \mathcal{N}.$$

Hence,

$$\liminf_{(s,y) \rightarrow (t,x), s>t} \text{dist}(y, \Gamma_s) \geq \gamma,$$

and therefore,

$$\text{dist}(x, \hat{P}_t) = \gamma \leq \liminf_{(s,y) \rightarrow (t,x), s>t} \text{dist}(y, \Gamma_s) = -\hat{d}(t, x).$$

Since by (4.12)  $z_*(t, x) \geq -\gamma$ ,

$$(6.5) \quad z_*(t, x) \geq \hat{d}(t, x).$$

We also have

$$z_*(t, x) \leq (z^*)_*(t, x) \leq \liminf_{(s,y) \rightarrow (t,x), s>t} z^*(s, y).$$

Step 3 and (6.4) imply that for every  $s$  sufficiently close to  $t$  and  $s > t$  we have,  $z^*(s, x) = d(s, x)$ . We use this in the above inequality and then recall (6.5) to obtain,

$$z_*(t, x) = \hat{d}(t, x), \quad \forall (t, x) \text{ satisfying } z_*(t, x) < 0.$$

5. In this step we will show that  $\hat{d}(t, x)$  defined in the previous step is equal to  $d_*(t, x)$  whenever  $z_*(t, x) < 0$ . Indeed by construction  $\hat{d} \geq d_*$ . We already know that  $\hat{d}(t, x) = z_*(t, x) < 0$ . Set  $\rho = d_*(t, x)$ . Then  $\rho < 0$ . By the definition of  $d_*$  and the Lipschitz continuity of  $d$ , there is a sequence  $t_k \rightarrow t$  satisfying,  $d(t_k, x) \rightarrow \rho$ . Since  $d(t_k, x) < 0$  for sufficiently large  $k$ ,  $(t_k, x) \in \mathcal{N}$  and step 3 implies that  $z^*(t_k, x) = d(t_k, x)$ . In summary;

$$\begin{aligned} z_*(t, x) &= \hat{d}(t, x) \geq d_*(t, x) = \lim_{k \rightarrow \infty} d(t_k, x) \\ &= \lim_{k \rightarrow \infty} z^*(t_k, x) \geq (z^*)_*(t, x) \geq z_*(t, x). \end{aligned}$$

Hence  $\hat{d}(t, x) = d_*(t, x)$  and this step together with steps 2 and 4 complete the proof of (3.9) on  $t < T_{est}$ .

6. Suppose that  $z^*(t, x) > 0$  and  $t < T_{est}$ . We proceed as in step 4 and then step 5 to prove that



$$z^*(t, x) = \limsup_{(s, y) \rightarrow (t, x), s > t} d(t, x) = d^*(t, x).$$

This identity and step 3 complete the proof of (3.8) on  $t < T_{est}$ .

7. An application of Lemma 6.1 and (4.4) yield that on  $(T_{est}, \infty) \times \mathcal{R}^d$  we have either  $z_* = z^* = -\infty$  or  $z_* = z^* = +\infty$ . Therefore

$$(6.6) \quad (T_{est}, \infty) \times \mathcal{R}^d \cap \Gamma = \emptyset.$$

Suppose that  $\mathcal{P}_t$  is empty for some  $t$ . Then (3.8) implies that if  $t < T_{est}$  then  $z^*(t, x) = +\infty$  for every  $x$ . Therefore  $t \geq T_{est}$ . A similar argument shows that if  $\mathcal{N}_t$  is empty, then  $t \geq T_{est}$ . Hence both  $\mathcal{P}_t$  and  $\mathcal{N}_t$  are nonempty for all  $t < T_{est}$ . So by (3.2)  $\Gamma_t$  is nonempty for all  $t < T_{est}$ . This and (6.6) imply that  $T_{est} = t_{est}$  (recall that  $t_{est}$  is defined in Section 3).

Combining all the steps we conclude that (3.8) and (3.9) hold with  $t_{est} = T_{est}$ . ■

We are now ready to prove Theorem 3.2.

**Proof of Theorem 3.2.** The  $\epsilon \rightarrow 0$  limit of (5.4), assumption (2.6), the “clearing-out”, Theorem 5.1, and Ilmanen’s argument in Section 6.3 in [63] yields a local upper bound on the  $d$ -dimensional Hausdorff measure of  $\Gamma \cap U$  for any compact subset  $U$  of  $(0, \infty) \times \mathcal{R}^d$ . The second assertion of the theorem is a consequence of Theorem 3.3, equation (4.1), gradient estimate (4.3) and Section 10.2 in [13]. Since the notation and the assumptions used in [13] are quite different than the ones used in this paper, we will now briefly sketch this argument.

1. In this step we will show that

$$z_{*t} - \Delta z_* \geq 0,$$

on  $\mathcal{P} \cap (0, T_{est}) \times \mathcal{R}^d$ . In fact when  $|Dz^\epsilon| \leq 1$ , this inequality follows immediately from (4.1). In general we will prove the above inequality by using a transformation, the gradient estimate (4.3) and (3.9).

For a small positive constant  $\beta$ , let  $\eta$  be a smooth, increasing function satisfying,  $\eta(0) = 0$ ,  $0 < \eta'' < \beta$ ,  $\eta' > 1$  in  $(0, \infty)$ ,  $\eta' < 1$  in  $(-\infty, 0)$ , and  $\eta \geq -\beta$ . Following [13], we define,

$$(6.7) \quad \hat{z}^\epsilon(t, x) = \inf_{\mathcal{R}^d} (\eta(z^\epsilon(t, y)) + |x - y|).$$

This transformation is very similar to the inf-convolution used extensively in the theory of viscosity solutions [68],[72]. We refer the reader to [34] and Chapter 5 in [48], for the properties of the inf-convolution. Since  $\eta$  is bounded from below by  $\beta$ , the above minimum is achieved, say at  $y(x)$  ( $y(x)$  also depends on  $t$  and  $\epsilon$ , but we suppress this dependence in our notation.) By calculus, (see [13] for details), we obtain

$$q(z^\epsilon(t, y(x))/\epsilon)[1 - |Dz^\epsilon(t, y(x))|^2] \geq 0, \quad \text{on } \{\hat{z}^\epsilon > 0\}.$$

Now by using equation (4.1) and the properties of viscosity solutions and the inf-convolution we obtain,

$$\begin{aligned} \hat{z}_i^\epsilon(t, x) - \Delta \hat{z}^\epsilon(t, x) + \eta''(z^\epsilon(t, y(x)))|Dz^\epsilon(t, y(x))|^2 \\ \geq \eta'(z^\epsilon(t, y(x)))[z_i^\epsilon(t, y(x)) - \Delta z^\epsilon(t, y(x))] \\ = \frac{2}{\epsilon} \eta'(z^\epsilon(t, y(x)))q(z^\epsilon(t, y(x))/\epsilon)[1 - |Dz^\epsilon(t, y(x))|^2], \end{aligned}$$

in the viscosity sense. Since  $\eta'' < \beta$ , we have,

$$(6.8) \quad \hat{z}_i^\epsilon(t, x) - \Delta \hat{z}^\epsilon(t, x) + \beta |Dz^\epsilon(t, y(x))|^2 \geq 0, \quad \text{on } \{\hat{z}^\epsilon > 0\}.$$

Let

$$\hat{z}_* (t, x) = \liminf_{(s, y) \rightarrow (t, x), \epsilon \rightarrow 0} \hat{z}^\epsilon (s, y).$$

Then the properties of  $\eta$ , (6.7) and (3.9) imply that  $\hat{z}_* = z_*$  on  $\mathcal{P} \cap (0, T_{\text{exit}})$ . Also by carefully letting  $\epsilon$  go to zero in (6.8) we obtain,

$$z_{*t}(t, x) - \Delta z_*(t, x) + \beta |Dz_*(t, x)|^2 \geq 0,$$

on  $\mathcal{P} \cap (0, T_{\text{exit}}) \times \mathcal{R}^d$ . Now let  $\beta$  go to zero and use the gradient estimate (4.3) to conclude that on  $\mathcal{P} \cap (0, T_{\text{exit}}) \times \mathcal{R}^d$ ,

$$(6.9) \quad z_{*t}(t, x) - \Delta z_*(t, x) \geq 0.$$

2. Lemma 2 in [13] and (6.9) imply (3.7). The intuitive idea behind this is simple. First we observe that since  $z_*$  is a distance function,  $|Dz_*|^2 = 1$  in the viscosity sense. We then formally differentiate this identity to obtain  $D^2 z_* Dz_* = 0$ . Hence formally  $\Delta z_* = F(Dz_*, D^2 z_*)$ , where  $F$  is as in the statement of Theorem 3.2. This identity and (6.9) imply,



$$z_{\epsilon,t}(t, x) - F(Dz_{\epsilon}(t, x), D^2z_{\epsilon}(t, x)) \geq 0,$$

on  $\mathcal{P} \cap (0, T_{\text{est}}) \times \mathcal{R}^d$ . See [13] for the details of this argument. ■

**Remark 6.1.** Following the ideas of Ilmanen, it may be possible to prove that  $\Gamma$  is a solution of the mean curvature flow in the sense of Brakke [17]. Since Brakke's solutions satisfy the distance function property of [13, 93], this would be a stronger result than Theorem 3.2. Indeed this result was proved by Ilmanen under the additional assumption that  $u_0 = q(z_0/\epsilon)$  and  $|Dz_0| \leq 1$  [63]. ■

## 7 Appendix: a result of Chen and deMotttoni-Schatzman.

In this section we state a result of deMotttoni-Schatzman and Chen. Then we prove a corollary which was used in earlier sections.

The following is a special case of a result proved by deMotttoni-Schatzman [78] and Chen [28]. The particular result stated below follows immediately from Theorem 3 in [28].

**Theorem 7.1 (Chen and deMotttoni-Schatzman)** *Let  $u^\epsilon$  be a solution of (2.2) and (2.3). Suppose that there are  $t_0 > 0$  and a one parameter family of bounded closed subsets  $\Omega_\epsilon$  of  $\mathcal{R}^d$  satisfying,*

- a. *boundary of  $\Omega_\epsilon$  is a classical solution of the mean curvature flow on  $(0, t_0)$ ,*
- b. *signed distance function  $d(t, x)$  is three times continuously differentiable on  $[0, t_0] \times \mathcal{R}^d$ , (where  $d(t, x)$  is the signed distance between  $x$  and the boundary of  $\Omega_\epsilon$ ),*
- c.  *$u_0^\epsilon > 0$  in the interior of  $\Omega_0$  and  $u_0^\epsilon < 0$  in the complement of  $\Omega_0$ , and there are positive constants  $C, h$ , independent of  $\epsilon$ , such that,*

$$|u_0^\epsilon(x)| \geq C|d(0, x)|, \quad |Du_0^\epsilon(x)| \geq C, \quad \forall |d(0, x)| < h.$$

*Then  $u^\epsilon$  converges to +1 uniformly on compact subsets of  $\{(t, x) : t \in (0, t_0), x \in \text{int}(\Omega_\epsilon)\}$ , and  $u^\epsilon$  converges to -1 uniformly on compact subsets of  $\{(t, x) : t \in (0, t_0), x \notin \Omega_\epsilon\}$ .*

**Corollary 7.1** *Suppose that there are subsequences  $\epsilon_n \rightarrow 0$  and  $t_n \rightarrow t_0$  and an open set  $O$  of  $\mathcal{R}^d$  satisfying,*

$$\liminf_{n \rightarrow \infty} \inf_{x \in O} u^{\epsilon_n}(t_n, x) = \alpha > 0,$$

or

$$\limsup_{n \rightarrow \infty} \sup_{x \in O} u^{\epsilon_n}(t_n, x) = -\alpha < 0.$$

*Then for every  $x \in O$  there is  $\delta > 0$  such that  $u^{\epsilon_n}$  converges to +1 or -1, uniformly on every compact subset of  $(t, t + \delta) \times B_\delta(x)$ .*

**Proof:** Without loss of generality we may assume that  $u^{\epsilon_n}(t_n, x) > 0$  on  $O$ . Then we have,

$$(7.1) \quad u^{\epsilon_n}(t_n, x) = \alpha/2 > 0, \quad \forall x \in O,$$

and sufficiently large  $n$ . Fix  $x_0 \in O$  and let  $v^\epsilon$  be the solution of (2.2) with initial data

$$v^\epsilon(0, x) = \frac{\alpha}{2} - \frac{|x - x_0|^2}{\delta_0} \left[1 + \frac{\alpha}{2}\right],$$

where,

$$\delta_0 = [\inf\{|y - x_0| : y \notin O\}]^2.$$

Then for every  $x \notin O$ ,  $|x - x_0| \geq \delta_0$ , and

$$v^\epsilon(0, x) \leq \frac{\alpha}{2} - \left[1 + \frac{\alpha}{2}\right] \leq -1, \quad \forall x \notin O.$$

Also for every  $x$ ,  $v^\epsilon(0, x) \leq \frac{\alpha}{2}$ . Therefore by (7.1),

$$(7.2) \quad v^{\epsilon_n}(0, x) \leq u^{\epsilon_n}(t_n, x), \quad \forall x \in \mathcal{R}^d,$$

and by maximum principle

$$v^{\epsilon_n}(t, x) \leq u^{\epsilon_n}(t_n + t, x), \quad \forall (t, x) \in [0, \infty) \times \mathcal{R}^d.$$

Observe that the zero level set of  $v^\epsilon(0, \cdot)$  is the boundary of a ball centered at  $x_0$  with radius

$$r_0 = \left[\frac{\alpha\delta_0}{2 + \alpha}\right]^{1/2}.$$

Hence the previous theorem holds with

$$\Omega_t = \{x \in \mathcal{R}^d : |x - x_0| \leq \sqrt{(r_0)^2 - 2(d-1)t}\}.$$

Now the conclusion of the corollary follows from (7.2) and Theorem 7.1. ■

## 8 Appendix: a gradient estimate.

In this section we prove the gradient estimate (4.3). As in Section 4, we define,

$$w^\epsilon = |Dz^\epsilon(t, x)|^2.$$

Recall that,

$$(8.1) \quad w_t^\epsilon + \mathcal{L}_t^\epsilon w^\epsilon + R^\epsilon(t, x, w^\epsilon) \leq 0, \text{ in } (0, \infty) \times \mathcal{R}^d,$$

where for a real number  $r$ ,  $(t, x) \in [0, \infty) \times \mathcal{R}^d$  and a smooth function  $\varphi \in C^2(\mathcal{R}^d)$ ,

$$\begin{aligned} \mathcal{L}_t^\epsilon \varphi(x) &= -\Delta \varphi(x) + \frac{4u^\epsilon(t, x)}{\epsilon} Dz^\epsilon(t, x) \cdot D\varphi(x), \\ R^\epsilon(t, x, r) &= \frac{4}{\epsilon^2} q'\left(\frac{z^\epsilon(t, x)}{\epsilon}\right) r(r-1), \end{aligned}$$

and as before  $q(r) = \tanh(r)$ . Set

$$W(t, x) = 1 + \frac{2}{\ln(1/\epsilon)} \frac{(z^\epsilon(t, x))^2 + 1}{t}.$$

Recall that the gradient estimate (4.3) states that for sufficiently small  $\epsilon$ ,  $w^\epsilon \leq W$ . We will first show that  $W$  is a supersolution of an equation very similar to (8.1). Then we complete the proof of (4.3) by an application of the maximum principle.

**Lemma 8.1** *There are a constant  $\epsilon_0$  and a function  $\lambda^\epsilon(t)$  such that for every  $\epsilon \leq \epsilon_0$ ,*

$$(8.2) \quad W_t + \mathcal{L}_t^\epsilon W + R^\epsilon(t, x, W) \geq \frac{\lambda^\epsilon(t)}{t} [W - w^\epsilon] \text{ in } (0, \infty) \times \mathcal{R}^d.$$

Moreover  $\lambda^\epsilon(t)$  is uniformly bounded in  $\epsilon$ , i.e.,

$$(8.3) \quad \lambda_0 = \sup\{|\lambda^\epsilon(t)| : t \geq 0, \epsilon \leq \epsilon_0\} < \infty.$$

**Proof:** Set,

$$\psi = (z^\epsilon)^2 + 1, \quad K(\epsilon) = 2[\ln(1/\epsilon)]^{-1}.$$

1. We directly calculate that

$$W_t + \mathcal{L}_t^\epsilon W = -\frac{K(\epsilon)\psi}{t^2} + \frac{K(\epsilon)}{t} \left[ \frac{4u^\epsilon}{\epsilon} z^\epsilon (w^\epsilon + 1) - 2w^\epsilon \right],$$

and

$$(8.4) \quad W_t + \mathcal{L}_t^\epsilon W + R^\epsilon(t, x, W) = I + J,$$

where

$$I = \frac{1}{t} \left[ -\frac{K(\epsilon)\psi}{t} + \frac{2u^\epsilon z^\epsilon K(\epsilon)}{\epsilon} (w^\epsilon + 1) \right] + \frac{1}{2} R^\epsilon(t, x, W),$$

$$J = \frac{K(\epsilon)}{t} \left[ \frac{2u^\epsilon z^\epsilon}{\epsilon} (w^\epsilon + 1) - 2w^\epsilon \right] + \frac{1}{2} R^\epsilon(t, x, W).$$

In the following steps we will estimate  $I$  and  $J$  separately.

2. We split the estimate of  $I$  into two cases and start with the case,

$$(8.5) \quad K(\epsilon)|z^\epsilon| \geq \epsilon.$$

(The other case will be analyzed in the next step.) The above inequality yields,

$$|u^\epsilon| = q\left(\frac{|z^\epsilon|}{\epsilon}\right) \geq q\left(\frac{1}{K(\epsilon)}\right) = \frac{1-\epsilon}{1+\epsilon} \geq \frac{1}{2},$$

provided that  $\epsilon \leq 1/3$ . Since  $u^\epsilon z^\epsilon = |u^\epsilon||z^\epsilon|$ ,

$$2u^\epsilon z^\epsilon K(\epsilon)/\epsilon = 2|u^\epsilon||z^\epsilon|K(\epsilon)/\epsilon \geq 1.$$

Using the above estimate and the positivity of  $R^\epsilon(t, x, W)$  we obtain,

$$I \geq \frac{1}{t} \left[ -\frac{K(\epsilon)\psi}{t} + (w^\epsilon + 1) \right] \geq -\frac{1}{t} [W - w^\epsilon].$$

3. Suppose that (8.5) does not hold, i.e.,

$$K(\epsilon)|z^\epsilon| < \epsilon \Rightarrow q'\left(\frac{z^\epsilon}{\epsilon}\right) \geq q'\left(\frac{1}{K(\epsilon)}\right).$$

Since  $q'(r) = 4e^{2r}(e^{2r} + 1)^{-2}$ ,

$$q'(\frac{z^\epsilon}{\epsilon}) \geq q'(\frac{1}{K(\epsilon)}) = 4\epsilon(\epsilon + 1)^{-2} \geq \epsilon,$$

provided that  $\epsilon \leq 1$ . We use this inequality in the definition of  $R^\epsilon$  to obtain,

$$\begin{aligned} R^\epsilon(t, x, W) &= \frac{4}{\epsilon^2} q'(\frac{z^\epsilon}{\epsilon})(W - 1)W, \\ &\geq \frac{4}{\epsilon} \frac{K(\epsilon)\psi}{t} \left[ \frac{K(\epsilon)\psi}{t} + 1 \right], \\ &\geq \frac{4}{\epsilon} \frac{(K(\epsilon))^2 \psi}{t^2}. \end{aligned}$$

In the third inequality we used the fact that  $\psi \geq 1$ . Since  $2K(\epsilon) \geq \epsilon$  for all  $\epsilon \leq 1$  and the product  $u^\epsilon z^\epsilon$  is always positive, the above inequality yields,

$$\begin{aligned} I &\geq -\frac{K(\epsilon)\psi}{t^2} + \frac{1}{2} R^\epsilon(t, x, W), \\ &\geq \frac{K(\epsilon)\psi}{t^2} \left[ -1 + \frac{2K(\epsilon)}{\epsilon} \right] \geq 0. \end{aligned}$$

4. Combining the two previous steps we conclude that for all  $\epsilon \leq 1/3$ ,

$$I \geq -\frac{1}{t} \mathbf{1}_A [W - w^\epsilon],$$

where  $\mathbf{1}_A$  is the characteristic function of the set  $A$  and

$$A = \{(t, x) : K(\epsilon)|z^\epsilon(t, x)| \geq \epsilon\}.$$

5. We continue with an estimate of  $J$ . First suppose that

$$(8.6) \quad |z^\epsilon| \geq 2\epsilon.$$

(The other case will be analyzed in the next step.) Then we have,

$$\frac{2}{\epsilon} u^\epsilon z^\epsilon = 2q\left(\frac{|z^\epsilon|}{\epsilon}\right) \frac{|z^\epsilon|}{\epsilon} \geq 4q(2) \geq 2.$$

Hence,

$$J \geq \frac{K(\epsilon)}{t} [2(w^\epsilon + 1) - 2w^\epsilon] \geq 0.$$

6. Now suppose that (8.6) does not hold, i.e.,  $|z^\epsilon| < 2\epsilon$ . Then,

$$R^\epsilon(t, x, W) = \frac{4}{\epsilon^2} q' \left( \frac{z^\epsilon(t, x)}{\epsilon} \right) (W - 1)W \geq \frac{4}{\epsilon^2} q'(2) \left[ \frac{K(\epsilon)\psi}{t} \right] W.$$

Recall that  $w^\epsilon z^\epsilon \geq 0$ . Therefore for  $\epsilon \leq \sqrt{q'(2)}$ ,

$$\begin{aligned} J &\geq -\frac{2K(\epsilon)w^\epsilon}{t} + \frac{1}{2}R^\epsilon(t, x, W), \\ &\geq \frac{2K(\epsilon)}{t} \left[ -w^\epsilon + \frac{q'(2)W}{\epsilon^2} \right], \\ &\geq \frac{2K(\epsilon)}{t} [W - w^\epsilon]. \end{aligned}$$

In the second inequality, we used the fact that  $\psi \geq 1$ .

7. Combining the two previous steps we conclude that for every  $\epsilon \leq \sqrt{q'(2)}$ ,

$$J \geq -\frac{2K(\epsilon)}{t} 1_B [W - w^\epsilon],$$

where

$$B = \{(t, x) : |z^\epsilon(t, x)| \leq 2\epsilon\}.$$

Now (8.2) follows from this step, Step 4 and (8.4) with  $\epsilon_0 = \sqrt{q'(2)}$  and

$$\lambda^\epsilon(t, x) = -1_A + 2K(\epsilon)1_B.$$

Finally, we prove (8.3) after observing that  $K(\epsilon) \rightarrow 0$  as  $\epsilon \rightarrow 0$ . ■

**Proof of Proposition 4.1.** Fix  $\epsilon \leq \epsilon_0$  and  $T > 0$ . We first assume that there exists a constant  $C(\epsilon) \geq 1$  satisfying,

$$(8.7) \quad w^\epsilon(0, x) \leq C(\epsilon), \quad \forall x \in \mathcal{R}^d.$$

We will remove this restriction in Step 6, below. Since  $C(\epsilon) \geq 1$ ,  $w \equiv C(\epsilon)$  is a supersolution of (8.1). Therefore by (8.7) and the maximum principle we have,

$$(8.8) \quad w^\epsilon(t, x) \leq C(\epsilon), \quad \forall (t, x) \in [0, \infty) \times \mathcal{R}^d.$$

To prove (4.3) we first assume that

$$\inf_{[0, T] \times \mathcal{R}^d} [W - w^\epsilon] < 0,$$

and then obtain a contradiction in the next five steps.

1. Set

$$\rho = \frac{4}{\epsilon^2} \|q'\|_\infty + \frac{\lambda_0 C(\epsilon)}{K(\epsilon)} + 1,$$

where  $\lambda_0$  and  $K(\epsilon)$  are as in the previous lemma. This technical choice of  $\rho$  will be clear in the next several steps. Then we have,

$$\inf\{e^{-\rho t}[W(t, x) - w^\epsilon(t, x)] : (t, x) \in [0, T] \times \mathcal{R}^d\} = -2b < 0.$$

For  $\delta \in (0, b]$ , choose  $(t_\delta, x_\delta) \in [0, T] \times \mathcal{R}^d$  such that,

$$e^{-\rho t_\delta}(W - w^\epsilon)(t_\delta, x_\delta) < -2b + \delta.$$

2. Let  $\eta$  be a smooth function satisfying,

$$0 \leq \eta \leq 1, \quad \eta(0) = 1, \quad \eta(x) = 0, \quad \forall |x| \geq 1.$$

Consider the auxiliary function,

$$\Phi(t, x) = e^{-\rho t}[W(t, x) - w^\epsilon(t, x)] - \delta\eta(x - x_\delta).$$

Then  $\Phi$  achieves its maximum over  $[0, T] \times \mathcal{R}^d$ , say at  $(\hat{t}, \hat{x})$ . Moreover,

$$(8.9) \quad \Phi(\hat{t}, \hat{x}) \leq \Phi(t_\delta, x_\delta) = e^{-\rho t_\delta}(W - w^\epsilon)(t_\delta, x_\delta) \leq -2b + \delta.$$

Since  $W(t, x) \geq K(\epsilon)/t$ , (8.8) implies that for all  $\delta \leq \min\{b, 1\}$ ,

$$0 \geq b + \Phi(\hat{t}, \hat{x}) \geq e^{-\rho \hat{t}}(W - w^\epsilon)(\hat{t}, \hat{x}) \geq e^{-\rho \hat{t}}\left(\frac{K(\epsilon)}{\hat{t}} - C(\epsilon)\right).$$

Therefore,

$$(8.10) \quad \hat{t} \geq K(\epsilon)/C(\epsilon).$$



3. Set

$$\bar{w}(t, x) = e^{-\epsilon t} w^\epsilon(t, x), \quad \bar{W}(t, x) = e^{-\epsilon t} W(t, x).$$

Then

$$(8.11) \quad \bar{w}_t - \mathcal{L}_t^\epsilon \bar{w} + \bar{R}(t, x, \bar{w}) \leq 0,$$

$$(8.12) \quad \bar{W}_t - \mathcal{L}_t^\epsilon \bar{W} + \bar{R}(t, x, \bar{W}) \geq \frac{\lambda^\epsilon}{\epsilon} [\bar{w} - \bar{W}],$$

where for  $r > 0$ ,  $(t, x) \in [0, \infty) \times \mathcal{R}^d$ ,

$$\bar{R}(t, x, r) = \varrho r + e^{-\epsilon t} R^\epsilon(t, x, e^{\epsilon t} r).$$

Using the definitions of  $R^\epsilon$  and  $\varrho$ , we directly estimate that,

$$(8.13) \quad \begin{aligned} \bar{R}_r(t, x, r) &= \varrho + R_r^\epsilon(t, x, e^{\epsilon t} r), \\ &\geq \varrho - \frac{4}{\epsilon^2} q' \left( \frac{z^\epsilon(t, x)}{\epsilon} \right), \\ &\geq 1 + \frac{\lambda_0 C(\epsilon)}{K(\epsilon)}. \end{aligned}$$

4. Let

$$\varphi = \bar{W} - \bar{w}.$$

Subtract (8.11) from (8.12) to obtain,

$$\varphi_t - \mathcal{L}_t^\epsilon \varphi \geq \bar{R}(t, x, \bar{w}) - \bar{R}(t, x, \bar{W}) - \frac{\lambda^\epsilon}{\epsilon} \varphi.$$

Since  $\varphi(\hat{t}, \hat{x}) \leq 0$ , (8.13) and (8.10) yield,

$$\bar{R}(\hat{t}, \hat{x}, \bar{w}) - \bar{R}(\hat{t}, \hat{x}, \bar{W}) - \frac{\lambda^\epsilon(\hat{t})}{\epsilon} \varphi \geq -\varphi.$$

Hence at  $(\hat{t}, \hat{x})$  we have,

$$(8.14) \quad \varphi_t - \mathcal{L}_t^\epsilon \varphi \geq -\varphi.$$

5. Recall that the auxiliary function  $\Phi = \varphi - \delta\eta$  defined in step 2 attains its maximum at  $(\hat{t}, \hat{x}) \in (0, T] \times \mathcal{R}^d$ . Therefore at  $(\hat{t}, \hat{x})$ ,

$$\Phi_{\hat{t}} - \mathcal{L}_{\hat{t}}^{\epsilon}\Phi \leq 0.$$

Now we use (8.14) and (8.9) to obtain,

$$2b - \delta[1 + \eta(\hat{x} - x_{\delta})] \leq -\varphi(\hat{t}, \hat{x}) \leq \varphi_{\hat{t}} - \mathcal{L}_{\hat{t}}^{\epsilon}\varphi = \Phi_{\hat{t}} - \mathcal{L}_{\hat{t}}^{\epsilon}\Phi - \delta\mathcal{L}_{\hat{t}}^{\epsilon}\eta \leq \delta L(\epsilon),$$

where  $L(\epsilon)$  is a constant depending on the function  $\eta$  and the operator  $\mathcal{L}^{\epsilon}$ . Since this constant is independent of  $\delta$ , we obtain a contradiction by letting  $\delta$  go to zero in the above string of inequalities. Hence  $W \geq w^{\epsilon}$  on  $[0, T] \times \mathcal{R}^d$  for every  $T > 0$ . So we have completed the proof of (4.3) under the additional assumption (8.7).

6. In this step we remove the restriction (8.7). First observe that,

$$|u_{\hat{t}}^{\epsilon}(t, x) - \Delta u^{\epsilon}(t, x)| \leq \frac{2}{\epsilon^2}, \quad |u^{\epsilon}(0, x)| \leq 1.$$

By well known properties of the heat kernel, we have,

$$|Du^{\epsilon}(t, x)| \leq C_d \sqrt{t} \left[ \frac{2}{\epsilon^2} + \frac{1}{t} \right],$$

where  $C_d$  is an appropriate constant, depending only on the dimension  $d$ . Fix  $\epsilon$ , and for a positive integer  $k$ , let  $u^k$  be the solution of (2.2) with initial data,

$$u^k(0, x) = \min\{\max\{u^{\epsilon}(k^{-1}, x), 1 - k^{-1}\}, -1 + k^{-1}\}.$$

Define  $z^k$  by,

$$u^k = q\left(\frac{z^k}{\epsilon}\right).$$

Clearly as  $k$  tends to infinity,  $u^k$  converges to  $u^{\epsilon}$  in  $C_{loc}^m((0, \infty) \times \mathcal{R}^d)$  for any  $m$ . Moreover,

$$|Dz^k(0, x)| = \epsilon |Du^k(0, x)| \left[ q'\left(\frac{z^k(0, x)}{\epsilon}\right) \right]^{-1} \leq \frac{\epsilon C_d}{\sqrt{k}} \left[ \frac{2}{\epsilon^2} + k \right] \left[ q'\left(\frac{1 - k^{-1}}{\epsilon}\right) \right]^{-1}.$$

Therefore by the previous steps,  $|Dz^k|^2 \leq W$ . Now we let  $k$  to go to infinity to complete the proof of (4.3).  $\blacksquare$

The following remark was pointed out to us by Ilmanen.

**Remark 8.1.** Observe that if  $u^\epsilon(t, x)$  is a solution (1.1), then for any  $\lambda > 0$ ,

$$v^\lambda(t, x) = u^\epsilon(\lambda^2 t, \lambda x),$$

is again a solution of (1.1) with  $\epsilon$  replaced with  $\epsilon/\lambda$ . Then by the gradient estimate (4.3),

$$\hat{z}^\lambda(t, x) = \frac{\epsilon}{\lambda} q^{-1}(v^\lambda(t, x)) = \frac{z^\epsilon(\lambda^2 t, \lambda x)}{\lambda},$$

satisfies,

$$|D\hat{z}^\lambda(t, x)|^2 \leq 1 + \frac{1}{2\ln(\lambda/\epsilon)} \frac{(\hat{z}^\lambda(t, x))^2 + 1}{t}.$$

The above estimate holds for all  $\lambda$  satisfying,  $\epsilon/\lambda \leq \epsilon_0$ , where  $\epsilon_0$  is as in the statement of Proposition 4.1. Since

$$z^\epsilon(t, x) = \lambda \hat{z}^\lambda\left(\frac{t}{\lambda^2}, \frac{x}{\lambda}\right),$$

the above estimate yields that,

$$|Dz^\epsilon(t, x)|^2 \leq 1 + \frac{1}{2\ln(\lambda/\epsilon)} \frac{(z^\epsilon(t, x))^2 + \lambda^2}{t}.$$

Now by minimizing the right-hand side over  $\lambda \geq \epsilon/\epsilon_0$ , we obtain a scale-invariant version of the estimate (4.3). ■

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