# RANDOM WALKS, TOTALLY UNIMODULAR MATRICES AND A RANDOMISED DUAL SIMPLEX ALGORITHM 

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#### Abstract

We discuss the application of random walks to generating a random basis of a totally unimodular matrix and to solving a linear program with such a constraint matrix. We also derive polynomial upper bounds on the combinatorial diameter of an associated polyhedron.


[^0]
## 1 Introduction

A matrix is totally unimodular if all its subdeterminants are $0, \pm \mathrm{l}$. Totally unimodular matrices are known to be the matrix representations of regular matroids [20]. Let Abea totally unimodular $m x n$ matrix with columns
 singular submatrices of $A$. These correspond to the bases of the associated regular matroid. We will, by abuse of terminology, identify A , or a basis JB , with the set of columns they contain. Now, assuming $A$ has full row rank (i.e. $B \wedge 0$ ), we can define a simple random walk on $B$ :

## NATURAL RANDOM WALK

Starting at an arbitrary basis $B o=B 6 \mathrm{~B}$, generate a random sequence $B_{0}, 2 \mathbf{2} \mathrm{i}, \ldots, 2 \mathbf{2} \mathrm{t}, \ldots € B$ as follows. At $B_{\boldsymbol{t}}$, randomly choose columns $a € B_{\boldsymbol{t}}$, $a^{\prime} £ A \backslash B_{t}$ Let $B_{t}^{\prime}=B_{t} \mathbf{U}\left\{a^{\prime}\right\} \backslash\{a\}$. If $B \backslash € B$ then $\mathbf{J 5}_{t+1} \mathbf{i}=£\{$, otherwise $B \%+\=B_{t}$.

Now the steady state distribution of this chain is uniform over B. (This is clear from the fact that the probability transition matrix is symmetric.) The crucial question is how quickly does the chain settle down ? Does it mix rapidly-Aldous [1] ? In the particular case of our problem in which $A$ is the node-arc incidence matrice of a (di)graph, or correspondingly the regular matroid is graphic^ the answer is known to be affirmative-Aldous [2], Broder [7]. We will extend this result and prove

Theorem 1 For any B€B

$$
\operatorname{IPrfA}_{3},-\mathrm{iq}-|\mathrm{B}|-\left\lvert\, \mathrm{S}\left(\mathrm{I}-\frac{1}{8 m^{4} n^{4}}\right)^{t} .\right.
$$

It is clear from this theorem that in time polynomial in $m, n, \ln (1 / 6)$ we can generate a basis $\hat{B}$ of $\boldsymbol{A}$ such that for any $\boldsymbol{B} € B$ we have

$$
\left|\operatorname{Pr}[\hat{B}=B]-|B|^{-1}\right| \leq \delta,
$$

i.e. $\hat{B}$ is an "almost uniformly generated" basis. We will prove the above theorem by relating the walk to one in a certain convex polytope $((A)$ associated with $A$, called its zonotope. For an arbitrary matrix $A$, the associated zonotope is defined by

$$
\left((A)=\left\{x € \mathbf{H}^{\mathrm{m}}: x=A y \text { for some } y €[0,1]^{\mathrm{n}}\right\}\right.
$$

The mixing time of Markov chains has attracted much attention lately in the Computer Science community, since the efficiency of various algorithms depends on this, e.g. Broder [6], Jerrum and Sinclair [21,13,14], Dyer, Frieze and Kannan [12], Karzanov and Khachyan [16], Lovász and Simonovits [17], Applegate and Kannan [3], Applegate, Kannan and Poison [4], Dyer and Frieze [11], Mihail and Winkler [19]. Theorem 1 could be used, in particular, to show how to estimate $\backslash B \backslash$ although as we shall see, this can be done more efficiently using the Binet-Cauchy formula for the determinant of the product of two rectangular matrices.

As already observed, one can consider $\backslash \boldsymbol{B} \backslash$ to be the set of bases of the regular matroid associated with $\boldsymbol{A}$. We note that, if one could generalise Theorem 1 to an arbitrary matroid, then one could (for example) efficiently estimate the reliability of a graph. This would be an important result.

Our second result concerns linear programs with totally unimodulax matrices
of coefficients. We consider the problem

$$
\begin{aligned}
\mathrm{LP}(b): & \begin{array}{l}
\text { minimise } c y \\
\text { subject to } A y
\end{array} \\
& =b \\
y & \geq 0
\end{aligned}
$$

Although it is already known, through the work of Tardos [23], that a strongly polynomial time algorithm exists for this problem when $A$ is totally unimodular, we will show that random walks may be used to give a randomised version of this result. We will defer the exact statement until later. What we show, in essence, is that the above problem can be solved by a randomised dual simplex algorithm, where pivots are chosen by executing a random walk. This is discussed in Section 4. As a corollary we will be able to give a polynomial upper bound on the combinatorial diameter of the polytope $P=\left\{x \in \boldsymbol{R}^{m}: A^{T} x \leq c\right\}$ when $A$ is totally unimodular.

## 2 Notation and terminolgy

## Conductance

Consider a Markov chain with state space $\Omega$, transition matrix $P=\left(p_{i j}\right)$ and steady state distribution $\pi_{i}$. If $I \subseteq \Omega$ with $\pi(I)=\sum_{i \in I} \pi_{i} \leq \frac{1}{2}$, let

$$
\Phi_{I}=\sum_{i \in I, j \notin I} \pi_{i} p_{i j} / \pi(I)
$$

i.e. $\Phi_{I}$ is the conditional probability that the next state will be in $\bar{I}$ given that the current state is in $I$, assuming the steady state distribution of the chain. The conductance of the chain is then $\Phi=\min _{I} \Phi_{I}$. The following theorem is implicit in [21], and stated more directly in [17].

Theorem $2 / / J \underline{\mathrm{C} f t}$ and $\left.i r^{\wedge} \dot{\mathrm{j}}\right)$ is the probability that the chain is in a state of J at time $t$ when started in state 1, then

$$
\left|\pi^{(t)}(J)-\pi(J)\right| \leq \sqrt{\pi(J) / \pi_{1}}\left(1-\Phi^{2} / 2\right)^{t}
$$

## Norms

For a vector $x € H^{n}$ we use $\|\mathrm{x}\|$ to denote the Euclidean or $\mathrm{L}_{2}$ norm. We will also need to use the $L \backslash$ and $L^{\wedge}$ norms which are written $\|z\| \mathrm{i},\|\wedge\| \mathrm{oo}$ respectively.

## 3 Analysis of the walk

We start by proving a result on the volume $\operatorname{vol}_{\mathrm{m}}(£(\mathrm{~A}))$ which is attributed by Stanley [22] to McMuUen. We give a proof which provides us with a decomposition of ( $(A)$ into parallelopipeds which is fundamental to our walks. Here $A$ need not be totally unimodular.

Theorem $3 \operatorname{vol}_{m}\left(((A))=\mathfrak{£}_{\text {в } \in \text { в }} \mid \operatorname{det} B \backslash\right.$

Proof If $B € B$ then $((B)$ is a parallelopiped with edges parallel to the columns of $B$ and it is well known that

$$
\begin{equation*}
\operatorname{vol}_{\mathrm{m}}(\mathbf{C}(B))=|\operatorname{det} £| . \tag{1}
\end{equation*}
$$

Let $\mathbf{c} € R^{n}$ be arbitrary, $0>0$ be arbitrarily small, and

$$
c_{\theta}=\left(c_{1}+\theta, c_{2}+\theta^{2}, \ldots, c_{n}+\theta^{n}\right)
$$

For each $\mathrm{x} €\left((A)_{y}\right.$ let $P_{x}=\left\{y €[0,1]^{\mathrm{n}}: A y=\mathrm{x}\right\}$, and let $£(x)$, be the unique optimal solution to

$$
\begin{equation*}
\text { minimise } c \$ y: y 6 P_{x^{-}} \tag{2}
\end{equation*}
$$

Since 0 is small, ((x) is the (unique) lexicographical optimum to the above problem. Thus there is some basis $B_{x} € B$ with columns $\mathbf{a}_{\mathrm{t}}, \mathbf{f} € / *$ such that $i j\left\{x\right.$ ) $6\{0,1\}$ for $j £ I_{x}$. (If there is a choice of $I_{x}$ due to degeneracy, choose the lexicographically first such.) Let now $\hat{\mathfrak{f}}(x)$ be defined by $\hat{\mathbf{f}}$;(x) = $6(*), \mathbf{J} £ \mathrm{~J}^{*}$ and $£(\mathrm{x})=0, \mathbf{t} \mathbf{G} \boldsymbol{I}_{x}$. Then

$$
\left.\mathrm{x} € \mathrm{ft}^{*}\right)+C\left(B_{X}\right) .
$$

Observe also that if $x^{f} € £(x)+C\left(B_{X}\right)$ and $0<x_{\boldsymbol{t}}^{\boldsymbol{f}}<1$ for $\mathbf{i} € \mathrm{i}^{*}$ then $/_{\mathrm{x}} /=I_{x}$ and $\mathrm{J}_{\mathrm{x}}=\mathrm{S}_{\mathrm{x}} /$. This is because changing the right hand side of the linear program (2) in this way does not affect the optimality of the basis $B_{x}$.

Conversely, suppose $B € B$ with columns a», $i € /$. There is a unique $r)(B) €\{0,1\}^{\mathrm{n}}$, with $\left.r\right] i=0$ (i $€ /$ ), such that if $\boldsymbol{x} € r f(B)+\mathrm{C}(\#)$ and $0<\mathbf{X i}<1$ for $\mathbf{t} € /$, then $B_{x}=B$ and $\hat{\mathfrak{f}}(\mathbf{x})=» 7(B)$. Indeed, for any such $\mathbf{x}$, the optimality conditions
where $/=\left\{i \backslash<\ldots<\mathbf{t}_{\mathrm{m}}^{\prime}\right\}$, will ensure $B_{x}=B$. Since 0 is arbitrarily small, the conditions (3) can of course be rewritten to be independent of 0. Summarising, the set $S$ of parallelopipeds $\left\{\hat{£}(\mathbf{x})+C\left(B_{X}\right): \times 6 C(\wedge)\right\}$ cover $C(A)$, intersect on a set of zero volume and each $B € B$ gives rise to a unique $P_{B} € £$. The theorem now follows.

D

Returning to the case where $A$ is totally unimodular, we see immediately that

$$
\operatorname{vol}_{m}(\zeta(A))=|\mathcal{B}|
$$

Thus we could approximate $|\mathcal{B}|$ by estimating the volume of $\zeta(A)$. This is however, not the easiest way of accomplishing this. By the identity of Binet-Cauchy (see, for example, [5, p327]) we have

$$
\operatorname{det} A A^{T}=\sum_{I}\left(\operatorname{det} B_{I}\right)^{2}=|\mathcal{B}|
$$

where the above sum ranges over all $m$-sets $I \subseteq[n]=\{1,2, \ldots, n\}$ and $B_{I}$ is the $m \times m$ submatrix of $A$ with columns $a_{i}, i \in I$. Thus $|\mathcal{B}|$ can be computed exactly by evaluating a determinant. This can be done in polynomial time, and even in NC.

This observation can be generalised somewhat. We can compute, for example, the number $\alpha_{k}$ of $k \times k$ nonsingular submatrices of $A$. Let $A^{\prime}$ be the $m \times(m+n)$ matrix obtained from $A$ by adding an $m \times m$ identity matrix $I_{m}$. Then $\alpha_{k}$ is the number of bases of $A^{\prime}$ which have ( $m-k$ ) columns in $I_{m}$. In general suppose we have an $M \times N$ totally unimodular matrix $D$, $S \subseteq[N]$, and we wish to compute the numbers $\beta_{k}, k=0,1, \ldots, M$ of bases of $D$ which have $k$ columns with indices in $S$. After column rearrangement, let $D=\left[D_{1} \mid D_{2}\right]$, where $D_{1}$ contains the columns with indices in $S$. Suppose $z$ is a complex variable, and let $D_{z}=\left[\sqrt{z} D_{1} \mid D_{2}\right]$. (The choice of branch for the square-root is unimportant.) The Binet-Cauchy theorem implies that

$$
\begin{equation*}
\operatorname{det} D_{z} D_{z}^{T}=\operatorname{det}\left(z D_{1} D_{1}^{T}+D_{2} D_{2}^{T}\right)=\sum_{k=0}^{M} \beta_{k} z^{k} \tag{4}
\end{equation*}
$$

and we can compute the $\beta_{k}$ by evaluating the coefficients of the above polynomial by interpolation, using only rational values of $z$.

More generally still, suppose for any fixed $r$, we partition the columns of $D$ into sets $S_{1}, S_{2}, \ldots, S_{r}$ and ask for the number of bases with $k_{1}$ columns in $S_{1}, \ldots, k_{r}$ columns in $S_{r}$, where $k_{1}+\cdots+k_{r}=M$. Call this number $\beta\left(k_{1}, \ldots, k_{r}\right)$. Letting $D=\left[D_{1}|\cdots| D_{r}\right]$ and $D_{z}=\left[\sqrt{z_{1}} D_{1}|\cdots| \sqrt{z_{r}} D_{r}\right]$, gives

$$
\begin{align*}
\operatorname{det} D_{z} D_{z}^{T} & =\operatorname{det}\left(z_{1} D_{1} D_{1}^{T}+\cdots+z_{r} D_{r} D_{r}^{T}\right) \\
& =\sum_{k_{1}+\ldots+k_{r}=M} \beta\left(k_{1}, \ldots, k_{r}\right) z_{1}^{k_{1}} \cdots z_{r}^{k_{r}} . \tag{5}
\end{align*}
$$

The right hand side is a homogeneous polynomial in $z_{1}, \ldots, z_{r}$ whose coefficients can again be determined by interpolation.

We note in passing that equation (4) gives strong information about the numbers $\beta_{k}$. It follows easily, by simultaneous diagonalisation of the pair of positive semidefinite matrices $D_{1} D_{1}^{T}$ (see [5]), $D_{2} D_{2}^{T}$, that the polynomial $\sum_{k=0}^{M} \beta_{k} z^{k}$ has only nonpositive real roots. This answers a question of Stanley [22], and implies (as he observes) that $\gamma_{k}=\binom{n}{k}^{-1} \beta_{k}$ is a log-concave sequence, i.e. $\gamma_{k}^{2} \geq \gamma_{k-1} \gamma_{k+1}(k=1,2, \ldots, M-1)$. (See [5, p53] for a proof of the log-concavity of the sequence $\left\{\gamma_{k}\right\}$ in this situation.)

It follows further that the coefficients $\beta\left(k_{1}, \ldots, k_{r}\right)$ are $\prod_{i=1}^{r} k_{i}$ ! times the mixed discriminants of the quadratic forms $x^{T}\left(D_{i} D_{i}^{T}\right) x(i=1, \ldots, r)$, where $x \in \boldsymbol{R}^{n}$. See $[8, \mathrm{p} 169]$ for definitions and properties. It is now easy to derive Stanley's theorem (Theorem 2.1 of [22]) on the log-concavity properties of the $\beta\left(k_{1}, \ldots, k_{r}\right)$ from the theory of mixed discriminants, in a similar way to which Stanley derives it from the theory of mixed volumes. Mixed volumes and discriminants have many close relationships with enumeration. Approximation of mixed volumes is considered in [10]. We will consider a random walk on $\mathcal{B}$ which is slightly different from the one described in

Theorem 1. We call it the restricted random walk. Take $\mathbf{c}=\mathbf{0}$ in Theorem 3 and consider the graph $F=(B, £)$ in which $B, B^{*}$ are adjacent if $P B, P B^{\prime}$ share an ( $\mathrm{m}-\mathrm{l}$ )-dimensional face. If $B$ now has degree $d s$ in $F$ we add $(4 m-d s)$ loops at $B$. We consider the usual random walk on $F$.

We start at an arbitrary basis $B_{o}$, which we can find in $O\left(m^{2} n\right)$ time. We then re-arrange the columns of $A$ so that those of $B Q$ are last and then we have $P B_{0}=\mathbf{C}\left({ }^{\wedge} 0\right)$ - In a general step of the walk, at basis $B_{u}$ we randomly choose one of the $\mathbf{4 m}$ edges of $F$ that are incident with $B_{t}$ and traverse it. If the edge is not a loop, then moving to the associated neighbouring base requires a dual simplex pivot and this can be carried out in $\boldsymbol{O}$ (rnn) time. (We select the column to leave the basis, whether its associated variable is to become non-basic at 0 or 1 , and then find the unique column to replace it, if one exists. Furthermore there is no need to keep an explicit value for $\mathbf{6}$ since the replacing column is independent of 0 whenever 6 is sufficiently small.) For $B$ G $B$ let $\psi_{(k)}^{(t)}=\operatorname{Pr}\left(\mathbf{j B}_{\mathrm{t}}=B\right)$. We are interested in the variational distance between the distribution $* W$ and the (uniform) steady state distribution. This can be bounded in terms of the conductance \$ of the associated Markov chain. Theorem 2 implies that for our random walk

$$
\begin{equation*}
\text { ki?-|Sn<(1-y }{ }^{\frac{\phi^{2}}{2}} \tag{6}
\end{equation*}
$$

where, for $5 \underline{C} B$,

$$
\$=\min _{|S| \leq||B|} \$ 5 .
$$

Here, letting $e(S: \bar{S})$ denote the number of edges between $S$ and $\overline{5}$ in $F$, it follows easily that

$$
\begin{equation*}
\Phi_{S}=\frac{e(S: S)}{4 \mathrm{~m}|5|} \tag{7}
\end{equation*}
$$

To put a lower bound on $\Phi$, fix $S$ and let $R=\bigcup_{B \in S} P_{B}, W=|\partial R \backslash \partial \zeta(A)|$, where $\partial$ denotes boundary and $|\mid$ denotes $(m-1)$-dimensional measure. Now, by a theorem of Lovász and Simonovits [17], with a small improvement from Dyer and Frieze [11],

$$
\begin{align*}
W & \geq \frac{2 \operatorname{vol}_{m}(R)}{\operatorname{diam}(\zeta)} \\
& \geq \frac{2|S|}{n \sqrt{m}} \tag{8}
\end{align*}
$$

where we have used the fact that, since $A$ has entries $0, \pm 1$,

$$
\operatorname{diam}(\zeta) \leq \sum_{i=1}^{n}\left\|a_{i}\right\| \leq n \sqrt{m}
$$

On the other hand

$$
\begin{equation*}
W \leq \sqrt{m} e(S: \bar{S}) \tag{9}
\end{equation*}
$$

since the area of each facet of each $P_{B}$ is at most $\sqrt{m}$. To see this suppose that $a_{1}, a_{2}, \ldots, a_{m}$ are linearly independent. Let $b$ be the normal to the hyperplane $H$ through the origin generated by $a_{1}, a_{2}, \ldots, a_{m-1}$. Assume, after relabelling coordinates if necessary, that $b_{1} \neq 0$ and scale so that $b_{1}=1$. It follows from Cramer's rule applied to the equations $b_{1}=1, b \cdot a_{i}=0,1 \leq i \leq m-1$ that $b_{i} \in\{0, \pm 1\}, 1 \leq i \leq m-1$. Now the perpendicular distance $h$ from the point $a_{m}$ to $H$ is $\left|b \cdot a_{m}\right| /\|b\|$. But $b \cdot a_{m}$ is a non-zero integer and $\|b\| \leq \sqrt{m}$. The area upper bound follows since $h^{-1}$ is the area of the face of the parallelopiped generated by $a_{1}, a_{2}, \ldots, a_{m-1}$. Applying (9) in (8) gives

$$
\begin{equation*}
\Phi \geq \frac{1}{2 m^{2} n} \tag{10}
\end{equation*}
$$

To obtain Theorem 1 we need only argue that the conductance $\Phi^{\prime}$ of the natural random walk is at least $\Phi / n$. But this follows easily from the definition of conductance. Fix a set $S \subseteq \mathcal{B}$. Let $B_{N W}^{(t)}$ and $B_{R W}^{(t)}$ refer to the $t^{\prime}$ th
of the natural and restricted random walks respectively, assuming they are both started in their steady state, i.e. uniformly on B. Let

$$
\pi_{s}=\operatorname{Pr}(\imath \# \mathrm{k} € 5)=\operatorname{Pr}(\mathrm{i} ? \mathrm{j} \& € S)=|S| /|\mathcal{B}|
$$

Then, in an obvious notation,

$$
\begin{aligned}
\pi_{S} \Phi_{S}^{\prime} & \left.=\sum_{B \in S_{f} B^{\prime} \in S} \operatorname{Pr}(B) \&=B \text { and } B \%=B^{\prime}\right) \\
& \geq \sum_{B \in S, B^{\prime} \in S} \frac{1}{n-m} \operatorname{Pr}\left(B_{R W}^{(0)}=\right. \\
& =\frac{1}{n-\mathbf{m}} \pi_{S} \Phi_{S}
\end{aligned}
$$

where the inequality follows from the fact that at any basis $B$ the natural random walk has probability ${ }^{\wedge} \mathbf{r}^{\circ \wedge}{ }^{\mathrm{ma}} \mathrm{ki}^{\mathrm{n}} \mathrm{S}$ the same move as the restricted random walk. This clearly proves $\${ }^{\prime}>\$ / n$ and Theorem 1 follows.

## 4 Linear Programming

In this section we consider the effectiveness of a random walk in solving the linear program $\mathrm{LP}(6)$ of Section 1. Our randomised algorithm works on the assumption that $\operatorname{LP}(6)$ is feasible, in which case it solves it with high probability. The assumption of feasibility is no restriction, since we can use, for example, the "big-M" method [20, pl36] if we suspect the problem may be infeasible.

We first describe an algorithm METROPLEX which (almost) solves the problem $\operatorname{LP}^{\prime}(6)$ in which $y \geq 0$ is replaced by $0 \leq y j \leq 1, j=1,2, \ldots, n$. We will then use this algorithm as a subroutine to solve LP(6).

Assume that we are given $0<d, \delta<1$. Our result will be

Theorem 4 With probability at least $(1-\delta)$, METROPLEX computes $\hat{y}$ such that, if $\hat{b}=A \hat{y}$,

1. $\|\hat{b}-b\| \leq d$
2. $\hat{y}$ solves $L P(\hat{b})$

Furthermore METROPLEX runs in $O\left(m^{11.5} n^{4} d^{-3} \ln ^{3}(m /(d \delta))\right.$ time.

METROPLEX uses a random walk to choose dual simplex pivots in a manner to be described shortly. We start conceptually with the decomposition of $\zeta(A)$ into parallelopipeds induced by $c$ as given in Theorem 3. Let

$$
\begin{aligned}
M & =\left\lceil 4\left((m+1) \ln \left(10 m^{3} / d\right)+\ln (4 / \delta)\right) / d\right\rceil \\
N & =\left\lceil 5 M m^{3 / 2}\right\rceil \\
T & =\left\lceil 9 m^{4} n^{2} N^{2}(M n \sqrt{m}+m \log (15 M n \sqrt{m})+2 \log (2 / \delta))\right\rceil
\end{aligned}
$$

Each parallelopiped $P_{B}$ is divided into $N^{m}$ sub-parallelopipeds (which we will call cells) of equal size in an obvious way. Denote these by $P_{B, i}, i=$ $1,2, \ldots, N^{m}$ and let $\sigma_{B, i}$ denote the centre of $P_{B, i}$. Also for $x \in \zeta(A)$ let $\phi(x)=e^{-M\|x-b\|}$ and $\psi\left(P_{B, i}\right)=\phi\left(\sigma_{B, i}\right)$.

We do a random walk on the cells as follows. We start with an arbitrary basis $B$ and choose a cell in $P_{B}$, any will do. Suppose now that $P=P_{B, i}, P^{\prime}=P_{B^{\prime}, i^{\prime}}$ share a common facet. When the walk is at $P$ the (transition) probability $\lambda\left(P, P^{\prime}\right)$ that the next state is $P^{\prime}$ is given by

$$
\lambda\left(P, P^{\prime}\right)=\frac{1}{4 m} \min \left\{1, \frac{\psi\left(P^{\prime}\right)}{\psi(P)}\right\}
$$

This is achieved by choosing a neighbouring cell at random (as in our first random walk) and moving to it with probability $\left.i l>\left(P^{\prime}\right) / i f\right\rangle(P)$ - This is an example of the Metropolis algorithm [18]. It is straightforward to check that the steady state probabilities $\boldsymbol{v}(\boldsymbol{P})$ are proportional to $r l>(P)$. We run the walk for $\boldsymbol{T}$ steps and then with high probability the current cell $\boldsymbol{P}$ is "close" to the cell which contains 6 . If in fact $P \mathbb{C} P_{B}$ where $\mathbf{6} € P_{B}$ then $B$ will be an optimal basis for $L P^{\prime}(6)$ and this will be easily recognisable and we will have solved $L P^{\prime}(6)$. In general we cannot conclude this although, when $d$ is small and $b$ is chosen randomly from $C\left({ }^{\wedge}\right)>$ this is likely to be the case.

Before analysing the mixing time of this walk we remark that the algorithm does have the flavour of a randomised dual simplex algorithm. Moving from cell to cell in the same parallelopiped requires adjusting the value of one basic variable and moving from parallelopiped to parallelopiped requires a dual simplex pivot as before. The random walk between pivots is used to determine which column should leave the basis.

We now discuss the conductance of the walk. Let ft denote the set of all cells. Let $S \underline{\mathrm{C}} \mathrm{ft}$ satisfy $\mathbf{T T}(\mathbf{S})_{<}<\backslash$ and let $\bar{S}=\mathrm{ft} \backslash S$. Let

$$
\begin{aligned}
&(S: S)^{-}=\left\{\left(P, P^{\prime}\right): P e S, P^{\prime} € S \text { and } P, P^{\prime} \text { share a facet }\right\} . \\
& \Phi_{S}=\frac{\left.\sum_{(P, P}\right) \in(S: S)}{} \pi(P) \lambda\left(P, P^{\prime}\right) \\
& w\{S) \\
&=\frac{\sum_{\left(P, P^{\prime}\right) \in(S: S)} \min \left\{\psi(P), \psi\left(P^{\prime}\right)\right\}}{4 m \sum_{P \in S} \psi(P)}
\end{aligned}
$$

Observe next that if $x, x^{\prime}$ lie in the same cell $P$ then

$$
\phi(x) / \phi\left(x^{\prime}\right) \leq \exp \{\operatorname{Afdiam}(\mathbf{P})\}
$$

$$
\begin{aligned}
& \leq \exp \left\{\frac{M m^{3 / 2}}{N}\right\} \\
& \leq c^{1 / 5}
\end{aligned}
$$

Thus, if $R=\backslash J\{P: P € 5\}$ and $W=d R \backslash d C(A)$, then

$$
\sum_{P e S} \psi(P) \leq e^{1 / 5} \int_{R} \phi(x) d x
$$

and

$$
N^{1-m} \sqrt{m} \sum_{(P, P>) S(S: 5)} m \dot{m}\left\{x(>(P), x i\rangle\left(P^{f}\right)\right\}>\mathrm{e}^{11 / 5} I_{J W}\langle f\rangle\{x) d x .
$$

(The volume of each cell is $\mathrm{JV} \sim^{\mathrm{m}}$ and each of its facets has area at most $7 \mathrm{~V}^{1}-{ }^{\mathrm{m}}{ }_{\mathrm{v}}{ }^{\mathbf{m}}$.) It follows that

$$
\begin{aligned}
\Phi_{S} & \geq \frac{e^{-2 / 5}}{4 N m^{3 / 2}} \frac{\int_{W} \phi(x) d x}{f_{R}\langle t\rangle(x) d x} \\
& \geq \frac{e^{-2 / 5}}{4 N m^{3 / 2}} \cdot \frac{2}{\operatorname{diam} \zeta(A)} \\
& >\frac{1}{Z m H N^{\prime}}
\end{aligned}
$$

The second inequality is a sharpening of an inequality of Applegate and Kannan [3] from Dyer and Frieze [11]. This inequality is a generalisation of the Lovász-Simonovits isoperimetric inequality used in Theorem 1 and relies on the fact that $\langle f\rangle(x)$ is log-concave. Thus the conductance $\$$ satisfies

$$
-\mathrm{Zm} * n N
$$

We need an upper bound on the total probability of cells at distance greater than $d$ from 6. Now each cell Ps,i contains a ball of radius $p=(y / \overline{i n} N)^{\prime l}$ centred at $<\boldsymbol{T B ;}$;- Hence the number of cells meeting a ball of radius $r$ is at
most $((r+\rho) / \rho)^{m}$. Hence if $\Omega_{d}$ denotes the set of cells with centre at distance at least $d$ from $b$ then

$$
\begin{aligned}
\psi\left(\Omega_{d}\right) & \leq \sum_{k=1}^{\infty}\left(\frac{d+k \rho}{\rho}\right)^{m} \exp \{-M(d+(k-1)) \rho\} \\
& =e^{-M(d-\rho)} \rho^{-m}\left(\sum_{k \rho \leq d}(d+k \rho)^{m} e^{-M k \rho}+\sum_{k \rho>d}(d+k \rho)^{m} e^{-M k \rho}\right) \\
& \leq e^{-M(d-\rho)} \rho^{-m}\left(2^{m} d^{m}+10 m^{2} 2^{m} d^{m} e^{-M d}\right)
\end{aligned}
$$

For the first sum we replace $(d+k \rho)$ by $2 d$. For the second sum we replace ( $d+k \rho$ ) by $2 k \rho$ and then observe that the ratio of successive terms is $(1+1 / k)^{m} e^{-M \rho} \leq \exp \left\{\frac{m}{k}-M \rho\right\} \leq \exp \left\{\frac{m \rho}{d}-M \rho\right\} \leq e^{-M \rho / 2} \leq 1-\frac{1}{10 m^{2}}$, since $M>2 m / d$, and $M \rho \geq 1 /\left(5 m^{2}\right)$. Now, using this latter inequality again, together with $M \geq 4, \rho \leq d / 2$,

$$
\begin{equation*}
\psi\left(\Omega_{d}\right) \leq e^{-M d / 2}\left(10 M m^{2}\right)^{m+1} \tag{11}
\end{equation*}
$$

To bound this, let $\lambda=M d / 2(m+1)$. Then

$$
\begin{aligned}
\psi\left(\Omega_{d}\right) & \leq\left(20 \lambda e^{-\lambda} m^{2}(m+1) / d\right)^{m+1} \\
& \leq\left(40 e^{-\lambda / 2} m^{3} / d\right)^{m+1} \\
& \leq \frac{\delta}{4}
\end{aligned}
$$

provided $\lambda \geq 2\left(\log \left(40 m^{3} / d\right)+\frac{1}{m+1} \log (\delta / 4)\right)$. Since our value of $M$ is large enough to ensure this, we have the bound. Moreover, since $\phi(b)=1$, we see that if $b$ lies in a cell $P$ then $\psi(P) \geq \frac{1}{2}$. Thus

$$
\pi\left(\Omega_{d}\right) \leq 2 \psi\left(\Omega_{d}\right) \leq \delta / 2
$$

We also need a lower bound on the steady state probability of the initial cell. If this is $P_{0}$, then using the bound on the diameter of $\zeta(A)$,

$$
\psi\left(P_{0}\right) \geq \exp \{-M n \sqrt{m}\}
$$

Also, since $\psi(P) \leq 1$ for all cells $P \in \Omega$,

$$
\psi(\Omega) \leq\binom{ n}{m} N^{m} \leq(e n N / M)^{m} \leq(15 M n \sqrt{m})^{m}
$$

Thus

$$
1 / \pi\left(P_{0}\right) \leq(15 M n \sqrt{m})^{m} \exp \{M n \sqrt{m}\}=C_{0}
$$

say. We now use our conductance bound and Theorem 2. This implies that after $T$ steps the probability we are in $\Omega_{d}$ is at most

$$
\begin{aligned}
\left(\frac{\delta}{2}+\sqrt{C_{0}}\left(1-\frac{\Phi^{2}}{2}\right)^{T}\right) & \leq \frac{\delta}{2}+\sqrt{C_{0}} \exp \left\{-\frac{T}{18 m^{4} n^{2} N^{2}}\right\} \\
& \leq \delta
\end{aligned}
$$

on substituting the relevant values. The time estimate for METROPLEX is $O(T m n)$ and Theorem 4 is proven.

We now return to the solution of $\operatorname{LP}(b)$. Let $x^{*}$ be the (lexicographically first) optimum solution. Since it is a basic solution, and $A$ is totally unimodular, we have

$$
\left\|x^{*}\right\|_{\infty} \leq \beta=\|b\|_{1} .
$$

Now change variables to $y=x / 2 \beta$ so that $\left\|y^{*}\right\| \leq \frac{1}{2}$ and define $b^{\prime}=b /(2 \beta)$. We now run METROPLEX on the problem $\operatorname{LP}^{\prime}\left(b^{\prime}\right)$ with $d=\frac{1}{6 m^{2} n}$ and $\delta=$ $\frac{1}{2 m}$. Suppose it is successful and produces $\hat{y}$ and $\hat{b}=A \hat{y}$ where $\|\hat{b}\|_{1} \geq$ $\frac{1}{3}$. It follows from a theorem of Cook, Gerards, Schrijver and Tardos (see Schrijver $[20, \mathrm{p} 126])$ that $\left\|\hat{y}-y^{*}\right\|_{\infty} \leq n d=\frac{1}{6 m^{2}}$ where $y^{*}=x^{*} /(2 \beta)$ solves $\mathrm{LP}^{\prime}\left(b^{\prime}\right)$. Clearly $\hat{y}_{j}=0$ for non-basic $j$ (else $\left\|\hat{y}-y^{*}\right\|_{\infty} \geq \frac{1}{2}$.) Also, since $A$ is a $0, \pm 1$ matrix and $\hat{y}$ is a basic solution, the largest component $\hat{y}_{\ell}$ of $\hat{y}$ is at least $\frac{1}{m}\|\hat{b}\|_{\infty} \geq \frac{1}{3 m^{2}}$. Hence

$$
y_{l}^{*} \geq \hat{y}_{\ell}-\frac{1}{6 m^{2}} \geq \frac{1}{6 m^{2}} .
$$

But this implies that xj is basic. Knowing this we can eliminate $x i$ and one row from the problem $\operatorname{LP}(6)$. Hence after $m$ successful iterations the problem will be solved. We thus have the following

Theorem 5 With probability at least $\backslash$ the above algorithm solves $L P(b)$. The running time is $O\left(r n^{I 7 B} n^{7} I^{3}(m n)\right)$ and so the algorithm is strongly polynomial

Of course repeated applications of the above algorithm will make the failure probability as small as we like.

## Remark

The above analysis can be applied to matrices $A$ whose entries axe $0, \pm 1, \pm 2$ and in which the sum of the absolute values in each column are at most 2. Call this an S-matrix and observe that the property is preserved under Gaussian elimination after removing the pivot row and column i.e. after removing the "discovered" basic variable. The crucial property for the success of METROPLEX is that the ratio of face surface area to volume is polynomially bounded for each cell. With a polynomial ratio of area to volume we can use (weighted) surface area and volumes as approximations in estimating conductance.

Assume $A$ is an S-matrix and $B$ is a basis matrix. Observe that $B \backslash$ is the matrix formed by deleting column 1 from $B$ then the (m-I)-dimensional volume of ((B) spanned by the last $\mathbf{m}-1$ columns of $\boldsymbol{B}$ satisfies

$$
\boldsymbol{S}^{2}=\operatorname{det} \boldsymbol{B} \boldsymbol{\bullet} \boldsymbol{B}_{X}
$$

$$
=\sum_{i=2}^{m}\left(\operatorname{det} B_{i, 1}\right)^{2}
$$

where $B_{\text {ifl }}$ is the matrix obtained by deleting row $t^{*}$ and column 1 . We will have (almost) justified our remark if we can prove, say, that

$$
\begin{equation*}
\left|B_{1,1}\right| \leq 2 \mid \text { detB } \mid \tag{12}
\end{equation*}
$$

Let the entries of $B$ be denoted 6 ,-j. If $\left|6_{1 t} i\right|=2$ then $|\operatorname{det} B \backslash=2| \operatorname{det} B_{1 f 1} \mid$. So assume w.l.o.g. that $\mathcal{\&} i \boldsymbol{i}=1$. Suppose J5i,i has r columns with $\pm 2$ 's in them. Then det $B_{X t} i \leq 2^{r+1}$ (since a non-singular $S$-matrix without $\pm 2^{\prime} s$ has determinant $\pm 1, \pm 2$ ). Using Gaussian elimination to remove the (at most one) non-zero ( $\pm 1$ ) entry in column 1 of $B$ we see that det $B \geq T$ and (12) follows.

The above analysis shows that the conductance is sufficiently large. The remainder of the proof can easily be justified once we observe that $B^{\prime \prime 1}$ has entries in $\{0, \pm \underset{2}{j}, \pm 1, \pm 2\}$.

## 5 Diameter of a polyhedron

In this section we give a polynomial bound on the combinatorial diameter 7Q of the polyhedron

$$
Q=\left\{x e R^{m}: A^{T} x \leq c\right\}
$$

where $A$ is a totally unimodular $m x n$ matrix, (By combinatorial diameter we mean the diameter of the graph induced by the vertices and edges of $Q$.)

We can assume that $Q$ is non-degenerate. If not then a change of $\mathbf{c}$ to $\mathbf{c}^{\wedge}$ will make it non-degenerate and the combinatorial diameter will not decrease.

Take two vertices $v i, v_{2}$ of $Q$. For $\mathbf{t}=\mathbf{1 , 2}$ the support of $\mathbf{v}$; decomposes $A$ into $B_{\{ }$and $J_{i}$ and correspondingly $\mathbf{c}$ into $<?_{B}^{\prime}, c^{\%}{ }_{N}$ such that

$$
B j v i=<4, \quad N j v i<4, \quad \mathbf{i}=1,2 .
$$

Let $\mathbf{e}$ denote the $\mathbf{m}$-dimensional vector of all l's and $\mathrm{A} ;=\|\neq \mathrm{te}\| \mathrm{li}\left({ }^{*}=1>2\right)$. Note $A_{r} \geq 1$. We then let

$$
6 i=\frac{1}{20 A_{t A} / \wedge \wedge^{e}}
$$

Clearly 6* G CM- Note that $\left\|\sigma_{t}\right\|_{-}<\|b i\|_{x}=l /(20 y / \overline{r n})$. Thus $v_{i}$ is the (unique) optimum solution to
maximise bjx subject to $\boldsymbol{x} €($ ?
By duality $f_{t} \cdot$ is also the optimum basis matrix for the problem $\operatorname{LP}\left(\boldsymbol{f}_{\boldsymbol{f}}\right)$ of Section 2.

We discuss applying a modification of the random walk of the previous section starting at 61 with target 62 - The modification will be that we will only walk on cells ft' for which the centre

$$
<, € £>=\left\{*: \|^{\star}-M l_{<} f^{\wedge}\right\}-
$$

Note that the cell containing 61 belongs to $\mathrm{ft}^{\prime}$. By doing this we ensure that (in the notation of Theorem 3 ) $\hat{\mathfrak{f}}(6)=0$ for each cell centre 6 . In fact $\mid(6){ }^{\wedge} 0$ implies $\|\sigma\| \geq l / y / m$. To see this observe that now 6 is outside any of the paxallelopipeds which contain the origin and we have shown (see the argument following (9)) that the distance from the origin to any facet of any of these paxallelopipeds is at least $l / y / r \bar{n}$.) Thus the upper bounds $y_{;} \leq 1$ are inactive in the walk and the bases met axe dual feasible for $\operatorname{LP}(6)_{\text {? }}$ for some 6, and so feasible for the polyhedron $Q$.

Once we show that the conductance of this walk is bounded below by $\mathbf{l} / \mathbf{p}(\mathbf{r n}, \mathrm{n})$ for some polynomial $\boldsymbol{p}$ we will be almost done. For then we will have shown that we can get from $B \backslash$ to $B_{2}$ (with positive probability) by a walk involving a polynomial number of pivots such that all intermediate bases are feasible for $Q$. We will then be able to prove

Theorem 6

$$
7_{Q}=O\left(m^{16} n^{3}(\ln (\mathbf{r n n}))^{3}\right)
$$

D
(Our current estimate for the polynomial must be far from the truth.) Let us first change the sizes of $M, T$ to

$$
\begin{aligned}
M & =\mathrm{riOOm}^{7} /^{2} \operatorname{nln}\left(\mathrm{e}^{10} \mathrm{mV}\right) \mathrm{l} \\
T & \left.=\backslash 10 m^{3 / 2} M N^{2}\right]
\end{aligned}
$$

$N$ remains the same function of $M$ and we promise to run METROPLEX with

$$
=\frac{1}{30 m^{3 / 2} n} \text { and } \delta=\frac{1}{2 m} .
$$

In order to prove the theorem we use the notion of //-conductance introduced by Lovász and Simonovits [17]. We use the notation of Section 2 here. For $0 \leq x \leq 1$ we let

$$
\begin{equation*}
h t(x)=\max \left\{7 \mathrm{r}^{\wedge}-x: u>€[0,1]^{10,1}, \mathrm{x} \longmapsto=x\right) \tag{13}
\end{equation*}
$$

where now xW , $i r$ axe treated as vectors of length $|\mathrm{ft}|$. Thus $\boldsymbol{h}_{\boldsymbol{t}}$ is a continuous version of the variational distance between $* W$ and TT. For $0 \leq \backslash i \leq 1 / 2$ we let the //-conductance of the chain be

$$
\Phi_{\mu}=\min _{\mu \leq \pi(I) \leq 1 / 2}\left\{\frac{\sum_{i \in I, j \in I} \pi_{i} p_{i j}}{\pi(I)-\mu}\right\} .
$$

Lovász and Simonovits proved the following generalisation of Theorem 2:

Theorem 7 Let $C=\max \left\{h_{0}(x): x \in[0, \mu] \cup[1-\mu, 1]\right\}$. Then

$$
h_{t}(x) \leq C+\exp \left\{-\frac{1}{2} \Phi_{\mu}^{2} t\right\} / \sqrt{\pi_{0}}
$$

We now proceed to bound $C$ and $\Phi_{\mu}$ where we let

$$
\begin{equation*}
\mu=e^{-M /(4 \sqrt{m})} \tag{14}
\end{equation*}
$$

which from (11) (with $d=8 /(9 \sqrt{m})$ ) is an upper bound to the limiting probability of the walk being in a cell which meets the boundary of the ball D.

## Upper bound for $\mathbf{C}$

Suppose now that $b_{1}$ lies in a cell $P_{0}$ and that $\pi_{0}=\pi\left(P_{0}\right)$. Then

$$
\begin{align*}
\pi_{0} & =\frac{\psi\left(P_{0}\right)}{\sum_{P \in \Omega^{\prime}} \psi(P)} \\
& \geq \frac{e^{-M /(9 \sqrt{m})}}{\binom{n}{m} N^{m}} \\
& \geq e^{-M /(8 \sqrt{m})} \tag{15}
\end{align*}
$$

Suppose first that $0 \leq x \leq \mu$. Then from (13) and (15) we have

$$
\begin{aligned}
h_{0}(x) & =\frac{x}{\pi_{0}}-x \\
& \leq \mu e^{M /(8 \sqrt{m})} \\
& =e^{-M /(8 \sqrt{m})}
\end{aligned}
$$

If $1-\mu \leq x \leq 1$ then (13) implies that $h_{0}(x) \leq \mu$ and so

$$
\begin{equation*}
C \leq e^{-M /(8 \sqrt{m})} \tag{16}
\end{equation*}
$$

## Lower bound for $\boldsymbol{\Phi}_{\boldsymbol{\mu}}$

Suppose now that $S \subseteq \Omega^{\prime}$ and $\mu \leq \pi(S) \leq 1 / 2$. Let $\hat{D}=\{b \in \zeta(A)$ : $\left.\left\|b-b_{2}\right\| \leq \frac{9}{10 \sqrt{m}}-\frac{m^{3 / 2}}{N}\right\}$, and note that

$$
\begin{equation*}
\hat{D} \subseteq \bigcup_{P \in \Omega^{\prime}} P \tag{17}
\end{equation*}
$$

Let $\hat{S}=\{P \in S: \sigma(P) \in \hat{D}\}$ and $\hat{\bar{S}}=\left\{P \in \Omega^{\prime} \backslash S: \sigma(P) \in \hat{D}\right\}$. Next let $\hat{R}=\hat{D} \cap\left(\cup_{P \in S} P\right)$ and let $\hat{W}=\partial \hat{R} \backslash \partial \hat{D}$. Then

$$
\begin{aligned}
\Phi_{S} & =\frac{\sum_{\left(P, P^{\prime}\right) \in(S: \bar{S})} \pi(P) \lambda\left(P, P^{\prime}\right)}{\pi(S)-\mu} \\
& \geq \frac{\sum_{\left(P, P^{\prime}\right) \in(\hat{S}: \hat{S})} \pi(P) \lambda\left(P, P^{\prime}\right)}{\pi(\hat{S})}
\end{aligned}
$$

since $(\hat{S}: \hat{\bar{S}}) \subseteq(S: \bar{S})$ and $\pi(S) \leq \pi(\hat{S})+\mu$. Applying the reasoning of the previous section to $\hat{D}$ we obtain

$$
\begin{aligned}
\Phi_{S} & \geq \frac{e^{-2 / 5}}{4 N m^{3 / 2}} \frac{\int_{\hat{W}} \phi(x) d x}{\int_{\hat{R}} \phi(x) d x} \\
& \geq \frac{e^{-2 / 5}}{4 N m^{3 / 2}} \cdot \frac{2}{\operatorname{diam}(\hat{D})} \\
& \geq \frac{1}{6 m N}
\end{aligned}
$$

and so

$$
\begin{equation*}
\Phi_{\mu} \geq \frac{1}{6 m N} \tag{18}
\end{equation*}
$$

Note that it was important for (17) to hold here. Replacing $\hat{D}$ by $D$ would perhaps give an overestimate for the weighted boundary between $S$ and $\bar{S}$. Applying Theorem 7, (11), (16) and (18) we see that after $T$ steps of METROPLEX the probability we are at a distance greater than $d$ from $b_{2}$ is at most $C+1 /(2 m)<1$. The final part of the proof that we can identify a basic variable goes through as we have scaled $d$ by $1 /(10 \sqrt{m})$. (We previously solved $\operatorname{LP}\left(b^{\prime}\right)$ with $\left\|b^{\prime}\right\|_{1}=\frac{1}{2}$ but now $\left\|b_{2}\right\|_{1}=1 /(20 \sqrt{m})$.) Note that identifying a basic variable is equivalent to identifying a facet of $Q$ containing $v_{2}$. The remainder of the path from $v_{1}$ to $v_{2}$ will be restricted to this facet. In all we have to identify $m$ such facets. The total number of pivots required is therefore $O(\mathrm{Tm})$ and Theorem 6 follows.

## 6 Concluding remarks

Our results on random generation extend those of Aldous and Broder for trees. They also differ in one important respect, in that we have showed that the "conductance" approach succeeds for the most natural random walk on these objects. The challenge of generalising these results to arbitrary matroids seems to us most likely to be achieved this way. (Though our proofs give no clue as to how this might be done.)

The time estimate for our linear programming algorithm is clearly rather large. We have not attempted to make its time bound as tight as possible, since our result is merely intended to demonstrate the existence of a polynomial time "simplex" algorithm for this class of problems. There are, of course, worst case strongly polynomial algorithms for these problems [23], but none resembles the simplex method except in very special cases. Note
that since total unimodularity is preserved under duality, our algorithm may also be regarded as a primal simplex method in which cost-increasing pivots are allowed with low probability. We believe our result on totally unimodular linear programs gives the most general problem class for which a strongly polynomial time variant of the simplex method is known to exist. We include all network problems, for example, where the usual variants of the primal simplex method are known not to be even polynomial [25, 9]. The best (exponential) bound here on the number of pivots which is independent of the size of the numbers is due to Tarjan [24], who also gives a polynomial "simplex" algorithm allowing cost-increasing pivots, but with only a weakly polynomial bound on the number of pivots. It must also be observed that Tarjan's algorithms use much of the sophisticated machinery of non-simplex network flow techniques. Thus his methods depart from the spirit of the simplex method in a way which ours do not. The obvious challenge is to generalise our results to linear programs in which the $A$ matrix has bounded entries or, more ambitiously, to arbitrary linear programs. Another issue is to what extent our linear programming algorithm can be de-randomised.

We have given a bound on the combinatorial diameter of polyhedra defined by totally unimodular constraint systems. Thus these polyhedra satisfy the so-called polynomial diameter conjecture [15] which is a weakening of the famous Hirsch conjecture. Again, as far as we know, this is the richest class of polyhedra for which the polynomial diameter conjecture is currently known to be true.

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# RANDOM WALKS, TOTALLY UNIMODULAR MATRICES AND A RANDOMISED DUALSIMPLEX ALGORITHM 

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