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Jacobians and Hardy Spaces

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Research Report No. 91-NA-001

May 1991

**Center for
Nonlinear Analysis**

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Introduction

We wish to illustrate here the links between various nonlinear quantities identified by the compensated—compactness method (L. Tartar [9],[10]), F. Murat [6],[7]) and the Hardy spaces. A systematic study of this matter can be found in R. Coifman, P. L. Lions, Y. Meyer and S. Semmes [3], and we want to illustrate it on the particular example of the Jacobian.

More precisely, we consider $J(u) = \det(\nabla u)$ when $u \in W^{1,p}(\mathbb{R}^N)^N$ for some $p \in [1,\infty[$ where $N \geq 2$. This quantity clearly makes sense in $L^1(\mathbb{R}^N)$ if $p=N$; however, in that case, there are various reasons to guess that $J(u)$ might be slightly better than L^1 . First of all, it is a classical fact that J is weakly sequentially continuous on $W^{1,N}(\mathbb{R}^N)^N$ — this fact is one of the key ingredients in J. Ball's theory of polyconvex functionals in Nonlinear Elasticity [1]. Next, several results by H. Wente [12], L. Tartar [11] indicate that L^1 is not optimal — see also H. Brézis and J. M. Coron [2]. Finally, the last piece of evidence is a striking recent result due to S. Müller [4] showing that if $u \in W_{loc}^{1,N}(\mathbb{R}^N)^N$ and $J(u) \geq 0$ a.e., then $J(u) \log(1+J(u)) \in L_{loc}^1(\mathbb{R}^N)$.

We will show below in Section 2 how all these results can be recovered from the following statement: $J(u) \in \mathcal{H}^1(\mathbb{R}^N)$ if $u \in W^{1,N}(\mathbb{R}^N)^N$. Here and everywhere below, we denote by $\mathcal{H}^p(\mathbb{R}^N)$ the following Hardy spaces:

$$(1) \quad \mathcal{H}^p(\mathbb{R}^N) = \{f \in S'(\mathbb{R}^N) / \sup_{t>0} |h_t * f| \in L^p(\mathbb{R}^N)\}, p > 0,$$

where h_t is a regularization kernel satisfying, for example

$$(2) \quad h_t = \frac{1}{t^N} h\left(\frac{\cdot}{t}\right), h \in \mathcal{D}(\mathbb{R}^N), 0 \leq h \text{ on } \mathbb{R}^N, \text{Supp } h \subset B_1,$$

where we denote by B_λ the open ball of radius λ and by $B_\lambda(x) = B(x, \lambda)$ the open ball centered at x of radius λ ($B_\lambda = B_\lambda(0) = B(0, \lambda)$). We shall see in fact that $J(u) \in \mathcal{H}^p(\mathbb{R}^N)$ if $u \in W^{1,pN}(\mathbb{R}^N)^N$, $\frac{N}{N+1} < p \leq 1$ and that $J(\nabla\phi) = \det(D^2\phi) \in \mathcal{H}^p(\mathbb{R}^N)$ if $\phi \in W^{2,pN}(\mathbb{R}^N)^N$, $\frac{N}{N+2} < p \leq 1$. Of course, one has to interpret $J(u)$ or $J(\nabla\phi)$ in a distribution sense explained below when $p < 1$.

We present in Section 3 a proof of these facts. To simplify the presentation and the notations we restrict our attention here to the case when $N = 2$.

2. Main results and consequences.

Of course, if $u \in W^{1,2}(\mathbb{R}^2)^2$, $J(u) = \det(\nabla u) \in L^2(\mathbb{R}^2)$. But, one easily checks that

$$(3) \quad J(u) = \partial_1(u_1 \partial_2 u_2) - \partial_2(u_2 \partial_1 u_1) \text{ in } \mathcal{D}'(\mathbb{R}^2),$$

and this last expression is well-defined (in the sense of distributions) whenever $u \in W^{1, \frac{4}{3}}(\mathbb{R}^2)^2$: indeed, one then deduces from Sobolev embeddings that $u \in L^4(\mathbb{R}^2)^2$ and thus $|u| |\nabla u|$ is integrable.

Next, if $u = \nabla \phi$, further cancellations of $J(u)$ take place and we may write

$$(4) \quad J(\nabla \phi) = -\frac{1}{2} \partial_1^2 ((\partial_2 \phi)^2) - \frac{1}{2} \partial_2^2 ((\partial_1 \phi)^2) + \partial_{12}^2 (\partial_1 \phi \partial_2 \phi) \text{ in } \mathcal{D}'(\mathbb{R}^2)$$

or

$$(5) \quad J(\nabla \phi) = \frac{1}{2} \partial_1^2 (\phi \partial_2^2 \phi) + \frac{1}{2} \partial_2^2 (\phi \partial_1^2 \phi) - \partial_{12}^2 (\phi \partial_{12}^2 \phi) \text{ in } \mathcal{D}'(\mathbb{R}^2).$$

Note that (4) makes sense as soon as $\phi \in W^{1,2}(\mathbb{R}^2)$ while (5) makes sense if $\phi \in W^{2,1}(\mathbb{R}^2)$ (since it implies $\phi \in C_0(\mathbb{R}^2)$). In fact, the two expressions are easily shown to be equal if $\phi \in W^{2,1}(\mathbb{R}^2)$ since $W^{2,1}(\mathbb{R}^2)$ embeds into $W^{1,2}(\mathbb{R}^2)$ and $\partial_j(\phi \partial_j \phi) = \phi \partial_j^2 \phi + (\partial_j \phi)^2$ ($\forall j$), $\partial_1 \phi \partial_2 \phi + \phi \partial_{12}^2 \phi = \frac{1}{2} \partial_1 (\phi \partial_2 \phi) + \frac{1}{2} \partial_2 (\phi \partial_1 \phi)$. Notice, finally, that by Sobolev embeddings, (4) makes sense if $\phi \in \bar{W}^{2,1}(\mathbb{R}^2) = \{\phi \in W^{1,1}(\mathbb{R}^2) / \partial_{i,j}^2 \phi \text{ is a bounded measure on } \mathbb{R}^2(\forall_{i,j})\}$.

We may now state our main results:

Theorem 1: Let $p \in (\frac{4}{3}, 2]$ and let $u \in W^{1,p}(\mathbb{R}^2)^2$, then $J(u) \in \mathcal{S}^{p/2}(\mathbb{R}^2)$.

Theorem 2: Let $p \in (1,2]$ and let $\phi \in W^{2,p}(\mathbb{R}^2)$, then $J(\nabla\phi) \in \mathcal{S}^{p/2}(\mathbb{R}^2)$.

Remarks: 1) These results also hold locally.

2) The borderline cases $p = \frac{4}{3}$ or $p = 1$ can also be studied – see also section 3 below.

3) One recovers immediately S. Müller's result [4] from Theorem 1 since if $f \in L^1_{loc}$, $f \geq 0$ a.e. then $f \in \mathcal{S}^1_{loc}(\mathbb{R}^N)$ if and only if $f \log(1+f) \in L^1_{loc}$ (see E. Stein [8]).

4) Observing that $\mathcal{S}^1(\mathbb{R}^2) \in W^{-1,2}(\mathbb{R}^2)$, one deduces that $W = (-\Delta)^{-1} J(u) \in W^{1,2}(\mathbb{R}^2)$ and $J(u) \in W^{-1,2}(\mathbb{R}^2)$ if $u \in W^{1,2}(\mathbb{R}^2)^2$. Furthermore, in that case, one sees that $\partial_{i,j} W \in \mathcal{S}^1(\mathbb{R}^2)$ ($\forall_{i,j}$) and this yields: $W \in \mathcal{S}L^1(\mathbb{R}^2)$. We recover in this way the results mentioned in the Introduction.

5) One can define a linear continuous map P from $\mathcal{S}^q(\mathbb{R}^N)$ into $L^q(\mathbb{R}^N)$ for $0 < q < 1$ which consists in taking the "a. e. part" of a distribution f in $\mathcal{S}^q(\mathbb{R}^N)$: more precisely, $Pf = \lim_{t \rightarrow 0} \text{a.e. } h_t * f$. Of course, $Pf = f$ if $f \in \mathcal{S}^1$ or L^1 and Pf is the regular part of f if f is a bounded measure.

Next, one remarks that when $p < 2$, one can also define a.e. $\det(\nabla u)$ or $\det(D^2\phi)$ obtaining thus a measurable function which lies obviously in $L^{p/2}$. We denote by $\text{Det}(\nabla u)$ or $\text{Det}(D^2\phi)$ these functions. Then, the above results yield easily: $\text{Det}(\nabla u) = P(J(u))$,
 $\text{Det}(D^2\phi) = P(J(\nabla\phi))$.

These relations yield and extend another recent result of S. Müller [5].

3 Proofs

Theorems 1 – 2 follow immediately from the following lemma and the classical maximal theorem:

Lemma 3: 1) Let $u \in W^{1,4/3}(\mathbb{R}^2)$; then we have for all $t > 0$, $x \in \mathbb{R}^2$

$$(6) \quad |h_t * J(u)| \leq C_0 \left(\int_{B(x,t)} |Du|^{4/3} dx \right)^{3/2}.$$

(2) Let $\phi \in W^{2,1}(\mathbb{R}^2)$; then we have for all $t > 0$, $x \in \mathbb{R}^2$

$$(7) \quad |h_t * J(\nabla\phi)| \leq C_0 \left(\int_{B(x,t)} |D^2\phi| dx \right)^2.$$

Remarks:

1) Here and everywhere below, C_0 denotes various constants independent of t , x , u , ϕ .

2) The estimate (7) is still true for $\phi \in \bar{W}^{2,1}$ provided we define $J(\nabla\phi)$ by (4) and the right hand side is replaced by the total mass of the measure $\sum_{i,j} \left| \frac{\partial^2 \phi}{\partial x_i \partial x_j} \right|$ on the ball $B(x,t)$.

3) Those estimates allow, in fact, to investigate the borderline cases $p = \frac{4}{3}$ or $p = 1$.

Proof of Lemma 3: We begin with Part 1). Using (3) and integrating by parts, we find

$$(8) \quad h_t * J(u) = \int u_1(y) [\partial_2 u_2(y) \frac{1}{t^3} \partial_1 h(\frac{x-y}{t}) - \partial_1 u_2(y) \frac{1}{t^3} \partial_2 h(\frac{x-y}{t})] dy.$$

But, clearly, these expressions are left invariant if we subtract constants from u_1 and u_2 .

Therefore, in particular, we have, denoting by $\int_{B(x,t)} u = \frac{1}{|B(x,t)|} \int_{B(x,t)} u(y) dy$,

$$(9) \quad h_t * J(u) = \int \frac{1}{t} (u_1 - \int_{B(x,t)} u_1) [\partial_2 u_2(y) \frac{1}{t^2} \partial_1 h(\frac{x-y}{t}) - \partial_1 u_2(y) \frac{1}{t^2} \partial_2 h(\frac{x-y}{t})] dy.$$

We now apply Hölder's inequality to find

$$(10) \quad |h_t * J(u)| \leq C_0 \left(\int_{B(x,t)} |\frac{1}{t} (u_1 - \int_{B(x,t)} u_1)|^4 dy \right)^{1/4} \left(\int_{B(x,t)} |Du|^{4/3} dy \right)^{3/4}.$$

And we obtain (6) by recalling the Sobolev–Poincaré's inequality

$$(11) \quad \left(\int_{B(x,t)} \frac{1}{t} (u_1 - \int_{B(x,t)} u_1) \right)^4 dy \leq C_0 \left(\int_{B(x,t)} |Du|^{4/3} dy \right)^{3/4}.$$

We now turn to part 2), which is proven in a similar way using either (4) or (5): we use for instance (4) and obtain as above

$$(12) \quad h_t * J(\nabla \phi) = -\frac{1}{2} \int (\partial_2 \phi(y))^2 \frac{1}{t^4} \partial_1^2 h(\frac{x-y}{t}) dy + \\ -\frac{1}{2} \int (\partial_1 \phi(y))^2 \frac{1}{t^4} \partial_2^2 h(\frac{x-y}{t}) dy + \int \partial_1 \phi(y) \partial_2 \phi(y) \frac{1}{t^4} \partial_{12}^2 h(\frac{x-y}{t}) dy.$$

Then we observe that this quantity is left invariant if we add to ϕ an arbitrary affine function so that, in other words, we may subtract respectively from $\partial_1\phi, \partial_2\phi$ the following quantities

$$\int_{B(x,t)} \partial_1\phi, \quad \int_{B(x,t)} \partial_2\phi.$$

We then find

$$(13) \quad |h_t * J(\nabla\phi)| \leq C_0 \int_{B(x,t)} \left| \frac{1}{t} \left\{ \nabla\phi - \int_{B(x,t)} \nabla\phi \right\} \right|^2 dy,$$

and we conclude again by Sobolev–Poincaré’s inequality:

$$\int_{B(x,t)} \left| \frac{1}{t} \left\{ f - \int_{B(x,t)} f \right\} \right|^2 dy \leq C_0 \left(\int_{B(x,t)} |Df| dy \right)^2, \text{ for all } f \in W^{1,1}(\mathbb{R}^2).$$

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