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## Local Invertibility of Sobolev Functions

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## 1 Introduction.

The aim of this paper is to give a simple proof of local invertibility of functions $v \in$ $W^{1, N}\left(\Omega, \mathbf{R}^{N}\right)$, where $\Omega \subset \mathbf{R}^{N}$ is an open set and $\operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega$ (Theorem 3.1). We show that the local inverse function $w$ is $W^{1,1}$ and under suitable hypotheses we improve regularity of $w$ to $W^{1, s}$ for some $s>1$. Precisely, it is shown that $v$ is locally invertible almost everywhere in the sense that, for almost every $x \in \Omega$ there is an open neighborhood $D$ of $x$ and there is a function $\boldsymbol{w} \in W^{1,1}(v(D), D)$ such that $v(D)$ is an open set,

$$
\begin{gather*}
v \circ w(y)=y \text { a.e. } y \in v(D),  \tag{1}\\
w \circ v(x)=x \text { a.e. } x \in D \tag{2}
\end{gather*}
$$

and

$$
\begin{equation*}
\nabla w(y)=(\nabla v)^{-1}(w(y)) \text { a.e. } x \in D \tag{3}
\end{equation*}
$$

where $(\nabla v)^{-1}(w(y))$ is the inverse matrix of $\nabla v(w(y))$. Moreover, if we assume that $\left|\frac{\operatorname{adj}(\nabla v)}{\operatorname{det} \nabla v}\right|^{s} \operatorname{det} \nabla v \in L^{1}(\Omega)$ for some $1 \leq s<+\infty$ then as in [Sv], we prove that $w \in$ $W^{1, s}(v(D), D)$. One can then deduce easily that if $\operatorname{det} \nabla v(x) \geq \gamma>0$ a.e. $x \in \Omega, v \in$ $W^{1, q}(\Omega)^{N}$ and $q \geq N(N-1)$, then $v: D \rightarrow v(D)$ and $w: v(D) \rightarrow D$ are homeomorphisms, (1) holds for every $y \in v(D)$, (2) holds for every $x \in D, w \in W^{1, N}(v(D), D)$ and $v$ is an open mapping on $\Omega \backslash L$ for a suitable $L \subset \mathbf{R}^{\boldsymbol{N}}$ which has zero measure (see Corollary 3.3). In particular, we conclude that if $N=2, v \in W^{1,2}(\Omega)^{2}$ and $\operatorname{det} \nabla v(x) \geq \gamma>0$ a.t. $x \in \Omega$ then $w \in W^{\mathbf{1 , 2}}(v(D), D)$ and there is a set of measure zero $L \subset \mathbf{R}^{N}$ such that $v$ is an open mapping on $\Omega \backslash L$ and we obtain a weaker version of [IS].

Conversely if $v \in W^{1, q}(\Omega)^{N}$, for some $q>N, \operatorname{det} \nabla v(x) \neq 0$ a.e. $x \in \Omega$ and if for almost every $x_{0} \in \Omega v$ is locally almost invertible in a neighborhood of $x_{0}$ in the sense of (1)- (3), then there are open sets $\Omega_{1}, \Omega_{2} \subset \mathbf{R}^{N}$ and a set of measure zero $N \subset \mathbf{R}^{N}$ such that $\Omega=\Omega_{1} \cup \Omega_{1} \cup N, \operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega_{1}$ and $\operatorname{det} \nabla v(x)<0$ a.e. $x \in \Omega_{2}$ (see Corollary 3.2).

Note that a homeomorphism $v \in W^{1, \infty}(\Omega)^{N}$ need not to satisfy $\operatorname{det} \nabla v(x) \neq 0$ a.c. $x \in$ $\Omega$. Such an example is provided in [MZ] (see Remarks 3.4).

The result in this paper is in the same spirit as the work in [Ba] (1981), [CN] (1987), [Sv] (1988) and [TQ] (1988). As far as we know, the existence and the regularity of the local inverse function $w$ is not an immediate consequence of these earlier results where assumptions are placed either on the trace $\left.v\right|_{\partial \Omega}$ or on $|v(\Omega)|$. By an elementary lemma (Lemma 3.5) and the invertibility result found in [TQ], one can obtain the existence of the local inverse function $w$ and then deduce its regularity. Due to his relaxed assumption $q>$ $N-1$ (here we have $q \geq N$ ), Q. Tang used an elaborated method to obtain the existence of an inverse $w \in W_{l o c}^{1,1}$ under the condition introduced by $[\mathrm{CN}], \int_{\Omega} \operatorname{det} \nabla v(x) d x \leq|v(\Omega)|$.

The proof that we present here concerning the local invertibility of $v$ is independent of the work by [Ba], [CN], [Sv], [TQ], and the method employed relies on basic properties of the degree theory.

In the sequel of this paper, we fix a bounded, open set $\Omega \subset \mathbf{R}^{N}$ and we consider a function $v \in W^{1, q}(\Omega)^{N}$. We denote by $\nabla v$ the gradient of $v$ i.e. the $N \times N$ matrix of the partial derivatives of $v$ and by $a d j \nabla v$ the adjugate ${ }^{1}$ of $\nabla v$.

As an application of the local invertibility property, we study the weak lower semicontinuity of functionals $E$ of the form

$$
E(u, v)=\int_{\Omega} W\left(\nabla u(x)(\nabla v(x))^{-1}\right) d x
$$

defined on the set

$$
B_{p, q}=\left\{(u, v) \in W^{1, p}\left(\Omega, \mathbf{R}^{N}\right) \times W^{1, q}\left(\Omega, \mathbf{R}^{N}\right) \mid \operatorname{det} \nabla v(x)=1 \text { a.e } x \in \Omega\right\}
$$

where $1 \leq p<+\infty, N \leq p \leq+\infty, \frac{1}{p}+\frac{N-1}{q}=\frac{1}{r} \leq 1$. When $N=3, \nabla u(x) \cdot(\nabla v(x))^{-1}$ represents the lattice of a neutral elasto-plastic change of state of a perfect cubic crystal, $u$ is the elastic deformation and $v$ corresponds to the slip or plastic deformation. (for details, see Ericksen [Er], Davini \& Parry [DP], Fonseca \& Parry [FP] and Dacorogna \& Fonseca [DF]). We prove that, under some convexity and growth assumptions on the function $W, E$ is weakly lower semicontinous on $B_{p, q}$. If $r>1$ and $q \neq+\infty$ we rely on the div-curl lemma (see Tartar [Ta]) to prove that

$$
\nabla u_{\epsilon} \cdot\left(\nabla v_{\epsilon}\right)^{-1}-\nabla u \cdot(\nabla v)^{-1} \text { weakly in } L^{r}
$$

whenever

$$
\left(u_{\epsilon}, v_{\epsilon}\right) \rightharpoonup(u, v) \text { weakly in } B_{p, q} .
$$

We notice, however, that the growth condition of $W$ and the weak lower semicontinuity of $E$ on $B_{p, q}$ do not always imply the existence of the minimum of $E$ on $B_{p, q}$. Indeed, $\left\{\left(\nabla u_{c} \cdot\left(\nabla v_{\epsilon}\right)^{-1}\right\}\right.$ being relatively compact in $L^{r}$ does not imply that $\left\{\left(\nabla u_{\epsilon}\right\}\right.$ or $\left\{\left(\nabla v_{\epsilon}\right)^{-1}\right\}$ are relatively compact in, respectively, $L^{p}, L^{\frac{9}{-1}}$ (see [DF] Proposition 4.1).

The paper is organized as follows: in the second section we fix notations and recall some definitions and well known properties related to Brouwer degree. In the third section we prove the local invertibility property of the mappings $v \in W^{1, q}\left(\Omega, \mathbf{R}^{N}\right), q \geq N$, under the condition $\operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega$. In view of our applications, in addition we prove that if $v_{\epsilon} \rightharpoonup v$ weakly in $W^{1, q} q \geq N$ and $\operatorname{det} \nabla v_{\epsilon}(x)>0$ then, up to a subsequence, $v_{\epsilon}$ and $v$ are respectively locally invertible on open sets $D_{\epsilon}(x)$ and $D(x)$ for almost every $x \in \Omega$, where $D_{\epsilon}(x)$ and $D(x)$ are neighbourhoods of $x$, such that $v_{\epsilon}\left(D_{\epsilon}(x)\right)=v(D(x))$ does not depend on $\epsilon$. The last section is devoted to the applications where we obtain the weak lower semicontinuity for a class of functionals $E$ on $B_{p, q}$.

[^0]
## 2 Preliminaries.

In the sequel we will use the following notations.
For $x=\left(x_{1}, \cdots, x_{N}\right) \in \mathbf{R}^{N},|x|$ stands for $\left(\left|x_{1}\right|^{2}+\cdots+\left|x_{N}\right|^{2}\right)^{\frac{1}{2}}$ and $|x|_{\infty}:=\max \left\{\left|x_{1}\right|, \cdots,\left|x_{N}\right|\right\}$. If $A \subset \mathbf{R}^{N}|A|$ denotes the Lebesgue measure of $A, A^{c}$ denotes its complement, dist $(x, A)$ is defined by $\inf \{|x-y|: y \in A\}$ and $\rho(x, A)$ is given by $\inf \left\{|x-y|_{\infty}: y \in A\right\}$. If $\Omega \subset \mathbf{R}^{N}$ is an open set, $v \in L^{1}(\Omega)^{N}$, then $\nabla v$ is the $N \times N$ matrix of the distributional derivatives $\frac{\partial v_{i}}{\partial x_{j}}$ and $\operatorname{det} \nabla v$ is the determinant of $\nabla v$.

We recall some properties of mappings.
Lemma 2.1 Let $\Omega$ be a bounded, open set in $\mathbf{R}^{N}$ and $v \in\left(W_{\text {loc }}^{1, N}(\Omega)\right)^{N}$ such that $\operatorname{det} \nabla v(x)>$ 0 a.e. $x \in \Omega$. Then $v$ is a continuous mapping on $\Omega$. Futhermore, if $K$ is a compact set and $V$ is an open set such that $K \subset V \subset \subset \Omega$, then there is a constant $C_{N}$ depending only on $N$, such that

$$
|v(x)-v(y)| \leq M^{\frac{1}{N}} C_{N} \theta(|x-y|)
$$

for every $x, y \in K$ verifying $|x-y| \leq \delta$, where

$$
\begin{gathered}
M=\int_{V}|\nabla v(x)|^{N} d x \\
\theta(t)=\left(\frac{2}{\log \left(\frac{2}{t}\right)}\right)^{\frac{1}{N}}
\end{gathered}
$$

and

$$
\delta=\min \left\{2, \frac{1}{2}\left(\operatorname{dist}\left(K, \mathbf{R}^{N} \backslash V\right)\right)^{2}\right\}
$$

Proof. This lemma is an immediate consequence of Theorem 3.5, p 294, Proposition 3.3, p 292 in [GR] and Theorem 4.4 p 339 in [Re] (see also [Man]). It can also be shown that, under the above hypotheses, $v$ is a monotonic mapping (see the definition of monotonic mapping below).

Definition 2.2 ([GR]) Let $\Omega$ be a bounded, connected, open set in $\mathbf{R}^{N}$ and $v \in W^{1, N}(\Omega)^{v}$. We say that $v$ is monotonic at the point $x \in \Omega$ if there is a number $0<r(x) \leq$ $d(x, \partial \Omega)$ such that for almost every $r \in(0, r(x))$ the pre-image of the intersection of the set $v(B(x, r))$ with the unbounded connected component of $\mathbf{R}^{\boldsymbol{N}} \backslash \boldsymbol{v}(\partial B(x, r))$ is of measure 0 in $B(x, r)$. We say that $v$ is a monotonic mapping in $\Omega$ if $v$ is monotonic at every point $x \in \Omega$.

We make some remarks on the Brouwer degree theory. For details we refer the reader to [Ll].

Let $\Omega \subset \mathbf{R}^{\boldsymbol{N}}$ be a bounded, open set and $v: \bar{\Omega} \rightarrow \mathbf{R}^{\boldsymbol{N}}$, a continuous function. For every $p \in \mathbf{R}^{N} \backslash v(\partial \Omega)$ the Brouwer degree $d(v, \Omega, p)$ of $v$ with respect to $\Omega$ at $p$ is a well defined integer depending only on the boundary values of $v$. In particular if $v \in C^{1}(\bar{\Omega})^{N}$ and $p \in \mathbf{R}^{N} \backslash\left(v(\partial \Omega) \cup v\left(Z_{v}\right)\right)$, we have

$$
d(v, \Omega, p)=\sum_{x \in v^{-1}(p)} \operatorname{sign} \operatorname{det} \nabla v(x)
$$

where

$$
\operatorname{sign} t= \begin{cases}1 & \text { if } t>0 \\ -1 & \text { if } t<0\end{cases}
$$

and $v\left(Z_{v}\right)$ denotes the image of the set $\{x \in \Omega \mid \operatorname{det} \nabla v(x)=0\}$.
We give some additional properties on the degree.
Proposition 2.3 (GGR]) Let $\Omega \subset \mathbf{R}^{N}$ be an open, bounded set, $v \in C^{0}(\bar{\Omega})^{N}$ and let $p \in \mathbf{R}^{N} \backslash v(\partial \Omega)$. Let $C_{p}$ be the connected component of $\mathbf{R}^{N} \backslash v(\partial \Omega)$ containing $p$. Then $w \epsilon$ have the following properties:

$$
\begin{align*}
& d(v, \Omega, p)=d(u, \Omega, p) \text { if } u \in C^{0}(\bar{\Omega})^{N} \text { and }|u-v|_{\infty}<\operatorname{dist}(p, v(\partial \Omega))  \tag{4}\\
& d(v, \Omega, p) \neq 0 \Rightarrow \exists x \in \Omega \text { such that } v(x)=p  \tag{5}\\
& d(v, \Omega, p)=d(v, \Omega, q) \forall q \in C_{p}  \tag{6}\\
& d(v, \Omega, p)=d(\phi, \Omega, p) \text { if } \phi \in C^{0}(\bar{\Omega})^{N} \text { and } \phi=v \text { on } \partial \Omega . \tag{7}
\end{align*}
$$

Moreover, the degree is invariant under homotopy, i.e.

$$
\begin{equation*}
d(H(\cdot, t), \Omega, p)=d(H(\cdot, 0), \Omega, p) \tag{8}
\end{equation*}
$$

for every homotopy $H \in C^{0}(\bar{\Omega} \times[0,1])^{N}$ such that $p \notin H(\partial \Omega, t)$, for every $t \in[0,1]$. Finally, if $K \subset \bar{\Omega}$ is a compact set and $p \notin v(K)$ then (excision property)

$$
\begin{equation*}
d(v, \Omega, p)=d(v, \Omega \backslash K, p) \tag{9}
\end{equation*}
$$

and if $\Omega=\cup_{i=1}^{+\infty} \Omega_{i}, \Omega_{i}$ mutually disjoint open sets then (decomposition property)

$$
\begin{equation*}
\sum_{i} d\left(v, \Omega_{i}, p\right)=d(v, \Omega, p) \tag{10}
\end{equation*}
$$

Proof. We refer the reader to [Ll].
Lemma 2.4 Let $\Omega \subset \mathbf{R}^{N}$ be a bounded, connected, open set and $v \in W^{1, N}(\Omega)^{N}$ such that $\operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega$. Let $f: \mathbf{R}^{\boldsymbol{N}} \rightarrow \mathbf{R}$ be a measurable function. Then
(i) for every measurable set $E \subset \Omega, x \rightarrow f \circ v(x)$ and $y \rightarrow N(v, E, y)$ are measurable and

$$
\begin{equation*}
\int_{E} f \circ v(x)|\operatorname{det} \nabla v(x)| d x=\int_{\mathbf{R}^{N}} N(v, E, y) f(y) d y \tag{11}
\end{equation*}
$$

where $N(v, E, y)$ is the cardinality of the elements of the set $\{x \in E \mid v(x)=y\}$.
(ii) If, in addition, $f$ is a continuous, bounded function, then for every connected, open set $V \subset \subset \Omega$ such that $|\partial V|=0$

$$
\begin{equation*}
\int_{V} f \circ v(x) \operatorname{det} \nabla v(x) d x=\int_{R^{N} \backslash v(\partial V)} d(v, V, y) f(y) d y \tag{12}
\end{equation*}
$$

(iii) If $D \subset \subset \Omega$ is an open such that $|\partial D|=0$ and $p \in \mathbf{R}^{N} \backslash v(\partial D)$, then

$$
\begin{equation*}
d(v, D, p)=\int_{D} f(v(x)) \operatorname{det} \nabla v(x) d x \tag{13}
\end{equation*}
$$

where $V$ is the connected component of $\mathbf{R}^{N} \backslash v(\partial D)$ containing $p$ and $f$ is any nonnegative, continuous real-valued function with compact support in $V$ and satisfying $\int_{\mathbf{R}^{N}} f(x) d x=1$.

Remarks 2.5 A function $v: \Omega \rightarrow \mathbf{R}^{N}$ is said to satisfy the N -property (Lusin's property) if

$$
|v(E)|=0
$$

whenever $E \subset \Omega$ is a measurable set such that $|E|=0$ and $v$ is said to satisfy the $N^{-1}$-property if

$$
\left|v^{-1}(A)\right|=0
$$

whenever $A \subset \mathbf{R}^{N}$ is a measurable set such that $|A|=0$.
a) It is known that if $v \in W^{1, N}(\Omega)^{N}, \operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega$ then $v$ satisfies the N and the $N^{-1}$-property (see [GR], p. 296-297).
b) Also, if $v \in W^{1, q}(\Omega)^{N}$ with $q>N$ then $v$ satisfies the $N$-property (For details we refer the reader to $[\mathrm{MM}]$ ).

Proof of Lemma 2.4. We refer the reader to [GR], Theorem 1.8, p. 280, Theorem 2.6, p. 288 or also to $[\mathrm{Sv}]$ for the proof of (11) and (12) in the case where $D$ is a domain.

First we prove that (12) is still valid even if $D$ is not connected and (13) is a by-product of this fact. To achieve this, let us remark that by Vitali's covering theorem there are $\left\{D_{i}\right\}$ a countable family of open balls mutually disjoint and a set $N$ of measure zero such that $\left(\cup_{i} D_{i}\right) \cap N=0$ and

$$
\left(\cup_{i} D_{i}\right) \cup N=D
$$

Setting $B=\cup_{i} D_{i}$, we have $\cup_{i} \partial D_{i} \subset \partial B$. If $y \in \mathbf{R}^{N} \backslash(v(\partial B) \cup v(\partial D))$, then by the decomposition formula (10)

$$
\begin{equation*}
\sum_{i} \chi_{v\left(D_{i}\right)} d\left(v, D_{i}, y\right)=\sum_{i} d\left(v, D_{i}, y\right)=d(v, B, y) . \tag{14}
\end{equation*}
$$

Let $K=\bar{D} \backslash B$. As $K$ is a compact set and $K \subset \partial D \cup N$, if $y \notin v(K)$ then, by the excision property of the degree (9), we obtain

$$
\begin{equation*}
d(v, D, y)=d(v, D \backslash K, y)=d(v, B, y) \tag{1.5}
\end{equation*}
$$

Using the fact that $v$ has the $N$-property (see Remark 2.5), $D_{i} \subset \subset \Omega,|\partial D|=|N|=$ $\left|\partial D_{i}\right|=0$, by (12), (14) and (15) we obtain

$$
\begin{aligned}
\int_{D} f \circ v(x) \operatorname{det} \nabla v(x) d x & =\int_{B} f \circ v(x) \operatorname{det} \nabla v(x) d x \\
& =\sum_{i} \int_{D_{i}} f \circ v(x) \operatorname{det} \nabla v(x) d x \\
& =\sum_{i} \int_{v\left(D_{i}\right) \backslash v\left(\partial D_{i}\right)} d\left(v, D_{i}, y\right) f(y) d y \\
& =\int_{v(B) \backslash v(\partial B)} d(v, B, y) f(y) d y \\
& =\int_{v(D) \backslash v(\partial D)} d(v, D, y) f(y) d y .
\end{aligned}
$$

Since $\int_{\mathbb{R}^{N}} f(x) d x=1$ and as the compact support of $f$ is included $V$, we conclude that

$$
\int_{D} f \circ v(x) \operatorname{det} \nabla v(x) d x=d(v, D, p)
$$

Definition 2.6 Let $\Omega \subset \mathbf{R}^{N}$ be an open set, let $v: \Omega \rightarrow \mathbf{R}^{N}$ be a function and $x_{0} \in \Omega$. 1.- We say that $v$ is completely differentiable at $x_{0}$ if there is a number $R_{0}>0$, a function $\epsilon: \mathbf{R} \rightarrow \mathbf{R}$ and $a N \times N$ matrix $\nabla v\left(x_{0}\right)$ such that

$$
v\left(x_{0}+h\right)=v\left(x_{0}\right)+\nabla v\left(x_{0}\right) h+|h| \epsilon(|h|)
$$

for every $h \in B\left(0, R_{0}\right)$ and $\lim _{t \rightarrow 0} \epsilon(t)=0$. In this case we call $\operatorname{det} \nabla v\left(x_{0}\right)$ the Jacobian of $v$ at $x_{0}$.
2.- We say that $v$ is weakly differentiable at $x_{0}$ if there is a set $A \subset \mathbf{R}$ and $a N \times N$ matrix $\nabla v\left(x_{0}\right)$ such that $\lim _{r \rightarrow 0} \frac{\mid \text { An }[0, r] \mid}{r}=1$ and

$$
\liminf _{t \rightarrow 0, t \in A} \gamma_{x_{0}}(t)=0
$$

where

$$
\gamma_{x_{0}}(t)=\sup \left\{\left.\left|\frac{v\left(x_{0}+t z\right)-v\left(x_{0}\right)}{t}-\nabla v\left(x_{0}\right) z\right|| | z \right\rvert\,=1\right\}
$$

In this case we call $\operatorname{det} \nabla v\left(x_{0}\right)$ the weak Jacobian of $v$ at $x_{0}$.
Lemma 2.7 Let $\Omega$ be a bounded open set in $\mathbf{R}^{N}$.
i) If $v \in W^{1, N}(\Omega)^{N}$ is a monotonic mapping, then $v$ is almost everywhere in $\Omega$ completely differentiable.
ii) If $v \in W^{1, q}(\Omega)^{N}, q>N$, then $v$ is almost everywhere in $\Omega$ completely differentiable.
iii) If $v \in W^{1, q}(\Omega)^{N}, q>N-1$, then $v$ is almost everywhere in $\Omega$ weakly differentiable.

Proof. We refer the reader to [GR] Theorem 5.4, p. 175, to [Re] and to [MZ].

## 3 Local invertibility in $W^{1,9}$.

We first state the main result of this section (Theorem 3.1) and some of its corollaries.
Theorem 3.1 Let ft $\mathbf{C} R^{N}$ be a bounded, open set and let $v € W^{h N}(Q)^{N}$ be a function such that $\operatorname{det} V v(x)>0$ a.e. $x €$ ft. Then for almost every $x_{0} G \mathbf{f t}, \mathrm{t}$; is locally almost invertible in a neighborhood of $x^{\wedge}$ in the sense that there exists $r \equiv r\left(x_{0}\right)>0$, an open set $D=D\left(x_{0}\right) \mathbf{C C}$ ft and a function $w: B(y o, r)-\bullet / ?$, with $\mathbf{j} / \mathbf{t}=\mathbf{t}\left(\mathrm{x}_{0}\right)$, such that

$$
\begin{aligned}
& w \in W^{1,1}\left(B\left(y_{0}, r\right)\right)^{N} \\
& w 0 v(x)=x \text { a.e. } x € D \\
& v 0 w(y)=y \text { a.e. } y € B\left(y_{0}, r\right), \\
& V w(y)=(V v) \sim(w(y)) \text { a.e. } y € B\left(y_{o}, r\right) .
\end{aligned}
$$

If, in addition, $\backslash^{\wedge} \wedge \backslash^{9} \operatorname{det} V v € L^{l}(Q)$ for some $1<s<+\mathbf{o o}$ then $w \in W^{l * *}\left(B\left(y_{0}, r\right), D\right)$.
Before proving Theorem 3.1 we list some of its consequences.
Corollary 3.2 Let ft $\mathrm{C} R^{N}$ be a bounded, open set, $q \geq N$, and $v e W^{h q}(Q,)^{N}$ be a function such that $\operatorname{det} V v(x) \wedge 0$ a.e. $x \notin \mathrm{ft}$.
a) Assume that fti,ft2 $\mathbf{C} R^{N}$ are two open sets and $N \mathbf{C} \mathbf{R}^{\mathrm{N}}$ is a set of measure zero such that $\mathrm{ft}=\mathrm{fti} \mathrm{U} \mathbf{f t i} \mathrm{U} N, \operatorname{det} V \boldsymbol{v}(x)>0$ a.e. $\boldsymbol{x} € \mathrm{ftj}$, and $\operatorname{det} V v(x)<0$ a.e. $x € \mathrm{fi}_{2}$. Then for almost every $X Q € \mathrm{ft} v$ is locally almost invertible in a neighborhood of $x_{0}$ in the sense above.
b) Conversely, if $q>N$, $\left.v 6 \mathrm{~W}^{\wedge} \mathrm{ft}\right)^{\wedge}$ and iffor almost every $x_{0} 6 \mathrm{ft} v$ is locally almost invertible in a neighborhood of $x_{0}$, then there are open sets $\mathrm{ft}_{\mathrm{x}}, \mathrm{ft}_{2} \mathrm{C} \mathrm{R}^{\mathrm{N}}$ and a null set $N C R^{N}$ such that $\mathrm{ft}=\mathrm{fti} \mathrm{U} \mathrm{ft}_{2} \mathrm{U} \mathrm{JV}, \operatorname{det} V v(x)>0$ a.e. $x € \mathrm{fti}$, and $\operatorname{detV} v(x)<0$ a.e. $x € f t 2-$

Corollary 3.3 Let $q \geq N$, let $\mathrm{ft}^{\mathbf{C}} \mathrm{R}^{\mathrm{N}}$ be a bounded, open set and let $\left.v € \mathrm{~W}^{\wedge} \mathrm{ft}\right) *$ be $a$ function such that $\operatorname{det} \operatorname{Vv}(x)=1$ a.e. $x € \mathrm{ft}$. Then the inverse function $w$ of Theorem S.I is such that

$$
w \quad € \quad W^{l}>? \&(v(D))^{N} .
$$

If, in addition, $q \geq N(N-1)$ then $w o v(x)=x$ for every $x 62$ ?, $v$ o $w(y)=y$ for every $y € B(y o, r), v$ is a local homeomorphism and $v$ is an open mapping on $\mathrm{ft} \backslash \mathrm{X}$ for some set $L \mathbf{C}$ ft of zero measure. In particular, if $N=2$ then $N(N-1)=N=2$ and $v i * a$ local homeomorphism at XQ.

We make some remarks and state some lemmas needeed for the proofs of Corollaries 3.2 and 3.3 , which will appear at the end of this section.

## Remarks 3.4

1.- Recall that $v \in W^{1, N}(\Omega)^{N}$ is said to be a mapping of bounded distortion if $|\nabla v(x)|^{N} \leq$ $K(\operatorname{det} \nabla v(x))$ for almost every $x \in \Omega$ and for some constant $K$. It is well known that every mapping of bounded distortion $v \in W^{1, N}(\Omega)^{N}$ is locally a homeomorphism at almost every point $x_{0} \in \Omega$ (see [Re] Theorem 6.6, pp. 187). Moreover mappings of bounded distortion are open mappings or constant in $\Omega$ (see [Re] Theorem 6.4, pp. 184).
2.- Note that, even if $v \in C^{1}(\bar{\Omega})^{N}$ is such that $\operatorname{det} \nabla v(x) \geq \gamma>0 \quad \forall x \in \Omega$, we cannot expect a global invertibility of $v$ without any regularity assumptions on the trace of $v$. As an example consider

$$
\Omega=\left\{(x, y) \in \mathbf{R}^{2}: 1<x^{2}+y^{2}<2\right\}, \quad v(x, y)=\left(x^{2}-y^{2}, 2 x y\right) .
$$

For every $(x, y) \in \Omega$ we have $\operatorname{det} \nabla v(x, y)=4\left(x^{2}+y^{2}\right) \geq 4$ although $v(x, y)=v(-x,-y)$ (see also [Ba]).
3.- Under the assumptions of Theorem 3.1, we cannot expect $v$ to be locally invertible everywhere. The following example is provided in [Ba]: let $N \geq 3$ and consider the cylinder

$$
\Omega=\left\{x \in \mathbf{R}^{N}: 0 \leq R<1,\left|x_{N}\right|<2\right\}
$$

where $x=\left(x_{1}, \cdots, x_{N}\right), R=\sqrt{x_{1}^{2}+\cdots+x_{N-1}^{2}}$ and $v=\left(v_{1}, \cdots, v_{N}\right)$ is defined by

$$
\begin{aligned}
& v_{i}(x)=R^{-\alpha} x_{i}, \quad i=1, \cdots, N-1 \\
& v_{N}(x)=R^{\beta} x_{N}, \quad\left|x_{N}\right| \leq 1 \\
& v_{N}(x)=\left[2\left(\left|x_{N}\right|-1\right)+\left(2-\left|x_{N}\right|\right) R^{\beta}\right] \operatorname{sign} x_{N}, \quad 1 \leq\left|x_{N}\right| \leq 2
\end{aligned}
$$

where $N<q<N(N-1), \frac{1}{N-1}-\frac{1}{q}<\alpha<\frac{N-1}{q}, \beta=\alpha(N-1)$. It is shown in [Ba] that $v \in W^{1, q}(\Omega)^{N}, \operatorname{det} \nabla v(x)>1-\alpha>0$ almost everywhere. However, one can easily see that

$$
v^{-1}(0)=\{(0, \cdots, 0, \lambda):|\lambda| \leq 1\}
$$

and so $v$ cannot be locally invertible at any point $(0, \cdots, 0, \lambda)$ for $|\lambda| \leq 1$.
4.- An example of a mapping $v \in W^{1, \infty}(\Omega)^{2},\left(\Omega \subset \mathbf{R}^{2}\right)$ is exhibited in [Ba], with $\operatorname{det} \nabla v(x)=1$ a.e. $x \in \Omega$, for which there is no sequence $v_{r} \in C^{1}(\bar{\Omega})^{2}$ such that $v_{r} \rightarrow v$ uniformly and $J_{\nu_{r}}(x)>0$ a.e. $x \in \Omega$. Therefore, to prove Theorem 3.1 one cannot approximate the function $v$ by a sequence of smooth functions $v_{r}$, expecting the functions $v_{r}$ to be locally invertible.
5.- Note that for every bounded, open set $\Omega \subset \mathbf{R}^{\boldsymbol{N}}$, there exist a measurable set $E \subset \Omega$ of non-zero measure and a homeomorphism $v \in W^{1, \infty}(\Omega)^{N}$ such that $\operatorname{det} \nabla v(x)=0$ for
every $x \in E$. The following example is provided in [MZ], Remarks 3.7. Let $E \subset[0,1]$ be a Cantor set of positive one dimensional measure $0<1-\alpha<1$ and write

$$
v_{1}(x)=v_{1}\left(x_{1}, \cdots, x_{N}\right)=\int_{0}^{x_{1}} \chi_{E^{c}}(t) d t
$$

where $\chi_{E^{c}}$ is the characteristic function of the complement of $E$ in $[0,1]$. Then $v(x)=$ $\left(v_{1}(x), x_{2}, \cdots, x_{N}\right)$ is such that $v \in W^{1, \infty}(\Omega)^{N}$, has $\operatorname{det} \nabla v(x)=0$ a.e. $x \in E \times[0,1]^{N-1}$ and $v$ is a homeomorphism of $[0,1]^{N}$ onto $[0, \alpha] \times[0,1]^{N-1}$.
6.- Due to the previous remark, the assumption $\operatorname{det} \nabla v(x) \neq 0$ a.e. $x \in \Omega$ in Corollary 3.2 is essential.

Lemma 3.5 Let $\Omega \subset \mathbf{R}^{N}$ be an open set, let $v \in C^{0}(\Omega)^{N}$ and $x_{0} \in \Omega$ such that $v$ is completely differentiable at $x_{0}$. Assume that $\operatorname{det}\left(\nabla v\left(x_{0}\right)\right) \neq 0$. Then there is $r_{0}>0$ such that for every $0<r \leq r_{0}$ the following assertions hold:

$$
\begin{align*}
& v\left(x_{0}+h\right) \neq v\left(x_{0}\right) \text { for every } h \in \bar{B}(0, r) \backslash\{0\}  \tag{16}\\
& d\left(v, B\left(x_{0}, r\right), v\left(x_{0}\right)\right)=\operatorname{sign}\left(\operatorname{det} \nabla v\left(x_{0}\right)\right) \tag{17}
\end{align*}
$$

Proof. Since $v$ is completely differentiable at $x_{0}$,

$$
v\left(x_{0}+h\right)=v\left(x_{0}\right)+\nabla v\left(x_{0}\right) h+|h| \epsilon(|h|)
$$

for $h \in \bar{B}\left(0, R_{0}\right)$, some $R_{0}>0$ and $\lim _{t \rightarrow 0} \epsilon(t)=0$. Let

$$
a=\inf \left\{\left|\nabla v\left(x_{0}\right) h\right|, \quad h \in \mathbf{R}^{N},|h|=1\right\}
$$

Since $\operatorname{det}\left(\nabla v\left(x_{0}\right)\right) \neq 0$ we obtain that $a>0$. Using the fact that $\lim _{t \rightarrow 0} \epsilon(t)=0$, we may find $0<r_{0} \leq R_{0}$ such that $|\epsilon(t)| \leq \frac{a}{2}$ for every $|t| \leq r_{0}$.

Claim 1: $v\left(x_{0}+h\right) \neq v\left(x_{0}\right)$ for every $h \in \bar{B}\left(0, r_{0}\right)$ such that $h \neq 0$.
Indeed, if $0<|h| \leq r_{0}$ then $|\epsilon(|h|)| \leq \frac{a}{2}$ and so

$$
\left|\frac{v\left(x_{0}+h\right)-v\left(x_{0}\right)}{|h|}\right| \geq\left|\nabla v\left(x_{0}\right) \frac{h}{|h|}\right|-|\epsilon(|h|)| \geq \frac{a}{2}>0
$$

and we obtain (16).
Claim 2: $d\left(v, B\left(x_{0}, r\right), v\left(x_{0}\right)\right)=\operatorname{sign}\left(\operatorname{det} \nabla v\left(x_{0}\right)\right)$ for every $0<r \leq r_{0}$.
Let us first notice that from (16), $d\left(v, B(0, r), v\left(x_{0}\right)\right)$ is well defined for every $0<r \leq r_{0}$. Fix $0<r \leq r_{0}$ and set

$$
u\left(x_{0}+h\right)=v\left(x_{0}\right)+\nabla v\left(x_{0}\right) h, \quad h \in \bar{B}(0, r)
$$

The function u is a linear mapping defined on $\overline{\mathrm{J}} 3\left(\mathrm{x}_{0}, r\right)$. Since $\operatorname{det}\left(V v\left(x_{0}\right)\right) \wedge 0$ we know that u is a one-to-one mapping and so $u\left(x_{0}\right) \wedge u(x)$ for every $x \mathrm{G} d B\left(x_{o}, r\right)$ i.e. $v\left(x_{0}\right) \wedge \mathrm{u}(\mathrm{x})$ for every $x \mathrm{G} 0 \mathrm{~J} 3\left(\mathrm{x}_{0}, \mathrm{r}\right)$. Therefore $d\left(u, B\left(x_{o}, r\right), v\left(x_{o}\right)\right)$ is well defined and $d\left(u, B\left(x_{o}, r\right), v(x o)\right)=\operatorname{sign}\left(\operatorname{det}\left(\operatorname{Vv}\left(x_{0}\right)\right)\right)$. The application $H$ defined by

$$
\boldsymbol{H}(\boldsymbol{x}, \boldsymbol{t})=\boldsymbol{t} \boldsymbol{v}(\boldsymbol{x})+(l-t) u(x) \quad \mathrm{xGB}\left(\mathrm{x}_{0}, \mathrm{r}\right), \quad<\mathrm{G}[\mathrm{O}, 1]
$$

is a homotopy between t ; and u . Moreover, for every $x \mathrm{G} d B\left(x_{o}, r\right)$ we have

Therefore $v\left(x_{0}\right) £ H\left(d B\left(x_{o}, r\right), t\right)$ for every $t$ G [0,1] and $<*\left(\#(., \mathrm{t}), £\left(\mathrm{x}_{\mathrm{o}}, \mathrm{r}\right), \mathrm{v}\left(\mathrm{x}_{\mathrm{o}}\right)\right){ }^{\text {is well }}$ defined. By (8) we obtain that $\mathrm{d}(\mathrm{i} /(-, \mathrm{t}), \mathrm{i}$ ?(xo,r), t ;(xo)) is independent of i , hence, taking $t=0, \mathrm{t}=1$ we obtain

$$
d\left(v, B\left(x_{0}, r\right), v\left(x_{0}\right)\right)=d\left(u, B\left(x_{0}, r\right), v\left(x_{0}\right)\right)=\operatorname{sign}\left(\operatorname{det}\left(\nabla v\left(x_{0}\right)\right)\right)
$$

and (17) is proved.
Remark 3.6 The relation between complete differentiability and topological degree was first observed by Reshetnyak ([Re]).

Lemma 3.7 Let $\boldsymbol{C l} \boldsymbol{C H}^{\boldsymbol{N}}$ be an open set, let $\boldsymbol{v} \mathbf{G} \boldsymbol{W}^{\boldsymbol{h N}}(\boldsymbol{i l})^{\boldsymbol{N}}$ be such that $\operatorname{detVv}\{x)>0$ a.e. $\mathbf{x}$ G ft. Then for every $X o G$ ft such that $\boldsymbol{v}$ is completely differentiable at $x_{0}$ and $\operatorname{det} V \boldsymbol{v}(x o)>0$ there is $\boldsymbol{R Q}=\mathrm{JRO}(\mathrm{XO})$ such that for every $\mathbf{0}<\boldsymbol{R}<$ Ro the following holds:

$$
\begin{align*}
& \left.N\left(v, B\left(x_{o}, R\right), y\right)\right)=1 \text { for almost every y } G C_{R},  \tag{18}\\
& d\left(v, B\left(x_{o}, R\right), y\right)=1 \text { for every y } E C_{R},  \tag{19}\\
& d(v, B, y)=1 \text { for every } y G v\{B) \backslash v(d B), \tag{20}
\end{align*}
$$

for every non empty, open set $B \mathbf{C} V_{\sim}^{X}(C R) f 1 B(x o, R)$ such that $\backslash d B \backslash=0$,
where $C R$ is the connected component of $R^{N} \backslash v\left(d B\left(x_{0}, R\right)\right)$ containing $y_{0}:=v\left(x_{0}\right)$ and $N(v, E, y)$ is the cardinality of the set $\{x G E \backslash v\{x)=y\}$.

Proof. By lemmas 2.2 and 2.7, t ; is continuous and monotonic on ft and is completely differentiable at almost every point $\mathrm{x} G \mathrm{ft}$. Fix $\mathrm{x}_{0} \mathrm{Gft}$ such that t ; is completely differentiable at xo and $\operatorname{detVv}(x o)>0$.

Proof of (19). By lemma 3.5 there is $R o>0$ such that $B\left\{x_{0}, R Q\right) \mathrm{CC} \mathrm{ft}$ and $d\left(v, B\left(z_{o}<R\right), y_{0}\right)=$ $\overline{1 \text { for every } \overline{0}<R<R Q \text { and (19) follows from (6). }}$

Proof of (18). Using the fact that $\operatorname{det} V v(x)>0$ a.e. $\mathrm{x} \mathrm{G} \mathrm{ft}, \mathrm{(11)}, \mathrm{(12)} \mathrm{and} \mathrm{(19)} \mathrm{yield} \mathrm{(18)}$.

Proof of (20). As $v$ satisfies the N-property (see Remark 2.5) $\left|v\left(\partial B\left(x_{0}, R_{0}\right)\right)\right|=0$ and $|v(\partial B)|=0$. Since $B$ is a non empty open set, by (11) we have that $|v(B)| \neq 0$ and so $|v(B) \backslash v(\partial B)| \neq 0$. Let $y \in v(B) \backslash v(\partial B)$ and $C$ be the connected component of $\mathbf{R}^{N} \backslash v(\partial B)$ containing $y$. As $\left|v\left(\partial B\left(x_{0}, R_{0}\right)\right)\right|=0$ and since $d(v, B, \cdot)$ is a constant on $C$, we may assume without loss of generality that $y \notin v\left(\partial B\left(x_{0}, R_{0}\right)\right)$. Let $\rho_{\epsilon} \in C^{\infty}\left(\mathbf{R}^{N}\right)$ be such that

$$
\begin{gather*}
0 \leq \rho_{\epsilon}(y), \forall y \in \mathbf{R}^{N}, \forall \epsilon>0 \\
\frac{1}{2} \leq \rho_{\epsilon}(y), \forall y \in B\left(0, \frac{\epsilon}{2}\right)  \tag{21}\\
\operatorname{supp} \rho_{\epsilon} \subset B(0, \epsilon), \quad \forall \epsilon>0 \\
\int_{\mathbf{R}^{N}} \rho_{\epsilon}(y) d y=1 \quad \forall \epsilon>0 .
\end{gather*}
$$

Since $y \in v(B)$ there is $x \in B$ such that $y=v(x)$. By (6) we have

$$
\lim _{\epsilon \rightarrow 0} \int_{B} \rho_{\epsilon}(v(z)-y) \operatorname{det} \nabla v(z) d z=d(v, B, y)
$$

and using the continuity of $v$ at $x$, we deduce that for every $\epsilon>0$ there is $\delta>0$ such that $|v(z)-y| \leq \frac{\epsilon}{2}$ for every $z \in B(x, \delta)$. Recalling that $\operatorname{det} \nabla v(z)>0$ a.e. $z \in B(x, \delta)$, by (21) and (22) we obtain

$$
\begin{equation*}
d(v, B, y)>0 \tag{23}
\end{equation*}
$$

Finally as the degree $d(v, \cdot, y)$ is a non decreasing function of the set, using (19) and the fact that $B \subset v^{-1}\left(C_{R}\right) \cap B\left(x_{0}, R\right)$ we obtain

$$
\begin{equation*}
d(v, B, y) \leq d\left(v, B\left(x_{0}, R\right), y\right)=1 \tag{24}
\end{equation*}
$$

which together with (23) and the fact that the degree is an integer number, yields (20).
Lemma 3.8 Let $\Omega, v, R_{0}$ and $x_{0}$ be as in Lemma 3.7, (18), (19). Let $C_{R_{0}}$ be the connected component of $\mathbf{R}^{N} \backslash v\left(\partial B\left(x_{0}, R_{0}\right)\right)$ containing $y_{0}:=v\left(x_{0}\right)$. Then for every $r>0$ such that $B\left(y_{0}, r\right) \subset \subset C_{R_{0}}$, if $O:=v^{-1}\left(B\left(y_{0}, r\right)\right) \cap B\left(x_{0}, R_{0}\right) \subset \subset B\left(x_{0}, R_{0}\right)$ then

$$
\begin{equation*}
v(O)=B\left(y_{0}, r\right), \quad v(\partial O) \subset \partial v(O)=\partial B\left(y_{0}, r\right) \tag{25}
\end{equation*}
$$

Proof. It is clear that $v(O) \subset B\left(y_{0}, r\right)$. Conversely, if $y \in B\left(y_{0}, r\right)$, by (19) $d\left(v, B\left(x_{0}, R_{0}\right), y\right)=$ 1 and so by (5) there exists $x \in B\left(x_{0}, R_{0}\right)$ such that $y=v(x)$, implying $y \in v(O)$. Let $x \in \partial O$ and let $\left\{a_{n}\right\} \subset O,\left\{b_{n}\right\} \subset B\left(x_{0}, R_{0}\right) \backslash O$ be such that

$$
\lim _{n \rightarrow+\infty} a_{n}=\lim _{n \rightarrow+\infty} b_{n}=x .
$$

We have $v\left(a_{n}\right) \in v(O)=v\left(v^{-1}\left(B\left(y_{0}, r\right)\right)\right)=B\left(y_{0}, r\right)$ and $v\left(b_{n}\right) \notin v(O)=B\left(y_{0}, r\right)$. Using the continuity of $v$ at $x$, we have

$$
v(x)=\lim _{n \rightarrow+\infty} v\left(a_{n}\right)=\lim _{n \rightarrow+\infty} v\left(b_{n}\right)
$$

and this gives $x \in \partial v(O)$.

Lemma 3.9 Let $v \in W^{1, N}(\Omega)^{N}, \operatorname{det} \nabla v(x)>0$ a.e. $x \in \Omega$ and let $x_{0} \in D$ be such that $v(x) \neq v\left(x_{0}\right)$ for every $x \in \bar{B}\left(x_{0}, R_{0}\right) \backslash\left\{x_{0}\right\}$. Let $0<R<R_{0}$ and let $C$ be an open set containing $y_{0}=v\left(x_{0}\right)$. Then there is $r>0$ such that $v^{-1}\left(B\left(y_{0}, r\right)\right) \cap B\left(x_{0}, R\right) \subset \subset B\left(x_{0}, R\right)$.

Proof. Define

$$
d(\delta)=\sup \left\{\left|x-x_{0}\right|: x \in \bar{B}\left(x_{0}, R\right),\left|v(x)-v\left(x_{0}\right)\right| \leq \delta\right\} .
$$

Since $v(x) \neq v\left(x_{0}\right)$ for every $x \in \bar{B}\left(x_{0}, R\right) \backslash\left\{x_{0}\right\}$ and $v$ is uniformly continuous on $\bar{B}\left(x_{0}, R\right)$ we have

$$
\lim _{\delta \rightarrow 0} d(\delta)=0
$$

Take now $r>0$ such that $d(r)<\frac{R}{2}$. We have

$$
v^{-1}\left(B\left(y_{0}, r\right)\right) \cap B\left(x_{0}, R\right) \subset B\left(x_{0}, \frac{R}{2}\right) \subset \subset B\left(x_{0}, R\right)
$$

Proof of Theorem 3.1 Let $\Omega^{\prime}$ be the set of points $x_{0} \in \Omega$ such that $v$ is completly differentiable at $x_{0}$ and $\operatorname{det} \nabla v\left(x_{0}\right)>0$. By Lemmas 2.7 and Lemma 2.2 we obtain $\left|\Omega \backslash \Omega^{\prime}\right|=0$. In the sequel, we fix $x_{0} \in \Omega^{\prime}$, we set $y_{0}=v\left(x_{0}\right)$ and show that $v$ is locally invertible at $x_{0}$. By Lemma 3.5 and Lemma 3.7 there is $R_{0}>0$ such that $B\left(x_{0}, R_{0}\right) \subset \subset \Omega$,

$$
\begin{equation*}
N\left(v, B\left(x_{0}, R_{0}\right), y\right)=1 \text { a.e. } y \in C_{R_{0}} \tag{26}
\end{equation*}
$$

where $C_{R_{0}}$ is the connected component of $\mathbf{R}^{N} \backslash v\left(\partial B\left(x_{0}, R_{0}\right)\right)$ containing $y_{0}$, with $N\left(v, B\left(x_{0}, R_{0}\right), y_{0}\right)=1$. By Lemma 3.9 we deduce that there is $r>0$ such that

$$
\begin{equation*}
v^{-1}\left(B\left(y_{0}, r\right)\right) \cap B\left(x_{0}, R_{0}\right) \subset \subset B\left(x_{0}, R_{0}\right) \tag{27}
\end{equation*}
$$

and

$$
\begin{equation*}
B\left(y_{0}, r\right) \subset \subset C_{R_{0}} \tag{28}
\end{equation*}
$$

Setting $D=v^{-1}\left(B\left(y_{0}, r\right)\right) \cap B\left(x_{0}, R_{0}\right)$, by (27) and (28) we have $D \subset v^{-1}\left(C_{R_{0}}\right) \cap B\left(x_{0}, R_{0}\right)$ and by Lemma 3.8

$$
\begin{equation*}
v(D)=B\left(y_{0}, r\right), v(\partial D) \subset \partial v(D)=\partial B\left(y_{0}, r\right) \tag{29}
\end{equation*}
$$

By the $N^{-1}$-property of $v$ (see Remark 2.5 and (29) ), we have $|\partial D|=0$ which together with (20) yields

$$
\begin{equation*}
d(v, D, y)=1 \quad \forall y \in v(D) \backslash v(\partial D) \tag{30}
\end{equation*}
$$

Using the definition of $D$, the fact that $D \subset B\left(x_{0}, R_{0}\right)$, (26) and (28), we obtain

$$
\begin{equation*}
N(v, D, y)=1 \text { a.e. } y \in v(D) \tag{31}
\end{equation*}
$$

Let $N:=\left\{y \in v(D) \equiv B\left(y_{0}, r\right) \mid d(v, D, y) \neq 1\right\}$ and define the candidate for local inverse function, $w$, by

$$
\begin{align*}
& w(y)=x \text { if } y \in v(D) \backslash N, \text { and } v(x)=y, x \in D  \tag{32}\\
& w(y)=x, \text { if } y \in N, v(x)=y \tag{33}
\end{align*}
$$

$x \in D$ being chosen by the axiom of choice.
Claiml: $w \in L^{\infty}\left(B\left(y_{0}, r\right)\right)^{N}$.
We have $w(y) \in D \subset \Omega$ for every $y \in v(D)$ and so $w$ is uniformly bounded in $v(D)$. To prove that $w$ is Lebesgue measurable, fix $\alpha \in R$ and show that the set

$$
A:=\left\{y \in v(D): w_{i}(y) \geq \alpha\right\}
$$

is measurable. We obtain $A=A_{1} \cup A_{2}$ where

$$
\begin{aligned}
& A_{1}:=\left\{y \in v(D) \backslash N: w_{i}(y) \geq \alpha\right\}, \\
& A_{2}:=\left\{y \in N: w_{i}(y) \geq \alpha\right\} .
\end{aligned}
$$

Since $\left|A_{2}\right|=0$ we deduce that $A_{2}$ is measurable. Using the fact that the restriction of $v$ to $v^{-1}(v(D) \backslash N)$ is one-to-one, one can see that

$$
\begin{aligned}
A_{1} & =\left\{v(x): x \in v^{-1}(v(D) \backslash N), x_{i} \geq \alpha\right\} \\
& =(v(D) \backslash N) \cap\left(\cup_{n=0}^{+\infty} v\left\{x \in \bar{B}\left(x_{0}, R_{0}\right), \alpha+n \leq x_{i} \leq \alpha+n+1\right\}\right) .
\end{aligned}
$$

Using the fact that for every $n \in \mathbf{N},\left\{x \in \bar{B}\left(x_{0}, R_{0}\right), \quad \alpha+n \leq x_{i} \leq \alpha+n+1\right\}$ is a compact set, $v$ is a continuous function and $v(D) \backslash N$ is measurable we obtain that $A_{1}$ is measurable and we conclude that $w \in L^{\infty}\left(B\left(y_{0}, r\right)\right)^{N}$.

## Claim 2:

$$
\begin{align*}
& v \circ w(y)=y \text { for every } y \in v(D) \equiv B\left(y_{0}, r\right),  \tag{34}\\
& w \circ v(x)=x \text { for every } x \in D \backslash v^{-1}(N) . \tag{35}
\end{align*}
$$

This follows immediatly from (32) and (33). One notice that, due to (30) and Remark $2.5,\left|v^{-1}(N)\right|=0$.

Claim 3: $f \circ w$ is measurable for every $f: D \rightarrow R$ measurable.
Knowing that every Lebesgue measurable set is a union of a Borel measurable set and a set of measure zero, to show that $f \circ w$ is measurable, by claim 1 it suffices to show that $\boldsymbol{w}^{-1}(R)$ is measurable for every $R \subset D$ so that $|R|=0$. Let $R$ be a subset of $D$ such that $|R|=0$. We have by (34)

$$
w^{-1}(R) \subset v(R),
$$

and since $|R|=0$, by the N-property of $v$, we obtain that $\left|w^{-1}(R)\right|=0$. Thus $w^{-1}(R)$ is measurable.

Let $g: v(D)=B\left(y_{0}, r\right) \rightarrow \mathbf{R}$ be defined by

$$
g(y)=\frac{|\operatorname{adj} \nabla v(w(y))|}{\operatorname{det} \nabla v(w(y))}
$$

Claim 4: $g \in L^{1}(v(D))$.
By claim $3 g$ is measurable. By Lemma 2.4 (11) where we set $f=\chi_{v(D)}$ the indicator of the set $v(D)$, by claim 2, and (31) we obtain

$$
\int_{v(D)}|g(y)| d y=\int_{D}|g \circ v(x)| \operatorname{det} \nabla v(x) d x=\int_{D}|a d j \nabla v(x)| d x
$$

Therefore $g \in L^{1}(v(D))$.
Claim 5: $w \in W^{1,1}(v(D))^{N}$ and $\nabla w(y)=\left(\frac{\operatorname{adj} \nabla v(w(y))}{\operatorname{det} \nabla v(w(y))}\right)^{T}$.
To prove claim 5, we fix $\phi \in C_{0}^{\infty}(v(D))$ and set $K=$ supp $\phi$. We show that

$$
\int_{v(D)} w_{\alpha}(y) \frac{\partial \phi}{\partial y_{j}}(y) d y=-\int_{v(D)} \frac{(\operatorname{adj} \nabla v(w(y)))_{\alpha}^{j}}{\operatorname{det} \nabla v(w(y))} \phi(y) d y
$$

Set $\delta=\operatorname{dist}(K, \partial v(D))>0$. Using the uniform continuity of $v$ on $\bar{D} \subset B\left(x_{0}, R_{0}\right)$ we choose $\epsilon>0$ such that

$$
\begin{equation*}
\left|v(x)-v\left(x^{\prime}\right)\right| \leq \frac{\delta}{4} \text { for every } x, x^{\prime} \in \bar{D},\left|x-x^{\prime}\right| \leq \epsilon \tag{36}
\end{equation*}
$$

Let $\left\{v_{n}\right\} \subset C^{\infty}(\bar{D})^{N}$ be such that

$$
\begin{equation*}
v_{n} \rightarrow v \text { in } C^{0}(\bar{D})^{N} \tag{37}
\end{equation*}
$$

and

$$
v_{n} \rightharpoonup v \text { in } W^{1, N}(D)^{N}
$$

By (37) we can assume without loss of generality that

$$
\begin{equation*}
\left|v-v_{n}\right|_{\infty} \leq \frac{\delta}{4} \text { for every } n \in N \tag{38}
\end{equation*}
$$

By the fact that $v(\partial D) \subset \partial v(D)$ (see (29)), by (36) and (38) we have that

$$
\operatorname{dist}(x, \partial D)<\epsilon \text { implies } \phi\left(v_{n}(x)\right)=0
$$

and so

$$
\phi \circ v_{n} \in C_{0}^{\infty}(D) .
$$

In the sequel we denote by $A_{\alpha}^{j}$ the component of the $j$-row and the $\alpha$-column of the $N \times N$ matrix $A$. By (11), (31) and (35) and the fact that for every $n \in N, \quad \sum_{\alpha=1}^{N} \frac{\partial\left(a d j \nabla v_{n}\right)_{a}^{a}}{\partial x_{\alpha}}=0$ for every $j=1, \cdots, N$ we have

$$
\begin{aligned}
\int_{v(D)} w_{\alpha}(y) \frac{\partial \phi}{\partial y_{j}}(y) d y & =\int_{D} w_{\alpha}(v(x)) \frac{\partial \phi}{\partial y_{j}}(v(x)) \operatorname{det} \nabla v(x) d x \\
& =\lim _{n \rightarrow+\infty} \int_{D} x_{\alpha} \frac{\partial \phi}{\partial y_{j}}\left(v_{n}(x)\right) \operatorname{det} \nabla v_{n}(x) d x \\
& =\lim _{n \rightarrow+\infty} \int_{D} x_{\alpha} \sum_{k=1}^{N}\left(\operatorname{adj} \nabla v_{n}(x)\right)_{k}^{j} \frac{\partial}{\partial x_{k}} \phi\left(v_{n}(x)\right) d x \\
& =-\lim _{n \rightarrow+\infty} \int_{D}\left(a d j \nabla v_{n}(x)\right)_{\alpha}^{j} \phi\left(v_{n}(x)\right) d x \\
& =-\int_{D}(a d j \nabla v(x))_{\alpha}^{j} \phi(v(x)) d x \\
& =-\int_{D} \frac{(\operatorname{adj} \nabla v(w \circ v(x)))_{\alpha}^{j}}{\operatorname{det} \nabla v(w \circ v(x))^{j}} \phi(\circ v(x)) \operatorname{det} \nabla v(x) d x \\
& =-\int_{v(D)} \frac{(\operatorname{adj} \nabla v(w(y)))_{\alpha}^{j}}{\operatorname{det} \nabla v(w(y))} \phi(y) d y .
\end{aligned}
$$

This equality together with claim 4 yields claim 5.
Claim 6: $\nabla w \in W^{1, s}(v(D))$ if and only if $|g \circ v|^{s} \operatorname{det} \nabla v \in L^{1}(v(D))$ for $1 \leq s<+\infty$.
Recall that $g(y)=\frac{|a d j \nabla v(w(y))|}{\operatorname{det} \nabla v(w(y))}$ and that $w \in L^{\infty}(v(D))^{N}$. Thus $\nabla w \in W^{1, s}(v(D))$ if and only if $\nabla w \in L^{s}(v(D))$. The result now follows from claim 5 and (11).

Remarks 3.10 It is possible to show that if $v \in W^{1, q}(\Omega)^{N}, q>N-1, \quad \operatorname{adj} \nabla v \in$ $L^{\frac{N}{N-1}}(\Omega), \operatorname{det} \nabla v(x)>0$ a.e. in $\Omega$ and if $v$ is continuous, then there is local invertibility a.e. in $\Omega$, i.e. for a.e. $x_{0} \in \Omega$ there exists $r>0$ such that $\left.v\right|_{B\left(x_{0}, r\right)}$ is almost everywhere injective with the inverse $w \in B V_{l o c}\left(\left.v\right|_{v\left(B\left(x_{0}, r\right)\right)}, \mathbf{R}^{N}\right)$ and there exists a set $E \subset v\left(B\left(x_{0}, r\right)\right)$ such that

$$
\begin{aligned}
& E \text { is an open set of } v\left(B\left(x_{0}, r\right)\right), \\
& \mid v\left(B\left(x_{0}, r\right) \backslash E \mid=0,\right. \\
& w \in W^{1,1}\left(E, R^{N}\right), \\
& v \circ w(y)=y \text { a.e. } y \in v\left(B\left(x_{0}, r\right)\right), \\
& w \circ v(x)=x \text { a.e. } x \in B\left(x_{0}, r\right) .
\end{aligned}
$$

To see this, we recall that by Lemma 2.7 iii) $v$ is weakly differentiable a.e. in $\Omega$ and by adapting the proof of Lemma 3.5 accordingly, it is possible to show that

$$
d\left(v, B\left(x_{0}, r\right), v\left(x_{0}\right)\right)=1
$$

for some $r>0$. Let $C_{0}$ be the connected component of $\mathbf{R}^{\boldsymbol{N}} \backslash \boldsymbol{v}\left(\partial B\left(x_{0}, r\right)\right)$ which contains $v\left(x_{0}\right)$. Then

$$
\begin{equation*}
d\left(v, B\left(x_{0}, r\right), y\right)=1 \tag{39}
\end{equation*}
$$

for every $y \in C_{0}$ and so, if we choose $0<r^{\prime}<r$ such that

$$
B\left(x_{0}, r^{\prime}\right) \subset B\left(x_{0}, r\right) \cap v^{-1}\left(C_{0}\right)
$$

then by (39) and since $\operatorname{det} \nabla v>0$ a.e. we have

$$
d\left(v, B\left(x_{0}, r^{\prime}\right), y\right) \leq 1
$$

for every $y \in \mathbf{R}^{N} \backslash v\left(\partial B\left(x_{0}, r^{\prime}\right)\right)$. It suffices now to use the results in [TQ], (1.3)-(1.5), (2.26) and Theorem 3.7 (i). Note, however, that in [TQ], it is assume that $a d j \nabla v \in L^{r}$, $r \geq \frac{q}{q-1}$ and if $N-1<q<N$, then $\frac{q}{q-1}>\frac{N}{N-1}$.

As it turns out, [TQ]'s results still hold for $r=\frac{N}{N-1}$ as remarked by [MTY] (see Theorem 5.3 in [MTY]).

## Proof of Corollary 3.2.

Proof of a) We have

$$
v \in W^{1, N}\left(\Omega_{1}\right)^{N}, \quad \operatorname{det} \nabla v(x)>0 \text { a.e. } x \in \Omega_{1}
$$

and

$$
v \in W^{1, N}\left(\Omega_{2}\right)^{N}, \quad \operatorname{det} \nabla v(x)<0 \text { a.e. } x \in \Omega_{2} .
$$

It suffices to apply Theorem 3.1 to $v$ and to $R_{0} v$ in $\Omega_{2}$, where $R_{0}$ is a constant rotation with $\operatorname{det} R_{0}=-1$.
Proof of b ) We now assume that $v \in W^{1, q}(\Omega)^{N}, q>N \operatorname{det} \nabla v(x) \neq 0$ a.e. $x \in \Omega$ and for almost every $x_{0} \in \Omega, v$ is locally almost injective in a neighborhood of $x_{0}$ in the sense that there is an open set $D \equiv D\left(x_{0}\right) \subset \subset \Omega$ and there is a function $w: v(D) \rightarrow D$ such that

$$
\begin{equation*}
w \circ v(x)=x \text { a.e. } x \in D . \tag{40}
\end{equation*}
$$

By Vitali's covering theorem there is a countable family of non-empty, open, mutually disjoint balls $\left\{B_{i}, i \in N\right\}$ and there is a sequence of functions $w_{i}: v\left(\bar{B}_{i}\right) \rightarrow \Omega$ such that $\bar{B}_{i} \subset \Omega$ and

$$
\begin{align*}
& \left|\Omega \backslash \cup_{i=1}^{+\infty} B_{i}\right|=0, \\
& w \circ v(x)=x \text { a.e. } x \in B_{i} . \tag{41}
\end{align*}
$$

The task ahead will be to partition $B_{i}$ into three subsets $B_{i}^{1}, B_{i}^{2}$ and $N_{i}$ such that $B_{i}^{1}, B_{i}^{2}$ are two open sets, $N_{i}$ is a set of measure zero,

$$
\begin{array}{ll}
\operatorname{det} \nabla v(x)>0 & \text { a.e. } \\
\operatorname{det} \nabla v(x)<0 & \text { a.e. } \\
\operatorname{de}, \\
B_{i}^{2} .
\end{array}
$$

Using the fact that $v \in W^{1, q}\left(B_{i}\right)^{N}, q>N$, by Lemma 2.7 and (41) we deduce that there is a set $A_{i} \subset \bar{B}_{i}$ of measure zero such that $v$ is completely differentiable at every $x \in B_{i} \backslash A_{i}$,

$$
\begin{align*}
& w \circ v(x)=x \text { for every } x \in \bar{B}_{i} \backslash A_{i}  \tag{42}\\
& \operatorname{det} \nabla v(x) \neq 0 \text { for every } x \in \bar{B}_{i} \backslash A_{i} .
\end{align*}
$$

Let $\left\{C^{j}\right\}$ be the countable collection of the (open) connected components of $\mathbf{R}^{\boldsymbol{N}} \backslash v\left(\partial B_{i}\right)$. By Remark 2.5 a ), c) we have

$$
\begin{equation*}
\left|v^{-1}\left(v\left(\partial B_{i} \cup A_{i}\right)\right)\right|=0 \tag{43}
\end{equation*}
$$

We claim that
Claiml $d\left(v, B_{i}, v(x)\right)=\operatorname{sign} \operatorname{det} \nabla v(x)$ for every $x \in B_{i} \backslash v^{-1}\left(v\left(\partial B_{i} \cup A_{i}\right)\right)$.
Fix $x \in B_{i} \backslash v^{-1}\left(v\left(\partial B_{i} \cup A_{i}\right)\right)$.
stepl We prove that $d\left(v, B\left(x, r_{0}\right), v(x)\right)=\operatorname{sign} \operatorname{det} \nabla v(x)$ for $r_{0}$ small enough. Using the fact that $v$ is completely differentiable and $\operatorname{det} \nabla v(x) \neq 0$, by Lemma 3.5 we deduce that there is $r_{0}>0$ such that for every $0<r \leq r_{0}$ we have

$$
d(v, B(x, r), v(x))=\operatorname{sign} \operatorname{det} \nabla v(x)
$$

step2 We show that $d\left(v, B_{i}, v(x)\right)=\operatorname{sign} \operatorname{det} \nabla v(x)$. Indeed, setting $K=\bar{B}_{i} \backslash B\left(x, r_{0}\right), H_{i}$ is a compact set included in $\bar{B}_{i}$ and by (42) $v(x) \notin v(K)$ because $v(x) \notin v\left(A_{i}\right)$. By the excision property of the degree (see Proposition 2.3) we obtain

$$
d\left(v, B_{i}, v(x)\right)=d\left(v, B\left(x, r_{0}\right), v(x)\right)=\operatorname{sign} \operatorname{det} \nabla v(x)
$$

Claim2 $\operatorname{sign} \operatorname{det} \nabla v(x)=\operatorname{sign} \operatorname{det} \nabla v\left(x^{\prime}\right)$ for every $x, x^{\prime} \in v^{-1}\left(C^{j}\right) \backslash v^{-1}\left(v\left(\partial B_{i} \cup A_{i}\right)\right)$.
Assume that $x, x^{\prime} \in v^{-1}\left(C^{j}\right) \backslash v^{-1}\left(v\left(\partial B_{i} \cup A_{i}\right)\right)$. Using claim 1 and the fact that the degree $d\left(v, B_{i}, \cdot\right)$ is constant on each $C^{j}$, we obtain that $\operatorname{sign} \operatorname{det} \nabla v(x)=\operatorname{sign} \operatorname{det} \nabla v\left(x^{\prime}\right)$.

We now conclude the proof of b$)$. Let $I=\left\{j \in \mathrm{~N} \mid \operatorname{det} \nabla v(x)>0\right.$ a.e. $\left.x \in v^{-1}\left(C^{j}\right)\right\}$ and $J=\left\{j \in N, \operatorname{det} \nabla v(x)<0\right.$ a.e. $\left.x \in v^{-1}\left(C^{j}\right)\right\}$. Set

$$
\begin{aligned}
& B_{i}^{1}=\cup_{j \in I} v^{-1}\left(C^{j}\right) \cap B_{i} \\
& B_{i}^{2}=\cup_{j \in J} v^{-1}\left(C^{j}\right) \cap B_{i}
\end{aligned}
$$

and

$$
N_{i}=B_{i} \backslash\left(B_{i}^{1} \cup B_{i}^{2}\right)
$$

Then $B_{i}=B_{i}^{1} \cup B_{i}^{2} \cup N_{i}$ and setting $\Omega_{1}=\cup_{i} B_{i}^{1}, \Omega_{2}=U_{i} B_{i}^{2}$ and $N=\Omega \backslash\left(\Omega_{1} \cup \Omega_{2}\right)$, then $|N|=0$ and $\Omega_{1}, \Omega_{2}$ have the required properties.

Proof of Corollary 3.3: To obtain that $w \in W^{1, \frac{q}{N-1}}(v(D), D)$ we take $s=\frac{q}{N-1}$ in Theorem 3.1. If $q \geq N(N-1)$ then $w \in W^{1, N}$,

$$
\operatorname{det} \nabla w(y)=\frac{1}{\operatorname{det} \nabla v(w(y))}>0 \text { a.e. } y \in v(D)
$$

and so, by Lemma 2.2 we deduce that $w$ is continuous. Hence $v$ and $w$ are homeomorphisms and $v$ is an open mappings in $\Omega^{\prime}$ for some $\Omega^{\prime} \subset \Omega$ open, where $\left|\Omega \backslash \Omega^{\prime}\right|=0$.

## 4 Semicontinuity involving variation of the domain.

The variational treatment of crystals with defects leads to the study of functionals of the type

$$
E(u, v)=\int_{\Omega} W\left(\nabla u(x)(\nabla v(x))^{-1}\right) d x
$$

where $\Omega \subset \mathbf{R}^{N}$ is a reference domain, $W$ is the strain energy density, $u$ is the elastic deformation and $v$ represents the slip (rearrangement) or plastic deformation with $\operatorname{det}(\nabla v(x))=1$ a.e. $x \in \Omega$. The underlying kinematical mode for slightly defective crystals was introduced by Davini [Dav] and later developed by Davini and Parry [DP]. As it turns out, matrices of the form

$$
\nabla u(x)(\nabla v(x))^{-1}
$$

represent lattice matrices of defect-preserving deformations (neutral deformations) and taking the viewpoint that equlibria correspond to a variational principle, Fonseca \& Parry [FP] studied the structure of some kind of generalized minimizers (Young measure solutions) for the energy $E(\cdot, \cdot)$ ( related variational problems were also investigated in [DP]).

Using the Div-Curl Lemma it follows that if $u_{n} \rightarrow u$ in $W^{1, \infty} w *$ and $v_{n}-v$ in $W^{1, \infty} w *$ then

$$
\nabla u_{n}\left(\nabla v_{n}\right)^{-1}-\nabla u(\nabla v)^{-1} \text { in } L^{\infty} w *
$$

Lower semicontinuity and relaxation properties of $E(\cdot, \cdot)$ were adressed only under additional material symmetry assumptions on $W$. Existence and regularity properties for minimizers of $E(\cdot, \cdot)$ were obtained in [DF]. Following this work, we stress the fact that the direct methods of the calculus of variations fail to apply to this problem, as sequential weak lower semicontinuity of $E(\cdot, \cdot)$ is not sufficient to guarantee the existence of minimizers. Indeed with $W(F)=\|F\|^{\Gamma}$, it is shown in [DF] that there are no minimizers in $\left\{(u, v) \in W^{1, \infty} \times W^{1, \infty} \mid u(x)=x\right.$ on $\partial \Omega, \operatorname{det}(\nabla v(x))=1$ a.e. $\}$ if $0<r<N=2$, while for $r>N$ existence is obtained for smooth ( $u, v$ ) (Theorem 2.3 [DF]).

It is clear that if $\left\{\left(u_{n}, v_{n}\right)\right\}$ is a minimizing sequence and if, $\left\|\nabla u_{n}\left(\nabla v_{n}\right)^{-1}\right\|^{r}$ is bounded in $L^{1}$ then

$$
\nabla u_{n}\left(\nabla v_{n}\right)^{-1}-L \text { in } L^{r},\left.u_{n}\right|_{\partial \Omega}=u_{0}, \operatorname{det}\left(\nabla v_{n}\right)=1 \text { a.e. }
$$

and so if some type of lower semicontinuity prevails, then

$$
\begin{equation*}
\int_{\Omega} W(L) d x \leq \liminf \int_{\Omega} W\left(\nabla u_{n}\left(\nabla v_{n}\right)^{-1}\right) d x \tag{44}
\end{equation*}
$$

It would remain to show that $L$ would still have the same structure, precisely

$$
L=\nabla u(\nabla v)^{-1}
$$

where $\left.u\right|_{\partial \Omega}=u_{0}, \operatorname{det}(\nabla v)=1$ a.e. Note that (44) is always satisfied if $W$ is a convex function. On the other hand, formally, as $\operatorname{det}(\nabla v)=1$ a.e. and setting $w=u\left(v^{-1}\right)$ then the energy becomes

$$
\int_{v(\Omega)} W(\nabla w(y)) d y
$$

which is now an energy functional involving variations of the domain. Hence, under this new formulation, quasiconvexity seems to be more appropriate than convexity (see [AF], [Ba] and [Da] ).
Suppose that $W$ is a quasiconvex function, i.e.

$$
W(F) \leq \frac{1}{|Q|} \int_{Q} W(F+\nabla \phi(x)) d x
$$

where $Q=(0,1)^{N}, \phi \in W_{0}^{1, \infty}(Q)^{N}$ and let $\nabla u_{n}\left(\nabla v_{n}\right)^{-1}-L$ in $L^{r}$. Can we say that

$$
\int_{\Omega} W(L) \leq \liminf \int_{\Omega} W\left(\nabla u_{n}\left(\nabla v_{n}\right)^{-1}\right) ?
$$

As an example, consider

$$
W(F)=\|F\|^{2}+|\operatorname{det}(F)|
$$

Although we are unable to answer this question, we prove the following result which is the main theorem of this section.

Theorem 4.1 Let $W: M^{N \times N} \rightarrow \mathbf{R}$ be a quasiconvex function such that

$$
-C_{1}\left(1+\|A\|^{*}\right) \leq W(A) \leq C_{2}\left(1+\|A\|^{r}\right)
$$

for some constants $C_{1}, C_{2}>0, r>s \geq 1, p \geq 1, q \geq N, \frac{1}{p}+\frac{N-1}{q}=\frac{1}{r}(W \geq 0$ if $r=s=1$ ). If $u_{n}-u$ in $W^{1, p}(\Omega)^{N}, v_{n} \rightarrow v$ in $W^{1, q}(\Omega)^{N}$, and $\operatorname{det}\left(\nabla v_{n}\right)=1$ a.e. in $\Omega$ then

$$
\int_{\Omega} W\left(\nabla u(\nabla v)^{-1}\right) d x \leq \liminf \int_{\Omega} W\left(\nabla u_{n}\left(\nabla v_{n}\right)^{-1}\right) d x
$$

Before proving Theorem 4.1 we make some remarks.

Remarks 4.2 1. It is dear that if it $€ W^{1 * *}, v € W^{l}<$ and $\operatorname{det} V v=1$ a.e. then $\mathbf{V u}(\mathrm{Vv})$ - $^{1} € \boldsymbol{V}$.
2. If $r>1$ then $5<r$ is a necessary condition as the counterexample by Murat and Tartar shows (see $[B M]$ ). Here $\mathbf{r}=\mathbf{s}=2=\operatorname{Ar}, \mathrm{ft}=(0,1)^{2}, W(F)=\operatorname{det}_{\{ } F(F), u_{n}-u$ in $H^{l}(S l), v_{n}(x)=x$ and

$$
\int_{o} \operatorname{de}^{* V \mathrm{Vu}} \mathbf{j} \not \liminf _{J o}^{/} \operatorname{detV} u_{n} .
$$

3.The growth condition cannot be dropped even if $W$ is polyconvex and nonegative. Precisely if the relation between $p, g, r$ and $s$ does not occur, the conclusion of Theorem 4.1 may be false. Indeed, using the example by Malý ([Ma]) with $q=+00, p<T V-1, W(F)=$ $\operatorname{det} F, N=r=5$, we may find $u_{n} \mathcal{F}^{*} u$ in $W^{\text {liP }}, \operatorname{tz}(x)=x$ with $r_{n}(z)=x$ and

$$
\int_{J o} \mid \operatorname{det}(V u) \backslash>\liminf \int J \quad \backslash \operatorname{det}\left(V u_{n}\right) \backslash .
$$

Moreover the growth condition prescribed in Theorem 4.1 is the well known growth condition ensuring weak lower semicontinuity of $E(u, i d)$ in $W^{l}>^{p}$ (see [AF] and [Da]).
4. We may ask if these results can be extended to the case ${ }^{\wedge}{ }_{-j}^{j}-<q<N$, since, due to Müller's result ([Mu]), if we assume that $\operatorname{DetVv}=1$ a.e. then $\operatorname{DetVv}=\operatorname{detVv}$ a.e. in n.
5.Having obtained lower semicontinuity of the energy in Theorem 4.1, the question now amounts to showing that one can find a minimizing sequence $\left\{\mathrm{Vu}_{\mathbf{n}}(\mathbf{V i} ; \mathbf{n})^{\prime \prime \prime 1}\right\}$ where $\left\{\mathbf{u}_{\mathrm{n}}\right\}$ is bounded in $\boldsymbol{W}^{l^{*}}$ and $\left\{v_{n}\right\}$ is bounded in $\boldsymbol{W}^{l * q}$. Actually, one only needs to show that there exists a sequence $\left\{/_{\mathrm{n}}\right\} \quad \mathrm{C} W^{l, \circ}\left(f l_{j} i l\right)$ such that $v_{n} o f_{n}$ is bounded in $W^{l^{*}}$ and

$$
\begin{aligned}
\mathrm{f} \operatorname{det} V f_{n}(x) & =1 \text { a.e. } \times 6 \mathrm{ft} \\
\mathrm{t} />(*) & =\mathbf{i} \boldsymbol{x} € \operatorname{an} .
\end{aligned}
$$

Due to the examples provided in [DF], we know that this may not be possible since the infimum of $E$ may be zero, which prevents the existence of minimizing sequence bounded in $\boldsymbol{W}^{l *} \boldsymbol{x} \boldsymbol{W}^{l}{ }^{l}$ 。

As usual in variational problems for which existence of minimizers is not guaranteed (such as variational problems for material that change phase and, here, for slightly defective materials), rather then studying the macroscopic limit of $V u_{n}(V z ; n) \sim^{1}$ we focus on the properties of the minimizing sequences.

The following may help to understand better why boundedness of $\left\{V \mathbf{u}_{\mathbf{n}}\left(V \boldsymbol{v}_{\boldsymbol{n}}\right) \sim^{l}\right\}$ may not entail the boundedness of $\left\{V u_{n}\right\}$ and $\left\{V v_{n}\right\}$. Using Theorem 4.1 we show that we may construct a minimizing sequence $\left\{V \mathbf{u}^{\wedge} V r J^{\wedge 1}\right\}$ with $\left\|V u_{c}\right\|_{p}=0(\wedge),\left\|V r_{c}\right\|_{9}=0(\underset{e j}{\boldsymbol{1}})$. for any $\mathrm{a}, f 3>0$.

Consider the "perturbed" family of variational problems

$$
E_{c}(u, v)=\int_{\Omega} W\left(\nabla u(\nabla v)^{-1}\right) d x+\epsilon^{\alpha p}\left\|\nabla u_{c}\right\|_{p}^{p}+\epsilon^{\beta q}\left\|\nabla v_{\epsilon}\right\|_{q}^{q},
$$

where $\left.u\right|_{\partial \Omega}=u_{0}, \operatorname{det} \nabla v=1$ a.e., $\quad \frac{1}{\mid \Omega} \int_{\Omega} v(x) d x=0$. Using the direct method of the Calculus of Variations, Poincarés inequality and Theorem 4.1, it follows immediatly that there exists $\left(u_{c}, v_{c}\right) \in W^{1, p} \times W^{1, q}$ such that

$$
E_{\epsilon}\left(u_{\epsilon}, v_{\epsilon}\right)=\inf \left\{E_{\epsilon}(u, v):(u, v) \in W^{1, p} \times W^{1, q}, \operatorname{det} \nabla v=1 \text { a.e. }\right\}
$$

Then, given an admissible pair ( $u, v$ )

$$
\begin{aligned}
E(u, v) & =\lim _{\epsilon \rightarrow 0+} E_{\epsilon}(u, v) \\
& \geq \lim \sup _{\epsilon \rightarrow 0+} E_{\epsilon}\left(u_{\epsilon}, v_{\epsilon}\right) \\
& \geq \lim \sup _{\epsilon \rightarrow 0+} E\left(u_{\epsilon}, v_{\epsilon}\right) \\
& \geq \inf E .
\end{aligned}
$$

Doing the same with $\liminf _{\epsilon \rightarrow 0+} E\left(u_{\epsilon}, v_{\epsilon}\right)$ and taking the infimum in $(u, v)$ we conclude that

$$
\inf E=\lim _{\epsilon \rightarrow 0+} E\left(u_{\epsilon}, v_{\epsilon}\right)
$$

and $\left\|\nabla u_{\epsilon}\right\|_{p}=0\left(\frac{1}{\epsilon^{\alpha}}\right),\left\|\nabla v_{\epsilon}\right\|_{q}=0\left(\frac{1}{\epsilon^{\beta}}\right)$.
The following two lemmas will be useful to prove Theorem 4.1.
Lemma 4.3 Let $\Omega^{\prime}, \Omega$ be two open sets of $\mathbf{R}^{N}$ such that $\Omega^{\prime} \subset \subset \Omega$, let $q \geq N$ and $v, v_{n} \in$ $W^{1, q}(\Omega)^{N}$ be such that $\operatorname{det} \nabla v(x)=\operatorname{det} \nabla v_{n}(x)=1$ a.e. $x \in \Omega$. Assume that $v_{n}-v$ in $W^{1, q}(\Omega)^{N}$. Then there exists a subsequence of $\left\{v_{n}\right\}$ (not relabelled) such that for almost every $x_{0} \in \Omega^{\prime}$ there exist open sets $D, D_{n} \subset \Omega^{\prime}$ containing $x_{0}$, there exist $n_{0} \in N, r_{0} \equiv$ $r\left(x_{0}\right)>0, w: B\left(y_{0}, r_{0}\right) \rightarrow D, w_{n}: B\left(y_{0}, r_{0}\right) \rightarrow D_{n}$, with $y_{0}=v\left(x_{0}\right)$ such that for $n \geq n_{0}$

$$
\begin{aligned}
& w_{n} \circ v_{n}(x)=x \text { a.e. } x \in \bar{D}_{n}, \\
& v_{n} \circ w_{n}(y)=y \text { for every } y \in \bar{B}\left(y_{0}, r_{0}\right) \text { and } v_{n}\left(D_{n}\right)=B\left(y_{0}, r_{0}\right) \\
& w \circ v(x)=x \text { a.e. } x \in \bar{D} \text { and } v\left(x_{0}\right) \neq v(x) \text { for } x \in D, x \neq x_{0} \\
& v \circ w(y)=y \text { for every } y \in \bar{B}\left(y_{0}, r_{0}\right) \text { and } v(D)=B\left(y_{0}, r_{0}\right), \\
& w_{n}, w \in W^{1, \frac{s}{N-1}} .
\end{aligned}
$$

Proof. Using Lemma 2.2 and the Ascoli-Arzela Theorem we obtain that, up to a subsequence, $v_{n}$ converges to $v$ uniformly in $\bar{\Omega}^{\prime}$. By Lemmas 3.7 and 2.7 for almost every
$x_{0} \in \Omega^{\prime}$, there is $R_{0}>0$ such that

$$
\begin{aligned}
& B\left(x_{0}, R_{0}\right) \subset \subset \Omega^{\prime} \\
& \left.N\left(v, B\left(x_{0}, R_{0}\right), y\right)\right)=1 \text { for almost every } y \in C_{R_{0}} \\
& d\left(v, B\left(x_{0}, R_{0}\right), y\right)=1 \text { for every } y \in C_{R_{0}} \\
& d(v, B, y)=1 \text { for every } y \in B \backslash v(\partial B)
\end{aligned}
$$

$$
\text { for every non empty open set } B \subset v^{-1}\left(C_{R_{0}}\right) \cap B\left(x_{0}, R_{0}\right) \text { such that }|v(\partial B)|=0
$$

where $C_{R_{0}}$ is the connected component of $\mathbf{R}^{N} \backslash v\left(\partial B\left(x_{0}, R_{0}\right)\right)$ containing $y_{0}:=v\left(x_{0}\right)$. Since $v$ is completely differentiable at $x_{0}$ and $\operatorname{det} \nabla v\left(x_{0}\right) \neq 0$ we may assume without loss of generality that $\left.N\left(v, B\left(x_{0}, R_{0}\right), y_{0}\right)\right)=1$. Fix $0<\epsilon<d\left(y_{0}, v\left(\partial B\left(x_{0}, R_{0}\right)\right)\right)$ and choose $n_{0} \in N$ such that $\left|v_{n}-v\right|_{\infty}<\epsilon$. Set

$$
A_{\epsilon}:=\left\{y \in C_{R_{0}}: \operatorname{dist}\left(y, v\left(\partial B\left(x_{0}, R_{0}\right)\right)\right)>\epsilon\right\}
$$

It is obvious that $A_{c}$ is a non-empty open set.
Claim $1 d\left(v_{n}, B\left(x_{0}, R_{0}\right), y\right)$ exists and is equal to 1 for every $y \in A_{\epsilon}$ and every $n \geq n_{0}$. By Proposition 2.3 (4), together with the fact that $d\left(v, B\left(x_{0}, R_{0}\right), y\right)=1$ for every $y \in C_{R_{0}}$, we have

$$
\begin{equation*}
d\left(v_{n}, B\left(x_{0}, R_{0}\right), y\right)=1 \tag{45}
\end{equation*}
$$

for every $y \in A_{\epsilon}$ and every $n \geq n_{0}$.
By Lemma 3.9 there is $0<r_{0}<R_{0}$ such that

$$
\begin{equation*}
\left.B\left(y_{0}, r_{0}\right) \subset \subset A_{\epsilon} \text { and } v^{-1}\left(B\left(y_{0}, r_{0}\right)\right) \cap B\left(x_{0}, R_{0}\right) \subset \subset B\left(x_{0}, R_{0}\right)\right) \tag{46}
\end{equation*}
$$

Claim 2 We claim that

$$
\begin{equation*}
B\left(y_{0}, r_{0}\right) \subset \subset C_{R_{0}}^{n} \tag{47}
\end{equation*}
$$

where $C_{R_{0}}^{n}$ is the connected component of $\mathbf{R}^{N} \backslash v_{n}\left(\partial B\left(x_{0}, R_{0}\right)\right)$ containing $y_{0}$.
We prove first that $A_{c} \subset \mathbf{R}^{N} \backslash v_{n}\left(\partial B\left(x_{0}, R_{0}\right)\right)$. Assume on the contrary that there is $y \in A_{c} \cap v_{n}\left(\partial B\left(x_{0}, R_{0}\right)\right)$ and choose $x \in \partial B\left(x_{0}, R_{0}\right)$ such that $y=v_{n}(x)$. We would have $\left|v_{n}(x)-v(x)\right|=|y-v(x)|>\epsilon>\left|v_{n}-v\right|_{\infty}$ which yields a contradiction. Fix $r^{\prime}>r_{0}$ such that $\bar{B}\left(y_{0}, r^{\prime}\right) \subset A_{c}$. We have $B\left(y_{0}, r^{\prime}\right)$ is a connected set included in $\mathbf{R}^{N} \backslash v_{n}\left(\partial B\left(x_{0}, R_{0}\right)\right)$ and containing $y_{0}$. We deduce that $B\left(y_{0}, r^{\prime}\right) \subset C_{R_{0}}^{n}$ and $B\left(y_{0}, r_{0}\right) \subset \subset C_{R_{0}}^{n}$.

Set $D=v^{-1}\left(B\left(y_{0}, r_{0}\right)\right) \cap B\left(x_{0}, R_{0}\right) \subset \subset \Omega^{\prime}$ and $D_{n}=v_{n}^{-1}\left(B\left(y_{0}, r_{0}\right)\right) \cap B\left(x_{0}, R_{0}\right) \subset \subset \Omega^{\prime}$. By (45), (46), (47) and using arguments similar to the ones of the proof of Theorem 3.1. together with Corollary 3.3 we deduce that for $n \geq n_{0}$ there is $w_{n}: \bar{B}\left(y_{0}, r_{0}\right) \rightarrow \bar{D}_{n}$, there is $w: \bar{B}\left(y_{0}, r_{0}\right) \rightarrow \bar{D}$ such that

$$
w_{n}, w \in W^{1, N^{\frac{s}{-1}}}\left(B\left(y_{0}, r_{0}\right)\right)^{N}
$$

$$
\begin{aligned}
& w_{n} \circ v_{n}(x)=x \text { a.e. } x \in \bar{D}_{n}, \\
& v_{n} \circ w_{n}(y)=y \text { a.e. } y \in \bar{B}\left(y_{0}, r_{0}\right) \\
& w \circ v(x)=x \text { a.e. } x \in \bar{D} \text { and } v\left(x_{0}\right) \neq v(x) \text { for } x \in \bar{D}, x \neq x_{0}, \\
& v \circ w(y)=y \text { a.e. } y \in \bar{B}\left(y_{0}, r_{0}\right) .
\end{aligned}
$$

Finally by Lemma $3.8, v_{n}\left(D_{n}\right)=v(D)=B\left(y_{0}, r_{0}\right)$.

## Remarks 4.4

1. It follows from the proof above that if the conclusion of Lemma 4.3 holds for $r \equiv r\left(x_{0}\right)>0$ then it holds also for $0<r^{\prime}<r$. Thus, as $v$ is continuous on $\bar{D}, v(x) \neq v\left(x_{0}\right)$ for $x \in D$ and $x \neq x_{0}$, we deduce that

$$
\lim _{r \rightarrow 0} \max \left\{\left|x-x_{0}\right|, x \in \bar{D}, v(x) \in B\left(y_{0}, r_{0}\right)\right\}=0
$$

2. It is possible to show that $\lim _{n \rightarrow+\infty}\left|D \Delta D_{n}\right|=0$. We divide the proof into two cases.
Claim $1 \lim _{n \rightarrow+\infty}\left|D \backslash D_{n}\right|=0$.
Let $F_{\epsilon}=B\left(y_{0}, r_{0}-\epsilon\right)$ and $O_{\epsilon}=v^{-1}\left(F_{\epsilon}\right) \cap D$. We prove first that for each $\epsilon$ fixed there exists $n_{0} \equiv n_{0}(\epsilon) \in \mathrm{N}$ such that $n \geq n_{0}$ implies $O_{\epsilon} \subset D_{n}$. Indeed, since $\left\{v_{n}\right\}$ converge to $v$ uniformly, there exists $n_{0} \equiv n_{0}(\epsilon) \in \mathbf{N}$ such that $\left|v-v_{n}\right|_{\infty} \leq \frac{\epsilon}{2}$ for every $n \geq n_{0}$. If $x \in O_{\epsilon}$, we obtain

$$
\left|v_{n}(x)-y_{0}\right| \leq\left|v(x)-y_{0}\right|+\left|v(x)-v_{n}(x)\right|<r_{0}
$$

and so $x \in D_{n}$. As $\cup_{\epsilon} O_{\epsilon}=D$ and the sequence $\left(O_{\epsilon}\right)$ is non-increasing, we have

$$
\lim _{\epsilon \rightarrow 0}\left|D \backslash O_{\epsilon}\right|=0
$$

which, together with the fact that $\left|D \backslash D_{n}\right| \leq\left|D \backslash O_{\epsilon}\right|$ for $n \geq n_{0}$, yields claim 1 .
Claim $2 \lim _{n \rightarrow+\infty}\left|D_{n} \backslash D\right|=0$.
For $\epsilon>0$ take $n_{0} \equiv n_{0}(\epsilon) \in N$ such that $\left|v-v_{n}\right|_{\infty} \leq \frac{\epsilon}{2}$ for every $n \geq n_{0}$. For $n \geq n_{0}$, we have
$\left\{x \in B\left(x_{0}, R_{0}\right): r-\frac{\epsilon}{2} \leq\left|v_{n}(x)-y_{0}\right|<r\right\} \subset\left\{x \in B\left(x_{0}, R_{0}\right): r-\epsilon \leq\left|v(x)-y_{0}\right|<r+\epsilon\right\}$
and since $v$ has the $N^{-1}$ property (see Remark 2.5) we obtain
$\left|\cap_{\epsilon}\left\{x \in B\left(x_{0}, R_{0}\right): r-\epsilon \leq\left|v(x)-y_{0}\right|<r+\epsilon\right\}\right|=\left|\left\{x \in B\left(x_{0}, R_{0}\right):\left|v(x)-y_{0}\right|=r\right\}\right|=0$.
To conclude the proof of claim 2 it suffices to remark that for $n \geq n_{0}$ we obtain

$$
D_{n} \backslash D \subset\left\{x \in B\left(x_{0}, R_{0}\right): r-\epsilon \leq\left|v(x)-y_{0}\right|<r+\epsilon\right\} .
$$

Lemma 4.5 Let $p \geq 1, q \geq N, r \geq 1$ be such that $\frac{1}{p}+\frac{N-1}{q}=\frac{1}{r}$. Assume that $\Omega \subset \mathbf{R}^{N}$ is an open, bounded set, $u_{n}, u \in W^{1, q}(\Omega)^{N}, u_{n} \rightharpoonup u$ in $\left.W^{1, p}(\Omega)^{N}, v_{n}, v \in W^{1, q} \Omega\right)^{N}$, $\operatorname{det} \nabla v_{n}=\operatorname{det} \nabla v=1$ a.e. in $\Omega$ and $v_{n} \rightarrow v$ in $W^{1, q}(\Omega)^{N}$. Let $x_{0} \in \Omega$, and $w_{n}, w$ be, respectively the local inverse function of $v_{n}, v$, in the open neighborhoods $D_{n}, D$ of $x_{0}$, let $y_{0}=v\left(x_{0}\right)$ and $B\left(y_{0}, r_{0}\right)$ be as in Lemma 4.3 and Remark 4.4. Then the following hold:
i) $u_{n} \circ w_{n} \in W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$ and $\nabla\left(u_{n} \circ w_{n}\right)(y)=\nabla u_{n}\left(w_{n}(y)\right)\left(\nabla v_{n}\left(w_{n}(y)\right)\right)^{-1}$ a.e.
ii) $u_{n} \circ w_{n}-u \circ w$ in $W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$ if $r>1$,
iii) $u_{n} \circ w_{n} \rightarrow u \circ w$ in $L^{1}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$ and $\left\{u_{n} \circ w_{n}\right\}$ is bounded in $W^{1,1}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$ if $r=1$.

Proof. We remind that by Lemma 4.3 we have

$$
\begin{align*}
& w_{n}, w \in W^{1, \cdot \frac{g}{N^{-1}}}\left(B\left(y_{0}, r_{0}\right)\right)^{N}, \quad v(D)=B\left(y_{0}, r_{0}\right), v_{n}\left(D_{n}\right)=B\left(y_{0}, r_{0}\right),  \tag{48}\\
& \nabla w(y)=(\nabla v(w(y)))^{-1}, \nabla w_{n}(y)=\left(\nabla v_{n}\left(w_{n}(y)\right)\right)^{-1} \text { a.e. } y \in B\left(y_{0}, r_{0}\right)  \tag{49}\\
& N(v, D, y)=N\left(v_{n}, D_{n}, y\right)=1 \text { a.e. } y \in B\left(y_{0}, r_{0}\right)  \tag{50}\\
& w \circ v(x)=x \text { a.e. } x \in D, w_{n} \circ v_{n}(x)=x \text { a.e. } x \in D_{n} . \tag{.51}
\end{align*}
$$

First step. We prove that $u \circ w, u_{n} \circ w_{n} \in W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$.
In fact by the change of variables formula (11), (48), (49), (50) and (51) we have

$$
\begin{aligned}
\int_{B\left(y_{0}, r_{0}\right)}|u \circ w(y)|^{r} d y & =\int_{v(D)}|u \circ w(y)|^{r} N(v, D, y) d y \\
& =\int_{D}|u(x)|^{r} d x<+\infty
\end{aligned}
$$

Thus

$$
u \circ w, u_{n} \circ w_{n} \in L^{r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}
$$

Let $\phi \in C_{0}^{\infty}\left(B\left(y_{0}, r_{0}\right)\right)$. By (11), (48), (49), (50), (51) and using the fact that each vector row of $a d j \nabla v$ is divergence free, we have

$$
\begin{aligned}
\int_{B\left(y_{0}, r_{0}\right)} u_{i} \circ w(y) \frac{\partial \phi}{\partial y_{j}} d y & =\int_{D} u_{i}(x) \frac{\partial \phi}{\partial y_{j}} \circ v(x) d x \\
& =-\int_{D} \sum_{l=1}^{N} \frac{\partial u_{i}}{\partial x_{l}}(x)\left((\nabla v(x))^{-1}\right)_{j}^{l} \phi \circ v(x) d x \\
& =-\int_{B\left(y_{0}, r_{0}\right)} \sum_{l=1}^{N} \frac{\partial u_{i}}{\partial x_{l}}(w(y))\left((\nabla v)^{-1} \circ w(y)\right)_{j}^{l} \phi(y) d y
\end{aligned}
$$

Thus

$$
u \circ w \in W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}
$$

and

$$
\nabla u \circ w(y)=\nabla u(w(y))(\nabla v(w(y)))^{-1} \text { a.e. in } B\left(y_{0}, r_{0}\right) .
$$

We have a similar result for $u_{n} \circ w_{n}$.
Second step. We conclude that $\left\{u_{n} \circ w_{n}\right\}$ is bounded in $W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$. Indeed

$$
\int_{B\left(y_{0}, r_{0}\right)}\left|u_{n} \circ w_{n}(y)\right|^{r} d y=\int_{D_{n}}\left|u_{n}(x)\right|^{r} d x \leq \int_{\Omega}\left|u_{n}(x)\right|^{r} d x
$$

Since $r \leq p$ and $\left\{u_{n}\right\}$ is bounded in $W^{1, p}(\Omega)^{N}$ we deduce that $\left\{u_{n} \circ w_{n}\right\}$ is bounded in $L^{r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$.
Also

$$
\begin{aligned}
\int_{B\left(y_{0}, r_{0}\right)}\left|\nabla u_{n} \circ w_{n}(y)\right|^{r} d y & =\int_{D}\left|\nabla u_{n}(x)\left(\nabla w_{n}(x)\right)^{-1}\right|^{r} d x \\
& \leq C^{\prime}\left[\int_{\Omega}\left|\nabla u_{n}(x)\right|^{p} d x\right]^{\frac{r}{p}}\left[\int_{\Omega}\left|\nabla v_{n}(x)\right|^{\frac{q}{-1}} d x\right]^{\frac{r(N-1)}{p}} \leq C
\end{aligned}
$$

for some constant $C$ which does not depend on $y_{0}, r$ and $n$. Thus $\left\{u_{n} \circ w_{n}\right\}$ is bounded in $W^{1, r}\left(B\left(y_{0}, r_{0}\right)\right)^{N}$.
Third step. We prove that, up to a subsequence, $u_{n} \circ w_{n}$ converges strongly in $L^{1}\left(B\left(y_{0}, r_{0}\right)\right)$ to $u \circ w$. Let $f \in C\left(\bar{B}\left(y_{0}, r_{0}\right)\right)$. By Remark $4.4 \lim _{n \rightarrow+\infty}\left|D \Delta D_{n}\right|=0$ and so

$$
\chi_{D_{n}}(x) \rightarrow \chi_{D}(x) \text { a.e. } x \in \Omega .
$$

Using the fact that $u_{n}-u$ in $W^{1, p}(\Omega)^{N}, v_{n}-v$ in $W^{1, q}(\Omega)^{N}$ and assuming, without loss of generality, that $u_{n} \rightarrow u$ a.e., $v_{n} \rightarrow v$ a.e. we obtain by (11) and the Lebesgue Dominated Convergence Theorem that

$$
\begin{aligned}
\lim _{n \rightarrow+\infty} \int_{B\left(y_{0}, r_{0}\right)} u_{n} \circ w_{n}(y) f(y) d y & =\lim _{n \rightarrow+\infty} \int_{D_{n}} u_{n}(x) f\left(v_{n}(x)\right) d x \\
& =\int_{D} u(x) f(v(x)) d x \\
& =\int_{B\left(y_{0}, r_{0}\right)} u \circ w(y) f(y) d y
\end{aligned}
$$

Therefore $u_{n} \circ w_{n}$ converges strongly to $u \circ w$ in measure and applying the Sobolev Imbedding Theorem to the bounded sequence $\left\{u_{n} \circ w_{n}\right\}$ in $W^{1, r}(\Omega)$, we conclude that, up to a subsequence, $u_{n} \circ w_{n}$ converges strongly in $L^{1}\left(B\left(y_{0}, r_{0}\right)\right)$ to $u \circ w$.
Fourth step. Using the second and the third step we conclude that $\left\{\nabla u_{n} \circ w_{n}\right\}$ is bounded in $W^{1, r}(\Omega)^{N}$,

$$
u_{n} \circ w_{n}-u \circ w \text { in } W^{1, r}(\Omega)^{N} \text { if } r>1
$$

and

$$
u_{n} \circ w_{n} \rightarrow u \circ w \text { in } L^{1}(\Omega)^{N} \text { if } r=1
$$

We now give the proof of Theorem 4.1.

Proof of Theorem 4.1. Without loss of generality (and, if necessary, after extracting a subsequence of $\left.\left\{\left(\mathbf{u}_{\mathbf{n}}, \mathbf{v}_{\mathrm{n}}\right)\right\}\right)$, we assume that

$$
\left.\liminf / W\left(V u_{n}(x)\left\{V v_{n}(x)\right) \sim^{l}\right) d x=\lim \quad / \mathbf{M}^{\wedge}\left(\operatorname{Vu}_{\mathbf{n}}(\mathbf{x})\left(V i ;{ }_{n}(\mathbf{x})\right)\right)^{1}\right) \mathbf{d x}<+00 .
$$

Fix $\mathrm{e}>0$ and let $\mathbf{Q}_{\mathrm{c}} \mathbf{C C}$ ft be an open set such that $\left|\mathrm{ft} \backslash \mathrm{ft}_{\mathrm{c}}\right|<\mathrm{c}$. By Lemma 2.2 and the Ascoli-Arzela Theorem, without loss of generality, we assume that $v_{n}$ converges to $v$ uniformly in $\overline{\mathbf{f}}_{\mathbf{c}}$. Set
$C=\left\{x € \mathrm{ft}_{\mathrm{c}} \backslash \boldsymbol{v}\right.$ is completely differentiate and almost invertible at x$\}$,
$A=\left\{J 9(x) \mid x 6 C, D(x)\right.$ is an open set of $f_{t}, v(D(x))$ is an open ball $\}$
and

$$
\text { ft'e }=U_{D \in A} D .
$$

As in the proof of Lemma 3.9, it is easy to see that

$$
\inf \{\operatorname{diamD}(x) \backslash D(x) \in A\}=0
$$

for every x G C. By Lemma 4.3 and Vitali's covering theorem (see [Fe] Theorem 2.8.17, p. 151) there exist $\left\{\mathbf{x}^{\mathbf{J}}, \boldsymbol{j} € \mathbf{N}\right\} \mathbf{C} \mathbf{f t}_{\mathbf{o}}\left\{-\mathbf{D}^{\mathbf{J}}, \boldsymbol{j} € \mathbf{N}\right\}$ a family of mutually disjoint, open neighborhoods of, respectively, $\mathbf{X j}, N$ a set of measure zero such that,

$$
\Omega=N \| \mathcal{N} D^{i}
$$

 Theorem 3.1, for some $\mathbf{r j}>0$ and with $y^{\mathbf{J}}=v\left(x^{\dot{J}}\right)$. Recall that

$$
\begin{aligned}
& \left.\mathrm{V}\left(\operatorname{uot}^{\wedge}\right)(\mathbf{y})=\operatorname{VtxK}(\mathbf{y})\right)(\mathrm{Vt} ; \mathrm{K}(\mathrm{j} /)) \mathbf{r}^{1} \text { a.e. } \boldsymbol{y} \operatorname{GJB}\left(\mathrm{y}^{\mathrm{J}}, \mathrm{H}\right), \\
& \mathbf{t i}^{\wedge} \text { o i? }(x)=x \text { a.e } \times 6 D^{\dot{j}}, \\
& \operatorname{voxv}^{i}(y)-y \text { - a.e } \quad \mathbf{y} \in \mathbf{B}\left(\mathbf{t} \mathbf{~}^{\mathbf{j}}, \dot{\mathbf{H}}\right)
\end{aligned}
$$

and $\mathbf{D}^{\mathbf{j}}=\mathbf{t} ;-^{\mathbf{1}}\left(\mathbf{B}\left(\mathbf{y}^{\mathbf{j}}, \mathbf{r}^{\mathbf{i}}\right)\right) \mathbf{n J 5}\left(\mathbf{x}^{\mathbf{J}}, \mathrm{JR}^{\wedge}\right)$ for some $\mathbf{i} \#>\mathbf{0}$. Fix $k G \mathrm{~N}$. By Lemma 4.5 we.obtain for each $\boldsymbol{j}=1, \cdots, k$ and up to a subsequence, the existence of $\boldsymbol{w}^{\mathbf{3}}{ }_{n} \mathbf{G} W^{\boldsymbol{l}} \wedge\left(B\left(y \backslash r^{J}\right)\right)^{\mathrm{A}}$ which is the inverse function of $\operatorname{Vnl}]^{\wedge}$ where $D^{3}{ }_{n} \approx \sim^{l}\left(B\left(y^{J}, r^{3}\right)\right) D B\left(x^{J}, R^{J}\right)$. Recall that $\frac{1}{r}=\frac{1}{p}+^{\wedge} \quad$ danla a so

$$
\begin{aligned}
& \mathbf{u}^{\wedge} \mathrm{OV}_{\mathbf{n}}(\mathbf{x})=\mathbf{x} \text { a.e. } \mathbf{x} \mathbf{G} D_{n}^{j}, \\
& u_{n} \circ w_{n}^{j} \in W^{1, r}\left(B\left(y^{j},\right)\right)^{N} \text {, } \\
& \left.\left.\nabla\left(u_{n} \circ w_{n}^{j}\right)(y)=V<_{\mathrm{n}} K(y)\right)\left(V v_{\mathrm{n}} K(y)\right)\right)-^{1} \text { a.e., } \\
& \mathrm{UnO}^{\wedge}-\mathbf{u o t}{ }^{\wedge} \text { in } W^{l f r}\left(B\left(y_{y}^{i} r^{i}\right)\right)^{N} \text { if r>1, } \\
& u_{n} o w>_{n^{-}}{ }^{*} u o x v>{ }^{-} \quad \text { in } L^{1}\left(B\left\{y_{t}^{i} r^{i}\right) f_{t}\right. \\
& \left\{\mathbf{u}_{\mathrm{n}} \mathrm{ou}^{\wedge}\right\} \text { is bounded in } W^{l, l}\left(B\left(y^{i}, r^{i}\right)\right)^{f f} \text { if } \mathbf{r}=1 \text {, } \\
& \operatorname{Uum}_{n \rightarrow+\infty}\left|\mathbf{D}_{n}^{j} \Delta D^{j}\right|=0 \text {. }
\end{aligned}
$$

Fix

$$
0<\eta<\min \left\{r^{j}: j=1, \cdots, k\right\} .
$$

There exists $n(\eta) \in N$ such that for every $n \geq n(\eta)$ we obtain

$$
\max \left\{\left|v_{n}(x)-v(x)\right| \mid x \in \Omega_{\epsilon}\right\}<\eta .
$$

Since $D^{j}=v^{-1}\left(B\left(y^{j}, r^{j}\right)\right) \cap B\left(x^{j}, R^{j}\right)$, we deduce that for every $n \geq n(\eta)$

$$
D_{n}^{j}(\eta):=D_{n}^{j} \cap v_{n}^{-1}\left(B\left(y^{j}, r^{j}-\eta\right)\right) \subset D^{j}
$$

and so $D_{n}^{i} \cap D_{n}^{j}=\emptyset$ if $i \neq j$. Set

$$
D^{j}(\eta):=D^{j} \cap v^{-1}\left(B\left(y^{j}, r^{j}-\eta\right)\right) .
$$

We divide the rest of the proof of Theorem 4.1 into two cases.
First case We assume that $1=r=\frac{1}{p}+\frac{N-1}{q}$ and there is a constant $C$ such that
 are mutually disjoint for every $n \in N$, we have by [FM]

$$
\begin{align*}
\int_{U_{j=1}^{k} D^{j}(\eta)} W\left(\nabla u(x)(\nabla v)^{-1}(x)\right) d x & =\sum_{j=1}^{k} \int_{D^{j}(\eta)} W\left(\nabla u(x)(\nabla v)^{-1}(x)\right) d x \\
& =\sum_{j=1}^{k} \int_{B\left(y^{j}, r^{j}-\eta\right)} W\left(\left(\nabla u \circ w^{j}\right)(y)\right) d y \\
& \leq \sum_{j=1}^{k} \liminf _{n \rightarrow+\infty} \int_{B\left(y^{j}, r^{j}-\eta\right)} W\left(\left(\nabla u_{n} \circ w_{n}^{j}\right)(y)\right) d y(  \tag{52}\\
& =\sum_{j=1}^{k} \liminf _{n \rightarrow+\infty} \int_{D_{n}^{j}(\eta)} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& \leq \liminf _{n \rightarrow+\infty} \sum_{j=1}^{k} \int_{D^{j}} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& \leq \liminf _{n \rightarrow+\infty} \int_{\Omega} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x
\end{align*}
$$

Letting $\eta$ go to zero, $k$ go to infinity and then $\epsilon$ go to zero we have

$$
E(u, v) \leq \liminf _{n \rightarrow+\infty} E\left(u_{n}, v_{n}\right)
$$

Second case We assume that $1<r=\frac{1}{p}+\frac{N-1}{q}$ and there are some constants $C_{1}, C_{2}>$ $0,1 \leq s \leq r$ such that $-C_{1}\left(1+|F|^{*}\right) \leq W(F) \leq C_{2}\left(1+|F|^{r}\right)$ for every $F \in M^{N \times N}$. The proof follows as in the first case, where on step (52) we use the lower semicontinuity
results of $[\mathrm{Da}]$ instead of $[\mathrm{FM}]$. Since $\left.\left\{\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right)\right\}$ is weakly relatively compact in $\Omega$, we have

$$
\begin{aligned}
\int_{U_{j=1}^{k} D^{j}(\eta)} W\left(\nabla u(x)(\nabla v)^{-1}(x)\right) d x \quad & =\sum_{j=1}^{k} \int_{D^{j}(\eta)} W\left(\nabla u(x)(\nabla v)^{-1}(x)\right) d x \\
& =\sum_{j=1}^{k} \int_{B\left(\boldsymbol{y}^{j}, r^{j}-\eta\right)} W\left(\left(\nabla u \circ w^{j}\right)(y)\right) d y \\
& \leq \sum_{j=1}^{k} \liminf _{n \rightarrow+\infty} \int_{B\left(y^{j}, r^{j}-\eta\right)} W\left(\left(\nabla u_{n} \circ w_{n}^{j}\right)(y)\right) d y \\
& =\sum_{j=1}^{k} \liminf _{n \rightarrow+\infty} \int_{D_{n}^{j}(\eta)} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& =\sum_{j=1}^{k} \liminf _{n \rightarrow+\infty}\left[\int_{D^{j}} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x\right. \\
& +\int_{D_{n}^{j}(\eta) \backslash D^{j}} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& \left.-\int_{D^{j} \backslash D_{n}^{j}(\eta)} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x\right] \\
& \leq \sum_{j=1}^{k} \liminf _{n \rightarrow+\infty} \int_{D^{j}} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& \left.+\left.C_{1} \int_{D^{j} \Delta D_{n}^{j}}\left(1+\mid \nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right)\right|^{s}\right) d x \\
& \leq \liminf _{n \rightarrow+\infty} \sum_{j=1}^{k} \int_{D^{j}} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x \\
& \leq \liminf _{n \rightarrow+\infty} \int_{\Omega} W\left(\nabla u_{n}(x)\left(\nabla v_{n}\right)^{-1}(x)\right) d x
\end{aligned}
$$

Letting $\eta$ go to zero, $k$ go to infinity and then $\epsilon$ go to zero we conclude that

$$
E(u, v) \leq \liminf _{n \rightarrow+\infty} E\left(u_{n}, v_{n}\right)
$$

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[^0]:    ${ }^{1}$ we recall that if $A$ is a $N \times N$ matrix, then $\operatorname{adj} A$ is a matrix such that $A \cdot \operatorname{adj} A=I_{N} \operatorname{det} A$.

