DET = DET -- A REMARK ON THE DISTRIBUTIONAL DETERMINANT

by

Stefan Müller

Department of Mathematics Carnegie Mellon University Pittsburgh, PA 15213

Research Report No. 90-76 2

February 1990

510.6 C28R 90-76

Det = det - A remark on the distributional determinant

Stefan Müller

Department of Mathematics, Carnegie Mellon University Pittsburgh, PA 15213-3890, USA

Abstract — A proof of a conjecture of J.M.Ball concerning the distributional determinant is given and an application to nonlinear elasticity is indicated.

INTRODUCTION. — The aim of this note is to prove a conjecture of J.M. Ball concerning the distributional determinant. Consider for illustration a mapping u of an open bounded set $\Omega \subset \mathbb{R}^2$ into \mathbb{R}^2 . The Jacobian determinant of u is given by

$$\det Du(x) = u_{.1}^1(x)u_{.2}^2(x) - u_{.2}^1(x)u_{.1}^2(x),$$

where upper indices denote components and where lower indices with comma refer to partial derivatives. For the weak continuity properties of the Jacobian determinant and the existence theory in nonlinear elasticity it is of crucial importance that det Du can be expressed as a divergence. Let

Det
$$Du = (u^1 u_{.2}^2)_{.1} - (u^1 u_{.1}^2)_{.2}$$
.

Clearly Det $Du = \det Du$ for $u \in C^2$; by approximation that identity is easily seen to hold in the sense of distributions if u merely lies in the Sobolev space $W^{1,2}(\Omega; \mathbb{R}^2)$. By the Sobolev imbedding theorem, Det Du is well defined as a distribution if $u \in W^{1,4/3}(\Omega; \mathbb{R}^2)$, but the identity det = Det fails in general if one only assumes $u \in W^{1,p}(\Omega; \mathbb{R}^2)$, $\forall p < 2$. Indeed, letting Ω be the unit ball and $u(x) = \frac{x}{|x|}$ one finds that det Du = 0 a.e., while Det $Du = \pi \delta_0$. The fact that in this example the desired identity fails only by a Dirac mass led Ball [1] to conjecture that det Du = Det Du whenever Det Du is an L^1 function. Here we give a proof of that conjecture, in fact of a slightly stronger result (see Theorem 1 below).

For the statement in the *n*-dimensional case recall that for an n by n matrix F its adjugate adj F is the transpose of the matrix of its cofactors

(so that Fadj $F = \det F \operatorname{Id}$) and that for any function $u : \Omega \subset \mathbb{R}^n \to \mathbb{R}^n$, $u \in W^{1,n-1}(\Omega; \mathbb{R}^n)$, adj Du satisfies the identity

$$(\operatorname{adj} Du)_{1,j}^{j} = 0,$$

in the sense of distributions (see [2]), summation over repeated indices being understood. The distributional determinant is then defined as

$$\operatorname{Det} Du = (u^1(\operatorname{adj} Du)_1^j)_{,j}.$$

Theorem 1 shows that if $u \in W^{1,n^2/(n+1)}$ (so that Det Du is defined) and if $\text{Det } Du \in L^1$ then $\text{Det } Du = \det Du$.

MAIN RESULT. — Theorem 1. Let $\Omega \subset \mathbf{R}^n$ be open, let $1 \leq p < n$ and let $v \in W^{1,p}(\Omega)$. Assume that $\sigma \in L^q(\Omega; \mathbf{R}^n)$ with $\frac{1}{p} - \frac{1}{n} + \frac{1}{q} \leq 1$ and that the distributional divergence of σ satisfies div $\sigma \in L^1(\Omega)$. Assume finally that the distribution

$$d = \operatorname{div}(v\sigma),$$

satisfies $d \in L^1(\Omega)$. Then

$$d(x) = Dv(x).\sigma(x) + v(x)\operatorname{div}\sigma(x),$$

for a.e. $x \in \Omega$.

Remarks. - 1. The assumption on q guarantees that $v\sigma \in L^1_{loc}$ so that d is well defined; if p > n, q = 1 is sufficient.

2. If d is assumed to be a Radon measure rather than an L^1 -function then $Dv.\sigma + v \operatorname{div} \sigma$ equals the regular part of d a.e.

The arguments used in the proof are entirely local, so W^{1,p}, L^q and L¹ could be replaced by W^{1,p}_{loc}, L^q_{loc} and L¹_{loc}.
The distributional determinant is obtained as a special case by letting

4. The distributional determinant is obtained as a special case by letting $v = u^1, \sigma^j = (\operatorname{adj} Du)_1^j, p = n^2/(n+1)$ and $q = p/(n-1) = n^2/(n^2-1)$.

5. Theorem 1 allows one to reformulate the existence theory of Ball [1] using the pointwise determinant det Du rather than the distributional determinant Det Du. In the two-dimensional case one would minimize in a subset of $\mathcal{A} = \{u \in W^{1,4/3} : \text{Det } Du \in L^1\}$, in the three-dimensional in a subset of $\mathcal{A} = \{u \in W^{1,p} : \text{Adj } Du \in L^q, \text{Det } Du \in L^1\}, p \geq 3/2, 1/p + 1/q \leq 4/3.$

- University Libraries Carnegic Mellon University Dischargh, PA 15213-3800 The main ingredient in the proof of Theorem 1 is a version of the Lebesgue point theorem for $W^{1,p}$ functions due to Calderon and Zygmund [3] (see Ziemer [4] for refinements and further references). Denoting by $B_r(x_0)$ the ball of radius r around x_0 and by -f the average we have

Theorem 2 ([3, Thm. 12]). - Let $\Omega \subset \mathbb{R}^n$ be open, $1 \leq p < n$ and $v \in W^{1,p}(\Omega)$. Then, for a.e. $x_0 \in \Omega$,

$$\lim_{r\to 0}\frac{1}{r}\left\{\int_{B_r(x_0)}|v(x)-v(x_0)-Dv(x_0)(x-x_0)|^{p^*}\,dx\right\}^{1/p^*}=0,$$

where $p^* = \frac{pn}{n-p}$.

PROOFS. — Proof of Theorem 1 (div $\sigma = 0$). - For the sake of simplicity we first deal with the case div $\sigma = 0$ which is the one relevant to Ball's conjecture. By the Lebesgue point theorem and Theorem 2 we have, for a.e. $x_0 \in \Omega$,

$$\lim_{r \to 0} \oint_{B_r(x_0)} |d(x) - d(x_0)| \, dx = 0, \tag{1}$$

$$\lim_{r \to 0} \oint_{B_r(x_0)} |\sigma(x) - \sigma(x_0)|^q \, dx = 0, \tag{2}$$

$$\lim_{r \to 0} \frac{1}{r} \left\{ f_{B_r(x_0)} |v(x) - v(x_0) - Dv(x_0)(x - x_0)|^{p^*} dx \right\}^{1/p^*} = 0.$$
(3)

Fix such a point x_0 , let $\psi \in C_0^{\infty}(B_1)$, $\psi \ge 0$, $\int_{\mathbf{R}^n} \psi(y) dy = 1$ and let $\psi_r(x) = r^{-n} \psi(\frac{x-x_0}{r})$. By (1)

$$\lim_{r \to 0} d(\psi_r) = \lim_{r \to 0} \int \psi_r(x) d(x) \, dx = d(x_0). \tag{4}$$

On the other hand letting

$$P(x) = v(x_0) + Dv(x_0)(x - x_0),$$

and writing B_r instead of $B_r(x_0)$ we have

$$d(\psi_r) = -\int_{\Omega} (\psi_r)_{,j}(x)v(x)\sigma^j(x) \, dx$$

= $-\int_{B_r} (\psi_r)_{,j}(x)(v(x) - P(x))\sigma^j(x) \, dx - \int_{B_r} (\psi_r)_{,j}P(x)\sigma^j(x) \, dx$

$$= -\int_{B_{r}} (\psi_{r})_{,j}(x)(v(x) - P(x))\sigma^{j}(x) dx + \int_{B_{r}} \psi_{r}(x) Dv(x_{0}).\sigma(x) dx$$

$$= -\int_{B_{r}} (\psi_{r})_{,j}(x)(v(x) - P(x))\sigma^{j}(x) dx + \int_{B_{r}} \psi_{r}(x) Dv(x_{0}).(\sigma(x) - \sigma(x_{0})) dx$$

$$+ \int_{B_{r}} \psi_{r}(x) Dv(x_{0}).\sigma(x_{0}) dx.$$
(5)

The last term is of course nothing but $Dv(x_0).\sigma(x_0)$. The first term in the last expression is bounded by

$$r^{-n-1}\sup|D\psi|\int_{B_r}|v(x)-P(x)||\sigma(x)|\,dx,$$

which by Hölder's inequality can be estimated by

$$\frac{C}{r} \left\{ \oint_{B_r} |v(x) - P(x)|^{p^*} dx \right\}^{1/p^*} \left\{ \oint_{B_r} |\sigma(x)|^q dx \right\}^{1/q}$$

and thus converges to zero as $r \to 0$ by (2) and (3). Finally, the second term in the last identity in (5) is bounded by

$$C|Dv(x_0)| \int_{B_r} |\sigma(x) - \sigma(x_0)| dx$$

and therefore converges to zero as $r \to 0$ by (2). It follows that

$$\lim_{r \to 0} d(\psi_r) = Dv(x_0).\sigma(x_0). \tag{6}$$

It should be noted that the derivation of (6) only depends on the assumptions on v and σ and not on the hypothesis $d \in L^1$. The theorem (for div $\sigma = 0$) now follows from (4) and (6).

Proof of Theorem 1 (general case). - Since div $\sigma \in L^1$ we may assume that in addition to (1) to (3) we also have

$$\lim_{r \to 0} \oint_{B_r(x_0)} \left| \operatorname{div} \sigma(x) - \operatorname{div} \sigma(x_0) \right| \, dx = 0. \tag{7}$$

The only difference in the case div $\sigma \neq 0$ is that in (5) an additional term

$$\int_{B_r} \psi_r(x) P(x) (\operatorname{div} \sigma)(x) \, dx$$



appears. This term may be rewritten as

$$\int_{B_r} \psi_r(x) (P(x) - P(x_0))(\operatorname{div} \sigma)(x) \, dx + \int_{B_r} \psi_r(x) P(x_0)(\operatorname{div} \sigma(x) - \operatorname{div} \sigma(x_0)) \, dx \\ + \int_{B_r} \psi_r(x) P(x_0)(\operatorname{div} \sigma)(x_0) \, dx$$

The last term is just $v(x_0) \operatorname{div} \sigma(x_0)$, the first term is bounded by

$$C|Dv(x_0)|r \oint_{B_r} |\operatorname{div} \sigma|(x) \, dx,$$

and the second by

$$C|v(x_0)| \oint_{B_r} |\operatorname{div} \sigma(x) - \operatorname{div} \sigma(x_0)| dx,$$

and in view of (7) both terms converge to zero as $r \to 0$. Thus

$$\lim_{r \to 0} d(\psi_r) = Dv(x_0) \cdot \sigma(x_0) + v(x_0) \operatorname{div} \sigma(x_0), \tag{8}$$

and the theorem follows from (4).

Proof of Remark 2. - If d is a Radon measure and d_{reg} its regular part then, by the differentiability theorem for measures (see, e.g. [5, Thm. 8.6]),

$$\lim_{r \to 0} d(\psi_r) = d_{reg}(x_0)$$

for a.e. x_0 , and the remark follows from (8).

References

- J.M.Ball, Convexity conditions and existence theorems in nonlinear elasticity, Arch. Rat. Mech. Anal., 63, 1977, pp. 337-403.
- [2] C.B.Morrey, Multiple integrals in the calculus of variations, Springer, Berlin-New York, 1966.
- [3] A.P.Calderon and A.Zygmund, Local properties of solutions of elliptic partial differential equations, *Studia Math.*, **20**, 1961, pp. 171–225.
- [4] W.P.Ziemer, Weakly differentiable functions, Springer, Berlin-New York, 1989.
- [5] W.Rudin, Real and complex analysis, McGraw Hill, New York, 1974.

: