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# NEMITSKY OPERATORS ON SOBOLEV SPACES 

## by

M. Marcus and V. J. Mizel ${ }^{l}$

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Introduction. The present paper deals with situations in which a function $g\left(\underset{\sim}{x}, t_{l}, \ldots, t_{m}\right)$ provides, via composition, a mapping ("Nemitsky operator") between Sobolev spaces. That is, we take $g$ to be a function satisfying "Caratheodory conditions" and we analyze circumstances under which for every system of functions $u_{1}, \ldots, u_{m} \in W_{1, q}(\Omega)$, where $W_{1, q}(\Omega)$ is the class of $L_{q}$ functions with $L_{q}$ summable strong first derivatives on the domain $\Omega \subset R_{n}$, the composite function given by $v(\underset{\sim}{x})=g\left(\underset{\sim}{x}, u_{1}(\underset{\sim}{x}), \ldots, u_{m}(\underset{\sim}{x})\right)$ belongs to $\mathrm{w}_{1, \mathrm{p}}{ }^{(\Omega)}$, with preassigned $1 \leq \mathrm{p}<\infty$. We suppose in addition to the Caratheodory conditions that, roughly speaking, $g$ is locally absolutely continuous on lines in $R_{m}$ parallel to the axes and has a similar but weaker property for lines in $\Omega$. This implies in some sense that the partial derivatives of $g$ exist almost everywhere in $\Omega \times R_{m}$, and in our hypotheses one prescribes for each of these partial derivatives a function of an appropriate kind which dominates it almost everywhere. Then whenever $u_{1}, \ldots, u_{m}$ are such that their composites with the dominating functions lie in appropriate $\mathrm{L}_{\mathrm{r}}(\Omega)$ spaces, it is shown that $v$ lies in $W_{1, p}(\Omega)$. (We remark that the analysis
for the case $p=1$ is considerably more complex than when p > 1.)

The above results are quite different from those usually studied with Nemitsky operators since such operators are generally examined only on spaces, such as the $L_{r}(\Omega)$ spaces, which are normal lattices of measurable functions ([10],[11]). These results should be of interest in the study of partial differential equations which involve nonlinear functions satisfying weak smoothness requirements.

In an earlier paper ([12]) we have likewise analyzed situations in which a function $g$ provides a mapping between Sobolev spaces. The methods of that paper are quite different from those used here and are restricted to situations in which a chain rule is available for the partial derivatives of $v$. Moreover, there the chain rule was an essential ingredient in determining when a function $g$ provides a mapping of the desired kind, while in the present paper a chain rule is generally not valid for the situations under study.

The approach we follow here relies heavily on a characterization of the spaces $W_{1, q}(\Omega)$ due to Gagliardo [6], Morrey [14] and Calkin [3]. It also utilizes a theorem of Hardy-Littlewood [ 8 ] on difference quotients under translation, as well as certain classical results of Tonelli [15, p. 123] on absolutely
continuous curves.
The plan of the paper is as follows. Section 1 is devoted to preliminaries. Section 2 deals with the basic problem for the case $p>1$. Section 3 extends these results to the case $p=1$. Section 4 analyzes continuity properties of the Nemitsky operators for the case $p>1$. Finally in Section 5, by restricting attention to the particular case of functions $g$ which are independent of $\underset{\sim}{x} \in \Omega$ and by strengthening our previous conditions, we obtain a chain rule for the partial derivatives of $v$.

## §1. Preliminaries

The following notations will be used in this paper.
A point in the Euclidean space $R_{n}$ will hereafter be denoted by $\mathrm{x}=\left(\mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{n}}\right)$; the Euclidean norm will be denoted by $|\cdot| \cdot$ We shall denote by $\mathfrak{L}_{k}$, k-dimensional Lebesgue measure and by $f_{k}, k$-dimensional Hausdorff measure. We shall use the same symbol for an equivalence class of functions (relative to Lebesgue measure) as for a representative of that class. The meaning will be clear from context.

If $f$ is a real function defined in a domain $\Omega$ in $R_{n}$, we denote by $\frac{\partial f}{\partial x_{k}}$ the classical partial derivative (with respect to $\mathrm{x}_{\mathrm{k}}$ ), wherever it exists; and we denote by $\partial_{\mathrm{x}_{\mathrm{k}}} \mathrm{f}$ the
distribution derivative (with respect to $X_{k}$ ) of $f$ in $\Omega$, whenever it is meaningful.

By $C^{k}(\Omega)$ we denote, as usual, the class of real functions which are continuous and possess continuous derivatives, up to order $k$, in $\Omega$. The subspace of $C^{k}(\Omega)$ consisting of those functions whose support is a compact subset of $\Omega$ will be denoted by $C_{o}^{k}(\Omega)$. The class of real functions $\{f\}$ such that $f$ is Lipschitz in $\Omega$ will be denoted by Lip( $\Omega$ ); the class of real functions $\{f\}$ such that $f$ is Lipschitz in every compact subset of $\Omega$ will be denoted by $\operatorname{Lip}^{l o c}(\Omega)$. Finally, we denote by $L_{p}(\Omega)$ the class of real functions $\{f\}$ which are Lebesgue $p$ summable in $\Omega$. The class of functions $\{f$ \} which belong to $L_{p}\left(\Omega^{1}\right)$ for every bounded domain $\Omega^{\prime}$ such that $\overline{\Omega^{1}} \subset \Omega$, will be denoted by $L_{p}^{\text {loc }}(\Omega)$. The standard norm in $L_{p}(\Omega)$ will be denoted by $\|\cdot\|_{L_{p}(\Omega)}$.

A real function $f$ defined on an open subset $O$ of the real line $R_{1}$, is said to be locally absolutely continuous (or l.a.c.) on $O$, if it is absolutely continuous on every compact subinterval of 0 . Similarly, $f$ is said to be locally of bounded variation (or l.b.v.) on $O$, if it is of bounded variation on every compact subinterval of $O$. If $O=\bigcup_{n=1}^{\infty} I_{n}$, where $\left\{I_{n}\right\}$ is a family of disjoint open intervals, we denote:
(1.1) tot. var. ${ }_{\mathrm{O}}[f]=\sum_{1}^{\infty}$ tot. var. ${ }_{I_{\mathrm{n}}}$ [f],
which may be finite or infinite.
In this paper, such notions, as "null set" and "almost everywhere", will always refer to the measure $\mathcal{E}_{\mathrm{n}}$, except when another measure is specified.

We bring now a number of preliminary results that will be needed in the following sections.

If $f$ is any real function defined on an interval $I$ on the real line, it is known that the domain of existence of $f^{\prime}$ is an $\mathcal{L}_{1}$-measurable set and $f^{\prime}$ is an $\mathscr{L}_{1}$-measurable function on this domain. Moreover if $f$ is Borel measurable, then $f$ f is Borel measurable. (See Saks [15], p. 112-113.)

For functions in more than one variable we have the following two results:

Lemma 1.1. Let $f$ be a real function defined in a domain $\Omega$ in $R_{n}$. If $f$ is Borel measurable, then the domains of existence of each of the derivatives $\frac{\partial f}{\partial x_{j}},(j=1, \ldots, n)$, are Borel sets, and the derivatives are Borel functions on their respective domains.

For proof, see Marcus and Mizel [12, Lemma 4.l].

Lemma 1.2. Let $f$ be a real measurable function in a domain $\Omega$ in $R_{n}$. Suppose that $f$ is continuous on almost every line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis (where i is a fixed index). Then the domain of existence of $\frac{\partial f}{\partial x_{i}}$ is measurable and $\frac{\partial f}{\partial x_{i}}$ is a measurable function on this domain.

This result is probably known, but we have not been able to locate any reference for it. Therefore, we present a proof below. If instead of considering the standard derivative $\frac{\partial f}{\partial x_{i}}$ one considers approximate partial derivatives, then results on their measurability may be found for instance in Saks [15] and Federer [5]. Actually, a result that is stronger than Lemma 1.2 (it assumes only that $f$ is measurable) is stated in Haslam-Jones and Burkill [ 2 ], but their proof contains a serious gap. Before we proceed with the proof of the lemma, we introduce a notation that will be useful in this proof and elsewhere. For any function $f$ we denote:

$$
\begin{equation*}
\delta_{h}^{i} f(x)=\frac{l}{h}\left[f\left(x+h e^{i}\right)-f(x)\right], \quad(h \neq 0), \tag{1.2}
\end{equation*}
$$

where $e^{i}=\left(\delta_{i, l}, \ldots, \delta_{i, n}\right)$.

Proof of Lemma 1.2. Let $\bar{D}_{i} f$ [resp. $\left.\underline{D}_{i} f\right]$ denote the upper [resp. the lower] derivative of $f$ in the $x_{i}$-direction. It is sufficient to show that both of these extreme derivatives are
measurable. Indeed, if this is shown, then the domain of existence of $\frac{\partial f}{\partial x_{i}}$ is precisely the set where $\bar{D}_{i} f-\underline{D}_{i} f=0$, which is measurable; on this set $\frac{\partial f}{\partial x_{i}}$ coincides with the measurable function $\bar{D}_{i} f$.

$$
\begin{gather*}
\text { By definition } \bar{D}_{i} f(x)=\underset{h}{\lim } \sup _{o} \delta_{h}^{i} f(x) \text {. We also define: } \\
\bar{D}_{i}^{r a t .} f(x)=\underset{r}{\lim \sup _{o} \delta_{r}^{i} f(x),} \tag{1.3}
\end{gather*}
$$

where $r$ is restricted to the rational numbers. Clearly, $\overline{D_{i}^{r a t .}} \mathrm{f}_{\mathrm{i}}$, being the lim sup of a countable family of measurable functions, is itself a measurable function in $\Omega$. If we similarly define $\underline{D}_{i}^{\text {rat. }} \mathrm{f}$ (with lim sup replaced by lim inf), then by the same token, $\underline{D}_{i}^{\text {rat. }}{ }_{f}$ is measurable in $\Omega$. Let $A$ be the set where $\bar{D}_{i}^{r a t}{ }_{f}=$ $\underline{D}_{i}^{\text {rat. }}$ f. In $A$ we define $\bar{D}_{i}^{r a t}{ }_{f}=D_{i}^{r a t .}{ }_{f}$. Then $A$ is a measurable set and $D_{i}^{\text {rat. }} f$ is measurable on $A$. If $B$ denotes the domain of existence of $\frac{\partial f}{\partial x_{i}}$, then clearly $B \subseteq A$ and $\frac{\partial f}{\partial x_{i}}=D_{i}^{r a t}{ }_{f}$ in $B$. We shall show that $A-B$ is a null set, thereby proving the assertion of the lemma.

Let $\tau$ be a line parallel to the $x_{i}$-axis such that $f$ is continuous on $\tau \cap \Omega$. We shall show that $A \cap \tau=B \cap \tau$. Let $x \in A \cap \tau$ and let $\left\{h_{\nu}\right\}_{l}^{\infty}$ be any sequence of numbers tending to zero, such that $h_{\nu} \neq 0,(\nu=1,2, \ldots)$. We may assume that the sequence of points $\left\{x+h_{\nu} e^{i}\right\}_{1}^{\infty}$ is contained in a
compact subinterval of $\tau \cap \Omega$. Choose a sequence of rational numbers $\left\{r_{\nu}\right\}_{l}^{\infty}$ such that $\lim r_{\nu} / h_{\nu}=1$ and such that $\left|f\left(x+r_{\nu} e^{i}\right)-f\left(x+h_{\nu} e^{i}\right)\right| \leq h_{\nu} / \nu$. (Here we use the continuity of $f$ on $\tau \cap \Omega$.) Then:

$$
\begin{align*}
\lim _{\nu} \delta_{h_{\nu}}^{i} f(x) & =\lim _{\nu}\left[\frac{r_{\nu}}{h_{\nu}} \delta_{r_{\nu}}^{i} f(x)+\frac{f\left(x+h_{\nu} e^{i}\right)-f\left(x+r_{\nu} e^{i}\right)}{h_{\nu}}\right]  \tag{1.4}\\
& =\lim _{\nu} \delta_{\delta_{\nu}^{i}}^{i} f(x)=D_{i}^{r a t} f(x) .
\end{align*}
$$

It follows from (1.4) that $A \cap \tau=B \cap \tau$. Since this holds for almost every line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis, it follows that A - B is a null set, and the proof is complete.

Corollary 1.1. Let $f$ have the properties stated in the lemma. If, for almost every line $\tau$ parallel to the $x_{i}$-axis, $\frac{\partial f}{\partial x_{i}}$ exists $\mathscr{L}_{1}$ - a.e. on $\tau \cap \Omega$, then $\frac{\partial f}{\partial \mathrm{x}_{\mathrm{i}}}$ exists a.e. in $\Omega$ and is measurable. By Fubini's theorem, this is an immediate consequence of the lemma.

Definition 1.1. Let $\Omega$ be a domain in $R_{n}$. We denote by $A_{i}(\Omega)$ the class of functions $\{f\}$ such that:
(i) $f$ is a real measurable function in $\Omega$.
(ii) For almost every line $\tau$ parallel to the $x_{i}$-axis,

$$
\mathrm{f} \text { is l.a.c. on } \tau \cap \Omega \text {. }
$$

The intersection ${ }_{n}^{n} A_{i}(\Omega)$ will be denoted by $A(\Omega)$. The class of functions $\{f\}$ such that $f$ coincides a.e. in $\Omega$ with a function $\tilde{f}$ in $A_{i}(\Omega)$ [resp. $\left.A(\Omega)\right]$ will be denoted by $A_{i}^{\prime}(\Omega) \quad\left[r e s p . A^{\prime}(\Omega)\right]$.

Finally, suppose that condition (ii) is replaced by:
(ii)' For almost every line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis, f is continuous and $1 . \mathrm{b} . \mathrm{v}$. on $\tau \cap \Omega$.

Then, the spaces corresponding to $A_{i}, A_{i}^{\prime}, A, A^{\prime}$ will be denoted by $B_{i}, B_{i}^{\prime}, B, B^{\prime}$ respectively. Note that $A_{i} \subset B_{i}, A_{i}^{\prime} \subset B_{i}^{\prime}$, etc. Remark 1.1. By Corollary 1.1, if $f \in B_{i}(\Omega)$, then $\frac{\partial f}{\partial x_{i}}$ exists a.e. in $\Omega$ and is measurable.

Definition 1.2. Let $f \in B_{i}^{\prime}(\Omega)$ and let $\tilde{f} \in B_{i}(\Omega)$ such that $\tilde{f}=f$ a.e. in $\Omega$. We denote by $\partial_{x_{i}}^{\prime} f$ the equivalence class of measurable functions in $\Omega$ which contains the function $\frac{\partial \tilde{f}}{\partial \mathrm{x}_{i}}$. Then $\partial_{X_{i}} f$ will be called the strong approximate derivative of $f$ with respect to $x_{i}$. We note that if $\widetilde{\mathrm{f}}_{1}, \widetilde{\mathrm{f}}_{2} \in \mathrm{~B}_{\mathrm{i}}(\Omega)$ and $\tilde{\mathrm{f}}_{1}=\widetilde{\mathrm{f}}_{2}$ abe. in $\Omega$, then $\frac{\partial \tilde{f}_{1}}{\partial \mathrm{x}_{\mathrm{i}}}=\frac{\partial \tilde{\mathrm{f}}_{2}}{\partial \mathrm{x}_{\mathrm{i}}}$ a.e. in $\Omega$.

Lemma 1.3. Suppose that $f \in L_{l}^{l o c}(\Omega) \cap A_{i}^{\prime}(\Omega)$. If $\partial_{X_{i}} f \in L_{l}^{l o c}(\Omega)$, then

$$
\begin{equation*}
\partial_{x_{i}}^{\prime} f=\partial_{x_{i}} f \quad \text { are. in } \Omega . \tag{1.5}
\end{equation*}
$$

Proof. Let $\tilde{f} \in A_{i}(\Omega)$ such that $\tilde{f}=f$ are. in $\Omega$. Let $\varphi \in C_{o}^{\infty}(\Omega)$. If $\tau$ is a line parallel to the $x_{i}$-axis, such that $\tilde{f}$ is l.a.c. on $\tau \cap \Omega$, we have:

$$
\int_{\tau \cap \Omega} \frac{\partial \tilde{f}}{\partial \mathrm{x}_{i}} \cdot \varphi d \mathrm{x}_{i}=-\int_{\tau \cap \Omega} \underset{\mathrm{f}}{ } \frac{\partial \varphi}{\partial \mathrm{x}_{i}} \mathrm{dx} \mathrm{x}_{\mathrm{i}}
$$

Hence, by Fubini's theorem:

$$
\int_{\Omega} \frac{\partial \tilde{\mathrm{f}}}{\partial \mathrm{x}_{\mathrm{i}}} \varphi \mathrm{dx}=-\int_{\Omega} \underset{\mathrm{f}}{\tilde{\mathrm{f}}} \frac{\partial \varphi}{\partial \mathrm{x}_{\mathrm{i}}} \mathrm{dx}=-\int_{\Omega} \mathrm{f} \frac{\partial \varphi}{\partial \mathrm{x}_{i}} \mathrm{dx}
$$

which proves the assertion of the lemma.

We denote by $W_{k, p}{ }^{(\Omega)} \quad(k \quad a \operatorname{positive}$ integer; $p \geq 1)$, the Sobolev space of real functions $\{f\}$ such that $f$ and its distribution derivatives up to order $k$, belong to $L_{p}(\Omega)$. This space is provided with the standard norm:

$$
\|f\|_{W_{k, p}(\Omega)}=\sum_{|\alpha| \leq k}\left\|\partial_{x}^{\alpha} f\right\|_{L_{p}(\Omega)},
$$

where $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right), \quad 0 \leq \alpha_{j}$ is an integer $(j=1, \ldots, n)$, $|\alpha|=\alpha_{1}+\ldots+\alpha_{n}$ and $\partial_{x}^{\alpha_{f}}=\partial_{x_{1}}^{\alpha_{1}} \ldots \partial_{x_{n}}^{\alpha_{n^{\prime}}}$.

The space of functions $\{f\}$ such that $f \in W_{k, p}\left(\Omega^{1}\right)$ for every bounded domain $\Omega^{r}$ such that $\bar{\Omega} \subset \Omega$ is denoted by $W_{k, p}^{l o c}(\Omega)$. The product space $\mathrm{W}_{\mathrm{k}, \mathrm{p}_{1}}(\Omega) \times \ldots \times \mathrm{W}_{\mathrm{k}, \mathrm{p}_{\mathrm{m}}}(\Omega)$ will be denoted
by $\underset{k, \tilde{p}^{(\Omega)}}{ }$, where $\tilde{p}=\left(p_{1}, \ldots, p_{m}\right)$.
The following characterization of $W_{1, p}(\Omega),(1 \leq p)$, is due to Gagliardo [6]. (Most of the essential features of this result (at least in local form) are also contained in the papers of Calkin [ 3 ] and Morrey [14].)

Lemma 1.4. Let $1 \leq p<\infty$. A function $f$, defined in $\Omega$, belongs to $W_{1, p}(\Omega)$ if and only if:
(i) $f \in A^{\prime}(\Omega)$;
(ii) $\quad \partial_{x_{i}}^{\prime} f \in L_{p}(\Omega), \quad(i=1, \ldots, n) ;$
(iii) $f \in L_{p}(\Omega)$.

Moreover, if $f \in W_{1, p}(\Omega)$ then $\partial_{x_{i}}^{\prime} f=\partial_{x_{i}} f$ a.e. in $\Omega,(i=1, \ldots, n)$.
Finally if $\Omega$ is bounded and has the cone property, then condition (iii) may be omitted.

Remark 1.2. 1. The result was not stated in this form in [6], but is an immediate consequence of Sections 1 and 2 of that paper.
2. As a consequence of this lemma we have the following

## local result:

$f \in W_{1, p}^{l o c}(\Omega)$ if and only if:
(i) $f \in A^{\prime}(\Omega)$;
(ii)' $\partial_{x_{i}} f \in L_{p}^{l o c}(\Omega), \quad i=1, \ldots, n$.
3. If $k>1$, then $W_{k, p}(\Omega)$ may be characterized inductively
by:

$$
\begin{equation*}
f \in W_{k, p}(\Omega) \Longleftrightarrow \partial_{x_{i}} f \in W_{k-1, p}(\Omega) \tag{1.6}
\end{equation*}
$$

The following two results on Sobolev spaces are well known. For proofs see for instance Agmon [ l ] (pp. 42-45). Combined, these results yield an alternative characterization of $W_{1, p}(\Omega)$, for $\quad 1<p<\infty$.

If $\Omega$ is a domain in $R_{n}$ and $\Omega$ a set in $R_{n}$, the notation $\Omega^{\prime} \subset \subset$ means that $\bar{\Omega}$ is a compact subset of $\Omega$. The boundary of $\Omega$ will be denoted by $\partial \Omega$.

Lemma 1.5. Let $f \in W_{1, p}(\Omega)$, where $1 \leq p<\infty$. If $\Omega^{r}$ is an open set such that $\Omega^{r} \subset \subset \Omega$ and if $0<h<d i s t .\left(\Omega^{r}, \partial \Omega\right)$, then:

$$
\begin{equation*}
\left\|\delta_{h}^{i} f\right\|_{L_{p}\left(\Omega^{r}\right)} \leq\left\|\partial_{x_{i}} f\right\|_{L_{p}(\Omega)}, \quad(i=1, \ldots, n) \tag{1.7}
\end{equation*}
$$

Lemma 1.6. Let $f \in L_{p}(\Omega)$, where $1<p<\infty$. Suppose that there exists a number $C$ such that, for every open set $\Omega^{1}$ with $\Omega^{\prime} \subset \subset \Omega$, and for sufficiently small $|\mathrm{h}|:$

$$
\begin{equation*}
\left\|\delta_{h}^{i} f\right\|_{L_{p}\left(\Omega^{\prime}\right)} \leq c \tag{1.8}
\end{equation*}
$$

Then

$$
\partial_{x_{i}} f \in L_{p}(\Omega) \text { and }\left\|\partial_{x_{i}} f\right\|_{L_{p}}(\Omega) \leq C . \quad \text { In particular, if (1.8) }
$$

$$
\text { holds for all } i \text {, }(i=1, \ldots, n) \text {, then } f \in W_{1, p}(\Omega)
$$

Remark. In [ 1 ] these results are stated for $p=2$. But the proofs given there, with only minor modifications, yield also the more general results stated above. The special assumption on $\Omega$, included in the statement of Theorem 3.15 of [1], was made for convenience only and is not really needed (see [1, p. 11]).

The next lemma deals with the situation considered in Lemma 1.6, for the case $p=1$, and $f$ a function of one variable. It is due to Hardy and Littlewood [8].

Lemma 1.7. Let $f \in L_{1}(I)$, where $I$ is an interval on the real line. Suppose that for every compact subinterval of $I$, say $I^{\prime}$, and for every sufficiently small $|\mathrm{h}|$ we have:

$$
\begin{equation*}
\int_{I^{\prime}}|f(\sigma+h)-f(\sigma)| /|h| d \sigma \leq c \tag{1.9}
\end{equation*}
$$

where $C$ is a constant independent of $I$ and $h$. Then $f$ coincides $\mathbb{S}_{1}$ - a.e. in $I$ with a function $\tilde{f}$ of bounded variation such that:

$$
\begin{equation*}
\text { tot. var. }{ }_{I}[\widetilde{\mathrm{f}}] \leq \mathrm{c} \tag{1.10}
\end{equation*}
$$

We shall need also the following two results due to valée Poussin [19]. (Stronger versions of these results were obtained by Serrin and Varberg [17]; their proofs are much simpler than the original proofs of valée poussin.)

Lemma 1.8. Let $s$ be an absolutely continuous real valued function on an interval $I$ of the real line. Let $N$ be an $\mathscr{L}_{1}-$ null set on $R_{1}$ and set $M=s^{-1}(N) \cap I$. Then $s^{\prime}=0$


Lemma 1.9. Let $w$ and $s$ be absolutely continuous real valued functions on intervals $J$ and $I$ respectively. If $s(I) \subset J$ and if $w$ is absolutely continuous in $I$, then:

$$
\left[\begin{array}{lll}
w & \circ & ]^{\prime} \tag{1.11}
\end{array}=\left[w^{\prime} \circ s\right] s^{\prime}, \quad s_{1}-\text { a.e. in } I,\right.
$$

provided that we interpret the right side as zero whenever $s^{\prime}(\sigma)=0$ (even if ( $w^{\prime} 0$ s) ( $\sigma$ ) is undefined or infinite).

Conversely, if with the above convention [ $w^{\prime}$ o s]s'
is summable on $I$, then $w \bullet s$ is absolutely continuous on $I$ and (1.11) holds.

The next result is due to Serrin [16] (unpublished).
For a more general result see Marcus and Mizel [12] (Theorem 4.3).

Lemma 1.10. Let $g: R_{1} \rightarrow R_{1}$ be an l.a.c. function. Suppose that $u \in W_{1, l}^{l o c}(\Omega)$ and set $v=g \circ u$. Then $v \in W_{l, l}^{l o c}(\Omega)$ if and only if the following condition holds:

$$
\begin{equation*}
v_{i}=\left[g^{\prime} 0 u\right] \partial_{x_{i}} u \in L_{l}^{l o c}(\Omega), \quad(i=1, \ldots, n), \tag{1.12}
\end{equation*}
$$

the product being interpreted as zero whenever $\partial_{x_{i}} u=0$.

Moreover, if (1.12) holds we have $v_{i}=\partial_{x_{i}} v$ ale. in $\Omega$, (i $=1, \ldots, n$ ).

For the sake of convenience we give a proof of this lemma. proof. By Lemma 1.4, there exists $\tilde{u} \in A(\Omega)$ such that $\tilde{u}=u$ a.e. in $\Omega$ and $\frac{\partial \tilde{u}}{\partial x_{i}}=\partial_{x_{i}} u$ a.e. in $\Omega$. set $\tilde{v}=g 0 \tilde{u}$.

First we assume that (1.12) holds. Let $\tau$ be a line parallel to the $\mathrm{x}_{\mathrm{i}}$-axis, such that $\tilde{\mathrm{u}}$ is l.a.c. on $\tau \cap \Omega$ and such that $\tilde{v}_{i}=\left[g^{\prime} \circ \tilde{u}\right] \frac{\partial \tilde{u}}{\partial x_{i}} \in L_{1}^{l o c}(\Omega)$. Then by Lemma 1.9, $\tilde{v}$ is 1.a.c. on $\tau \cap \Omega$ and $\frac{\partial \tilde{v}}{\partial \mathrm{x}_{\mathrm{i}}}=\tilde{\mathrm{v}}_{\mathrm{i}} \mathfrak{L}_{1}$-abe. in $\tau \cap \Omega$. Since this holds for almost every line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$ axis $(i=l, \ldots, n)$ it follows that $\tilde{v} \in A(\Omega)$ and that $\frac{\partial \tilde{v}}{\partial x_{i}}=\tilde{v}_{i}$ a.e. in $\Omega$. Hence by (1.12) and Lemma 1.4 (see also Remark 1.2(3)) it follows that $\tilde{v} \in W_{1,1}^{l o c}(\Omega)$.

Now, suppose that $v \in W_{l, l}^{10 C}(\Omega)$. Then $\tilde{v}=g \circ \tilde{u} \in A(\Omega)$. Indeed, $\tilde{v}$ is continuous on $\tau \cap \Omega$, for almost every line $\tau$ parallel to one of the axes and $\tilde{v}=v$ abe. in $\Omega$. Since $\mathrm{v} \in \mathrm{A}^{\prime}(\Omega)$ (by Lemma 1.4) it follows that $\tilde{v} \in \mathrm{~A}(\Omega)$.

If $\tau$ is a line parallel to the $\mathrm{x}_{\mathrm{i}}$-axis such that both $\tilde{u}$ and $\tilde{v}$ are 1.a.c. on $\tau \cap \Omega$, it follows from Lemma 1.9 that:

$$
\frac{\partial \tilde{v}}{\partial x_{i}}=\left[\begin{array}{lll}
g^{\prime} & \circ & \tilde{u}
\end{array}\right] \frac{\partial \tilde{u}}{\partial x_{i}}
$$

Since $\tilde{v} \in W_{l, l}^{l o c}(\Omega)$ this implies (1.12). This completes the proof of the lemma.

Corollary 1.2. If $\Omega$ is bounded and has the cone property, the statement of the lemma is valid also in the case the " $v \in W_{1,1}^{l o c}(\Omega) "$ is replaced by $" v \in W_{1, p}(\Omega) "$ and ${ }^{l} v_{i} \in L_{l}^{l o c}(\Omega) "$ is replaced by $" v_{i} \in L_{p}(\Omega),(1 \leq p<\infty) "$.

This follows immediately by Lemma 1.4.
§2. On a Class of Nemitsky Operators
Let $\Omega$ be a domain in $R_{n}$ and let $g=g(x, \underset{\sim}{t})$ be a real
function defined in $\Omega \times R_{m}$. Here $x=\left(x_{1}, \ldots, x_{n}\right)$ denotes a point in $R_{n}$ and $\underset{\sim}{t}=\left(t_{1}, \ldots, t_{m}\right)$ denotes a point in $R_{m}$. Definition 2.1. A function $g$ as above is called a Caratheodory function if:
(i) For a.e. $x \in \Omega, g(x, \cdot)$ is a continuous function on $R_{m}$.
(ii) For every fixed $\underset{\sim}{t} \in R_{m}, g(\cdot, \underset{\sim}{t})$ is a measurable function in $\Omega$.

With a given Caratheodory function $g$, we associate an operator $G$ defined by:

$$
\underset{\sim}{\operatorname{Gu}}(x)=g(x, \underset{\sim}{u}(x))=(g \circ \underset{\sim}{u})(x)
$$

where $\underset{\sim}{u}=\left(u_{1}, \ldots, u_{m}\right)$ is measurable in $\Omega$. Such an operator $G$ is called a Nemitsky operator.

By a theorem due to Caratheodory [4], if $\underset{\sim}{u}$ is a measurable vector valued function as above, $G \underset{\sim}{u}$ is measurable in $\Omega$. (For the proof see also Vainberg [18], p. 152.)

In this section we consider the following problem:
Given a vector valued function $\underset{\sim}{u} \in \mathbb{W} \underset{\mathcal{q}}{(\Omega)}$, where
$\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$, state conditions on $g$ such that $\underset{\sim}{G} \in W_{1, p}(\Omega)$.
In the theorems that follow we describe a set of rather weak conditions on $g$ which imply this property of the associated operator G.

First we introduce:

Definition 2.2. Let $g$ be a real function defined on $\Omega \times R_{m}$. We shall say that $g$ is an l.a.c. Caratheodory function if:
(i) There exists a null subset of $\Omega$, to be denoted by $N=N_{g}$, such that for every fixed $x \in \Omega-N$ :
(a) $g(x, \cdot)$ is continuous in $R_{m}$;
(b) For every line parallel to one of the axes in $R_{m}, \quad g(x, \cdot)$ restricted to this line is locally absolutely continuous.
(ii) For every fixed $\underset{\sim}{t} \in R_{m}, g(\cdot, t \underset{\sim}{t}) \in A^{\prime}(\Omega)$.

Note that a function $g$ as above is in particular a

Caratheodory function.
With this definition we have:

Theorem 2.1. Let $\Omega$ be a bounded domain in $R_{n}$, possessing the cone property. Let $g$ be an l.a.c. Caratheodory function in $\Omega \times R_{m}$. Let $p>1$ and $\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ where $q_{i} \geq p$. Given certain functions $a, b, a_{i}, b_{i, j}$ suppose that:
I. For every fixed $\underset{\sim}{t} \in \mathrm{R}_{\mathrm{m}}$ :
(2.1)

$$
\left|\partial_{x_{i}}^{\prime} g(x, t)\right| \leq a(x)+b(\underset{\sim}{t}), \quad \text { a.e. in } \Omega, \quad(i=1, \ldots, n),
$$

where $\partial_{x_{i}} g$ denotes the strong approximate derivative of $g$, as in Definition l.2.
II. The inequality:

$$
\begin{equation*}
\left|\frac{\partial g(x, t)}{\partial t_{i}}\right| \leq a_{k}(x)+\sum_{j=1}^{m} b_{k, j}\left(t_{j}\right), \quad(k=1, \ldots, m), \tag{2.2}
\end{equation*}
$$

holds at every point $(x, \underset{\sim}{t}) \in(\Omega-N) \times R_{m}$ at which the estimated derivative exists in the classical sense. Here, $N=N_{g}$ is the set mentioned in Definition 2.2.

The assumptions on $a, b, a_{k}, b_{k, j}$ are as follows:
(2.3)

$$
0 \leq a \in L_{p}(\Omega) ;
$$

$$
\begin{equation*}
0 \leq \mathrm{b} \text { is continuous in } \mathrm{R}_{\mathrm{m}} \tag{2.4}
\end{equation*}
$$

(2.5) $0 \leq a_{k} \in L_{q_{k}^{\prime}}(\Omega), \quad$ where $\frac{1}{q_{k}^{\prime}}+\frac{l}{q_{k}}=\frac{1}{p}, \quad(k=1, \ldots, m) ;$
(2.6) $0 \leq b_{k, j}$ is an extended real valued Borel measurable function on $R_{1}, \quad(k, j=1, \ldots, m) ;$

$$
\begin{equation*}
\mathrm{b}_{\mathrm{k}, \mathrm{k}} \in \mathrm{~L}_{1}^{\mathrm{loc}}\left(\mathrm{R}_{1}\right), \quad(\mathrm{k}=1, \ldots, \mathrm{~m}) \tag{2.7}
\end{equation*}
$$

Let $\underset{\sim}{u}=\left(u_{1}, \ldots, u_{m}\right) \in W_{1}, \tilde{q}^{(\Omega)}$ and suppose that:
$\mathrm{b} \circ \underset{\sim}{u} \in \mathrm{~L}_{\mathrm{p}}(\Omega) ;$

$$
\begin{equation*}
\mathrm{b}_{\mathrm{k}, \mathrm{j}} \circ \mathrm{u}_{j} \in \mathrm{~L}_{\mathrm{q}_{\mathrm{k}}^{\prime}}(\Omega), \quad(\mathrm{k}, j=1, \ldots, \mathrm{~m} ; \mathrm{k} \neq j) ; \tag{2.9}
\end{equation*}
$$

(2.10)

$$
\begin{aligned}
& {\left[b_{k, k} \quad u_{k}\right] \partial_{x_{i}} u_{k} \in L_{p}(\Omega), \quad(k=1, \ldots, m ; i=1, \ldots, n),} \\
& \text { where the product is to be interpreted as zero } \\
& \text { whenever } \partial_{x_{i}} u_{k}=0 . \text { Then } v=g \circ \underset{\sim}{u} \in W_{1, p}(\Omega) .
\end{aligned}
$$

Proof. Let $M$ be a countable dense set in $R_{m}$. For each fixed $\underset{\sim}{t^{\prime}} \in \mathrm{R}_{\mathrm{m}}$ we may modify $\mathrm{g}(\cdot, \underset{\sim}{t})$ on a null subset of $\Omega$, say $N_{t^{\prime}}$, such that the modified function is in $A(\Omega)$. We make this modification for every $\underset{\sim}{t} \in M$, leaving $g(x, \underset{\sim}{t})$ unchanged when $\underset{\sim}{t \notin M}$, and denote the modified function by $g_{0}$. Let $N_{M}=U_{t^{\prime} \in M}^{N_{t^{\prime}}}$; then $N_{M}$ is a null subset of $\Omega$. Note that $g_{0}$ may differ from $g$ only on $N_{M} \times M$. Clearly $g_{0}$ satisfies all the assumptions that have been made with respect to $g$, except that
in II $N=N_{g}$ may have to be replaced by a larger null set (egg. $\quad N \cup N_{M}$ ).

Since $g(x, \underset{\sim}{u}(x))=g_{0}(x, \underset{\sim}{u}(x))$ abe. in $\Omega$ it is sufficient to prove that $g_{0} \circ \underset{\sim}{u} \in W_{1, p}(\Omega)$.

In order to simplify the notation we shall assume that the given function $g$ already satisfies the additional condition:
(2.11)

$$
g\left(\cdot, t^{\prime}\right) \in A(\Omega),
$$

$\forall{\underset{\sim}{t}}^{\prime} \in M$,
with $M$ as above. Then (by Definition 1.2), for every fixed ${\underset{\sim}{t}}^{\prime} \in M:$

$$
\partial_{x_{i}}^{\prime} g\left(x, t^{\prime}\right)=\frac{\partial g}{\partial x_{i}}\left(x, t^{\prime}\right), \quad \text { a.e. in } \Omega, \quad(i=1, \ldots, n) .
$$

Hence, taking into account that $M$ is countable, there exists a null subset of $\Omega$, say $N_{1}$, such that (by (2.1)):
(2.1)' $\quad\left|\frac{\partial g}{\partial x_{i}}(x, \underset{\sim}{t})\right| \leq a(x)+b(\underset{\sim}{t}), \quad \forall(x, \underset{\sim}{t}) \in\left(\Omega-N_{1}\right) \times M, \quad(i=1, \ldots, n)$.

Let ${\underset{\sim}{t}}^{0}$ be a fixed point in $R^{m}$. Then $g\left(\cdot,{\underset{\sim}{t}}^{0}\right) \in A^{\prime}(\Omega)$ and by (2.1) $\quad \partial_{x_{i}}^{\prime} g\left(\cdot,{\underset{\sim}{t}}^{0}\right) \in L_{p}(\Omega), \quad(i=1, \ldots, n)$. Hence by Lemma 1.4 it follows that:

$$
\begin{equation*}
g\left(\cdot,{\underset{\sim}{t}}^{o}\right) \in W_{1, p}(\Omega), \quad \forall{\underset{\sim}{t}}^{o} \in R_{m} \tag{2.12}
\end{equation*}
$$

Denote:
(2.13)

$$
\beta_{i}(\rho)=\int_{0}^{\rho} b_{i, i}(\rho) d \rho, \quad-\infty<\rho<\infty, \quad i=1, \ldots, n
$$

Then $\beta_{i}$ is l.a.c. on $R_{1}$. By $(2,10)$ and Corollary 1.2 it follows that

$$
\begin{equation*}
\beta_{i} \circ u_{i} \in W_{1, p}(\Omega), \quad i=1, \ldots, n \tag{2.14}
\end{equation*}
$$

(In deriving (2.12) and (2.14) we used the fact that $\Omega$ is bounded and has the cone property.)

We prove now that $v=g 0 \underset{\sim}{u} \in L_{p}(\Omega)$. First we remark that, by the theorem of Caratheodory [4] mentioned before, $v$ is a measurable function in $\Omega$.

If $x \in \Omega-N$, then by (2.2):
(2.15) $\left|g(x, t)-g\left(x, t_{\sim}^{o}\right)\right| \leq\left|\int_{t_{1}^{o}}^{t_{1}} \frac{\partial g}{\partial t_{1}}\left(x, \sigma, t_{2}^{0}, \ldots, t_{m}^{o}\right) d \sigma\right|+\ldots$

$$
+\left|\int_{t_{m}^{o}}^{t_{m}} \frac{\partial g}{\partial t_{m}}\left(x, t_{1}, \ldots, t_{m-1}, \sigma\right) d \sigma\right| \leq
$$

$$
\leq \sum_{i=1}^{m}\left\{a_{i}(x)\left|t_{i}-t_{i}^{o}\right|+\sum_{j=1}^{i-1} b_{i, j}\left(t_{j}\right)\left|t_{i}-t_{i}^{o}\right|\right.
$$

$$
\left.+\sum_{j=i+1}^{m} b_{i, j}\left(t_{j}^{o}\right)\left|t_{i}-t_{i}^{o}\right|+\left|\beta_{i}\left(t_{i}\right)-\beta_{i}\left(t_{i}^{o}\right)\right|\right\}
$$

To simplify the notation we denote:

$$
c_{i}^{(1)}(\underset{\sim}{t})=\sum_{j=1}^{i-1} b_{i, j}\left(t_{j}\right), \quad c_{i}^{(2)}(\underset{\sim}{t})=\sum_{j=i+1}^{m} b_{i, j}\left(t_{j}\right)
$$

(2.16)

$$
c_{i}(\underset{\sim}{t})=c_{i}^{(l)}(\underset{\sim}{t})+c_{i}^{(2)}(\underset{\sim}{t}) .
$$

Then, for $x \in \Omega-N$, we have:
(2.17) $\left|g(x, t)-g\left(x,{\underset{\sim}{t}}^{0}\right)\right| \leq \sum_{i=1}^{m}\left[a_{i}(x)+c_{i}^{(1)}(\underset{\sim}{t})+c_{i}^{(2)}\left({\underset{\sim}{t}}_{0}^{o}\right)\right]\left|t_{i}-t_{i}^{o}\right|$

$$
+\sum_{i=1}^{m}\left|\beta_{i}\left(t_{i}\right)-\beta_{i}\left(t_{i}^{o}\right)\right|
$$

Now, pick a point ${\underset{\sim}{t}}^{0}$ such that $b_{i, j}\left(t_{j}^{0}\right)$ is finite for is $=1, \ldots, m, \quad i \neq j$. (Clearly, by (2.9), such a point exists.) Then, from (2.5), (2.9), (2.14), (2.17) we get:

$$
\text { (2.18) } \begin{aligned}
\left\|v-g\left(\cdot, t^{o}\right)\right\|_{L_{p}(\Omega)} & \leq \sum_{i=1}^{m}\left[\left\|a_{i}\right\|_{L_{q_{i}^{\prime}}(\Omega)}+\left\|c_{i}^{(l)} \circ \underset{\sim}{u}\right\|_{L_{q_{i}^{\prime}}(\Omega)}\right]\left\|u_{i}-t_{i}^{o}\right\|_{L_{q_{i}}}(\Omega) \\
& +\sum_{i=1}^{m} c_{i}^{(2)}\left(\underset{\sim}{t^{o}}\right)\left\|u_{i}-t_{i}^{o}\right\|_{L_{p}}(\Omega) \\
& +\sum_{i=1}^{m}\left\|\beta_{i} 0 u_{i}-\beta_{i}\left(t_{i}^{o}\right)\right\|_{L_{p}(\Omega)}
\end{aligned}
$$

Note that since $\Omega$ is bounded and $u_{i} \in L_{q_{i}}(\Omega)$, with $q_{i} \geq p$, it follows that $u_{i} \in L_{p}(\Omega)$. Taking into account (2.12) we conclude that $v \in L_{p}(\Omega)$.

In order to show that $v \in W_{1, p}(\Omega)$ we have to discuss some additional properties of $g$.

First we observe that $g$ satisfies the following condition:
For a.e. line $\tau$ in $R_{n}$, parallel to the $x_{i}$-axis:
(2.19)

$$
\left|g\left(x^{\prime}, \underset{\sim}{t}\right)-g\left(x^{\prime \prime}, \underset{\sim}{t}\right)\right| \leq\left|\int_{x_{i}^{\prime}}^{x_{i}^{\prime \prime}} a(x) d x_{i}\right|+b(\underset{\sim}{t})\left|x_{i}^{\prime}-x_{i}^{\prime \prime}\right|,
$$

for every $\underset{\sim}{t} \in R_{m}$ and every two points $x^{\prime}, x^{\prime \prime}$ lying in one interval of $\tau \cap \Omega$, such that $x^{\prime}, x^{\prime \prime} \notin N$. (The index $i$ will be kept fixed throughout the following part of the proof.)

Indeed, for a.e. line $\tau$ parallel to the $x_{i}$-axis the following three conditions are satisfied:
$\left(\alpha_{1}\right) \quad \tau \cap\left(N \cup N_{1}\right)$ is an $\delta_{1}$-null set;
( $\alpha_{2}$ ) "a" restricted to $\tau \cap \Omega$ is in $L_{p}$;
$\left(a_{3}\right) \quad g(\cdot, t)$ is l.a.c. on $\tau \cap \Omega$ for every $\underset{\sim}{t} \in M$.

This follows from (2.3), (2.11) and the fact that $N \cup N_{1}$ is a null set.

If $\tau$ is a line as above, satisfying conditions ( $\alpha_{1}$ ), $\left(\alpha_{2}\right),\left(\alpha_{3}\right)$, and if $\underset{\sim}{t} \in M$, (2.19) follows immediately from (2.1)', for any two points $x^{\prime}, x^{\prime \prime}$ lying in a subinterval of $\tau \cap \Omega$. If in adaition $x^{\prime}, x^{\prime \prime} \notin N$, then by the continuity of $g$ with respect to $\underset{\sim}{t}$ (Definition $2.2(i)$ ) and by the continuity of $b$ in $R_{m}$ we conclude that (2.19) holds for every $\underset{\sim}{t} \in R_{m}$. Here we
are using the fact that $M$ is a dense subset of $R_{m}$. Furthermore, for such a line $\tau$ and for every $\underset{\sim}{t} \in R_{m}$, we can modify $g(\cdot, \underset{\sim}{t})$ on $\tau \cap N$ in such a way that the modified function will be l.a.c. on $\tau \cap \Omega$ and will satisfy (2.19) for every two points $x^{\prime}, x^{\prime \prime}$ lying in a subinterval of $\tau \cap \Omega$. Indeed, for every fixed $\underset{\sim}{t} \in \mathrm{R}_{\mathrm{m}}, \mathrm{g}(\cdot, \underset{\sim}{t})$ restricted to $(\tau \cap \Omega)-N$ is uniformly continuous (by (2.19)). Since $\tau \cap N$ is an $\mathbb{L}_{1}$-null set and hence has a dense complement, it follows (by a standard argument) that $g(\cdot, t \underset{\sim}{t})$ may be redefined on $\tau \cap N$ in such a way that it will become uniformly continuous on $\tau \cap \Omega$. obviously, the function thus modified will have the properties stated above.

Denote the function resulting from this modification of $g$ on all lines $\tau$ as above, by $g_{i}$. Note that $g_{i}(x, \underset{\sim}{t})=g(x, \underset{\sim}{t})$ for all $(x, \underset{\sim}{t}) \in(\Omega-N) \times R_{m}$. Hence $g_{i}$ will also satisfy condition (i) of Definition 2.2 as well as inequalities (2.2) and (2.17). Set $v_{i}=g_{i}$ • $\underset{\sim}{u} ; ~ c l e a r l y ~ v=v_{i}$ a.e. in $\Omega$. Let $\tau$ be a line parallel to the $x_{i}$-axis satisfying conditions ( $\alpha_{1}$ )$\left(\alpha_{3}\right)$. Let $x^{0} \in(\tau \cap \Omega)-N$ and let $|h| \neq 0$ be a sufficiently small so that $x^{\circ}$ and $x_{h}^{0}=x^{\circ}+h e^{i}$ belong to one subinterval of $\tau \cap \Omega$. Then by (2.17) and (2.19):
(2.20) $\left|\delta_{h}^{i} v_{i}\left(x^{o}\right)\right| \leq \frac{1}{|h|}\left|g_{i}\left(x_{h}^{o}, \underset{\sim}{u}\left(x_{h}^{o}\right)\right)-g_{i}\left(x^{o}, \underset{\sim}{u}\left(x_{h}^{o}\right)\right)\right|$

$$
\begin{aligned}
& +\frac{1}{|h|}\left|g_{i}\left(x^{o}, \underset{\sim}{u}\left(x_{h}^{o}\right)\right)-g_{i}\left(x^{o}, \underset{\sim}{u}\left(x^{o}\right)\right)\right| \\
& \leq \frac{1}{|h|} \int_{0}^{|h|} a\left(x^{o}+\xi e^{i}\right) d \xi+(b o \underset{\sim}{u})\left(x_{h}^{o}\right)
\end{aligned}
$$

$$
+\sum_{k=1}^{m}\left[a_{k}\left(x^{o}\right)+\left(c_{k}^{(1)} \circ \underset{\sim}{u}\right)\left(x_{h}^{o}\right)+\left(c_{k}^{(2)} \circ \underset{\sim}{u}\right)\left(x^{o}\right)\right]\left|\delta_{h}^{i} u_{k}\left(x^{o}\right)\right|
$$

$$
+\sum_{k=1}^{m}\left|\delta_{h}^{i}\left(\beta_{k} \circ u_{k}\right)\left(x^{o}\right)\right|
$$

Let $\Omega^{1}$ be an open subset of $\Omega$ such that $\bar{\Omega} \subset \Omega$ and let $h_{0}=$ dist. $\left(\Omega^{1}, \partial \Omega\right)$. since $u_{k} \in W_{1, q_{k}}(\Omega)$ and $\beta_{k} \circ u_{k} \in W_{1, p}(\Omega)$, it follows (by Lemma 1.5) that:
(2.21)

$$
\left\{\begin{array}{l}
\left\|\delta_{h}^{i} u_{k}\right\|_{L_{q_{k}}}\left(\Omega^{\prime}\right) \leq\left\|\partial_{x_{i}} u_{k}\right\|_{L_{q_{k}}(\Omega)}, \\
\left\|\delta_{h}^{i}\left[\beta_{k} \circ u_{k}\right]\right\|_{L_{p}(\Omega)} \leq\left\|\partial_{x_{i}}\left[\beta_{k} \cdot u_{k}\right]\right\|_{L_{p}}(\Omega),\left(0<|h|<h_{o}\right)
\end{array}\right.
$$

By (2.20) and (2.21):
(2.22) $\left\|\delta_{h}^{i} v_{i}\right\|_{L_{p}\left(\Omega^{\prime}\right)} \leq\|a\|_{L_{p}(\Omega)}+\|b \bullet \underset{\sim}{u}\|_{L_{p}}$

$$
\begin{align*}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}(\Omega)}+\left\|c_{k} \circ \underset{\sim}{u}\right\|_{L_{q_{k}^{\prime}}(\Omega)}\right]\left\|\partial_{x_{i}} u_{k}\right\|_{L_{q_{k}}}(\Omega) \\
& +\sum_{k=1}^{m}\left\|\partial_{k_{i}}\left(\beta_{k} \circ u_{k}\right)\right\|_{L_{p}(\Omega)}, \quad\left(0<|h|<h_{o}\right)
\end{align*}
$$

Here we used Minkowski's inequality and Hölder's inequality. For reference we shall denote the right side of (22) by $K_{i}$. We note that $K_{i}$ does not depend on $\Omega$ or $h$, for sufficiently small $|\mathrm{h}|$.

$$
\text { Since } v_{i} \in L_{p}(\Omega),(1<p<\infty) \text {, it follows from (2.22) (by }
$$

Lemma 1.6) that $\partial_{X_{i}} v_{i} \in L_{p}(\Omega)$ and that:

$$
\begin{equation*}
\left\|\partial_{x_{i}} v_{i}\right\|_{L_{p}(\Omega)} \leq K_{i} \tag{2.23}
\end{equation*}
$$

We remark that this is the only place in our arguments where the assumption $\quad 1<p$ was needed.

$$
\text { Now, } v_{i}=v \text { a.e. in } \Omega \text {; hence, it follows that } \partial_{x_{i}} v \in L_{p}(\Omega)
$$ and that:

$$
\begin{equation*}
\left\|\partial_{x_{i}} v\right\|_{L_{p}(\Omega)} \leq K_{i} \tag{2.24}
\end{equation*}
$$

Finally, since this holds for every $i$, ( $i=1, \ldots, n$ ) we conclude that $v \in W_{1, p}(\Omega)$.

Corollary 2.1. In addition to the assumptions of the theorem, suppose that $b_{i, j}(0)$ is finite for $i, j=1, \ldots, m(i \neq j)$. Then, without loss of generality we may assume also that $b_{i, j}(0)=0$ for $i, j$ as above. In this case, $v$ satisfies the following inequality:
(2.25)

$$
\begin{aligned}
\|v\|_{W_{1, p}}(\Omega) & \leq\|g(\cdot, \underset{\sim}{0})\|_{L_{p}(\Omega)}+\|a\|_{L_{p}(\Omega)}+\|b \bullet \underset{\sim}{u}\|_{L_{p}(\Omega)} \\
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}(\Omega)}+\left\|c_{k} \circ \underset{\sim}{u}\right\|_{L_{q_{k}^{\prime}}(\Omega)}\right]\left\|u_{k}\right\|_{W_{1, q_{k}}}(\Omega) \\
& +\sum_{k=1}^{m}\left\|\beta_{k} \cdot u_{k}\right\|_{W_{1, p}}(\Omega)
\end{aligned}
$$

This inequality follows immediately from (2.18) with ${\underset{\sim}{t}}^{0}=(0, \ldots, 0)$ and (2.24).

Corollary 2.2. If $\Omega$ is any domain in $R_{n}$ (possibly unbounded), the theorem will still be valid if we make the following additional assumptions:
(2.26)

$$
\begin{cases}b_{i, j}(0)=0, & (i, j=1, \ldots, m ; i \neq j), \\ g(\cdot, 0) \in L_{p}(\Omega), & (i=1, \ldots, n),\end{cases}
$$

with $\beta_{i}$ as defined in the proof of the theorem.

The assumption that $\Omega$ is bounded and has the cone property has been used only in the proof of (2.12), (2.14) and (2.18). Since it is enough, for our purposes, to obtain (2.18) with ${\underset{\sim}{t}}^{0}=(0, \ldots, 0)$, the conditions (2.26) make it possible to dispense with this special assumption on $\Omega$.

Corollary 2.3. Under the assumptions of the theorem we have:
(2.27) $\left|\partial_{x_{i}} v(x)\right| \leq a(x)+(b 0 \underset{\sim}{u})(x)$

$$
+\sum_{k=1}^{m}\left[a_{k}(x)+\sum_{j=1}^{m}\left(b_{k, j} \circ u_{j}\right)(x)\right]\left|\partial_{x_{i}} u_{k}(x)\right|
$$

a.e. in $\Omega,(i=1, \ldots, n)$, the products on the right being interpreted as zero whenever $\partial_{x_{i}} u_{k}=0$.
Proof. Let $\tilde{u}_{k}, \tilde{v}$ be functions in $A(\Omega)$ such that $v=\tilde{v}$ and $u_{k}=\tilde{u}_{k}(k=1, \ldots, m)$, are. in $\Omega$. Such functions exist by Lemma 1.4. We denote $v^{*}=g(x, \underset{\sim}{\sim})$.

By (2.14), $\beta_{i} \circ \tilde{u}_{i} \in W_{1, p}(\Omega)$ so that (by Lemma 1.4) $\beta_{i} \circ \tilde{u}_{i} \in A^{\prime}(\Omega)$. But $\beta_{i} \bullet \tilde{u}_{i}$ is continuous on every segment where $\tilde{u}_{i}$ is continuous. Therefore $\beta_{i} \bullet \tilde{u}_{i} \in A(\Omega),(i=1, \ldots, n)$.

Let $\tau$ be a line parallel to the $\mathrm{x}_{\mathrm{i}}$-axis such that $\tau$ satisfies conditions $\left(\alpha_{1}\right)-\left(\alpha_{3}\right)$ and in addition:
(2.28)

$$
\left\{\begin{array}{l}
\underset{\sim}{\tilde{u}}, \tilde{v}, \beta_{k} \circ u_{k}(k=1, \ldots, m) \text { are l.a.c. on } \tau \cap \Omega ; \\
\mathrm{b}_{\mathrm{k}, j} \circ \tilde{u}_{j} \text { restricted to } \tau \cap \Omega \text { is locally summable } \\
(k, j=1, \ldots, m ; k \neq j) ; \\
\tilde{v}=v^{*} \dot{L}_{1}-\text { a.e. on } \tau \cap \Omega
\end{array}\right.
$$

These conditions are satisfied by ace. line $\tau$ parallel to the $x_{i}$-axis.

Further, let $\mathrm{x}^{\mathrm{O}}$ be a point in $(\tau \cap \Omega)-N$ such that:


These conditions are satisfied by $\delta_{1}$ - almost every point on $\tau \cap \Omega$.

Let $\left\{h_{\nu}\right\}_{l}^{\infty}$ be a sequence of non-zero numbers such that $h_{\nu} \rightarrow 0$ and such that the points $x^{\nu}=x^{0}+h_{\nu} e^{i} \quad(\nu=1,2, \ldots)$ lie in the subinterval of $\tau \cap \Omega$ which contains $x^{\circ}$. Moreover, choose $h_{\nu}$ in such a manner that $x^{\nu} \notin N, \tilde{v}\left(x^{\nu}\right)=v^{*}\left(x^{\nu}\right),(\nu=1,2, \ldots)$ and finally $b_{k, j} \circ \tilde{u}_{j}\left(x^{\nu}\right) \rightarrow b_{k, j} \circ \tilde{u}_{j}\left(x^{\circ}\right),(k, j=1, \ldots, m ; k \neq j)$. This is possible since by condition (2.29) $\mathrm{x}^{\mathrm{o}}$ is actually a point of approximate continuity of the functions $b_{k, j} \bullet \tilde{u}_{j}$ restricted to $\tau \cap \Omega$. (For the definition of approximate continuity see Saks [15], p. 132.)

By (2.17) and (2.19) we obtain:

$$
\begin{aligned}
\left|\delta_{h}^{i} \tilde{v}\left(x^{o}\right)\right|= & \left|\delta_{h}^{i} v_{\nu}^{*}\left(x^{o}\right)\right| \leq \frac{1}{|h|} \int_{0}^{|h|} a\left(x^{o}+\xi e^{i}\right) d \xi+(b \bullet \underset{\sim}{\tilde{u}})\left(x_{h}^{o}\right) \\
& +\sum_{k=1}^{m}\left[a_{k}\left(x^{o}\right)+\left(c_{k}^{(1)} \bullet \underset{\sim}{\tilde{u}}\right)\left(x_{h}^{o}\right)+\left(c_{k}^{(2)} \bullet \underset{\sim}{\tilde{u}}\right)\left(x^{o}\right)\right]\left|\delta_{h_{\nu}}^{i} \tilde{u}_{k}\left(x^{o}\right)\right| \\
& +\sum_{k=1}^{m}\left|\delta_{h_{\nu}}^{i}\left(\beta_{k} \circ \tilde{u}_{k}\right)\left(x^{o}\right)\right| .
\end{aligned}
$$

Letting $\nu \rightarrow \infty$ we get:
(2.30) $\left|\frac{\partial \tilde{v}}{\partial \mathrm{x}_{i}}\left(\mathrm{x}^{0}\right)\right| \leq \mathrm{a}\left(\mathrm{x}^{0}\right)+(\mathrm{b} \bullet \underset{\sim}{\underset{\sim}{u}})\left(\mathrm{x}^{0}\right)$

$$
\begin{aligned}
& \quad+\sum_{k=1}^{m}\left[a_{k}\left(x^{o}\right)+\left(c_{k} \cdot \underset{\sim}{\sim}\right)\left(x^{o}\right)\right]\left|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\left(x^{o}\right)\right| \\
& +\sum_{k=1}^{m}\left|\frac{\partial\left(\beta_{k} 0 \tilde{u}_{k}\right)}{\partial x_{i}}\left(x^{o}\right)\right| .
\end{aligned}
$$

This inequality holds $\delta_{1}$ - abe. on $\tau \cap \Omega$ for almost every line $\tau$ parallel to the $x_{i}$-axis. Since both sides of the inequality are measurable functions, it follows (by Fubini's theorem) that the inequality holds a.e. in $\Omega$. Finally we note that by Lemma 1.10 :

$$
\begin{equation*}
\frac{\partial\left(\beta_{k} \circ \tilde{u}_{k}\right)}{\partial x_{i}}=\left[b_{k, k} \circ \tilde{u}_{k}\right] \cdot \frac{\partial \tilde{u}_{k}}{\partial x_{i}}, \text { a.e. in } \Omega \tag{2.31}
\end{equation*}
$$

the product being interpreted as zero whenever $\frac{\partial \tilde{u}_{k}}{\partial x_{i}}=0$. commining (2.30) and (2.31) and taking into account that $\frac{\partial u_{k}}{\partial x_{i}}=\partial_{x_{i}} \tilde{u}_{k}$ a.e. in $\Omega,(k=1, \ldots, m ; i=1, \ldots, n)$ we obtain (2.27).

## §3. On a Class of Nemitsky Operators (Con't)

In the previous section we considered Nemitsky operators associated with l.a.c. Caratheodory functions, which map an $R_{m}{ }^{-}$ valued function $\underset{\sim}{u} \in \mathbb{W} \underset{1, \widetilde{q}}{(\Omega)}$ to a function in $W_{1, p}(\Omega)$ with $p>1$. The case $p=1$ requires a different treatment. In the present section we deal with this special case.

Theorem 3.1. Let $p=1$ and $\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ with $q_{1}=\ldots=q_{m}=1$. Then, under the assumptions of Theorem 2.1 with $p$ and $\tilde{q}$ as above we have $v=g \circ \underset{\sim}{u} W_{1, l}(\Omega)$.

Proof. As in the proof of Theorem 2.1, we may and shall assume that $g$ satisfies condition (2.11) and inequality (2.1)', where $M$ is a dense countable subset of $R_{m}$. We also use the various notations introduced in the proof of that theorem.

By Lemma 1.4, there exist functions $\widetilde{u}_{k} \in A(\Omega)$ such that $\tilde{u}_{k}=u_{k}$ and $\frac{\partial \tilde{u}_{k}}{\partial x_{i}}=\partial_{x_{i}} u_{k}$ a.e. in $\Omega,(k=1, \ldots, m ; i=1, \ldots, n)$. Denote by $N_{2}$ the set of points in $\Omega$ where at least one of the following relations does not hold:
(3.1)

$$
\underset{\sim}{u}(x)=\underset{\sim}{\underset{\sim}{u}}(x) ; \quad a_{k}(x) \leq\left\|a_{k}\right\|_{L_{\infty}}(\Omega) ;\left(b_{k, j} \bullet u_{j}\right)(x) \leq\left\|b_{k, j} \bullet u_{j}\right\|_{L_{\infty}}(\Omega),
$$

$(k, j=1, \ldots, m ; k \neq j) . \quad B y(2.5)$ and (2.9) these relations hold on a subset of $\Omega$ of full measure, so that $N_{2}$ is a null set. Let $\tau$ be a line parallel to the $x_{i}$-axis such that
conditions $\left(\alpha_{1}\right)-\left(\alpha_{3}\right)$ (described in the proof of Theorem 2.1) are satisfied and such that:

$$
\begin{aligned}
& \left(\alpha_{4}\right) \underset{\sim}{\tilde{u}} \text { and } \beta_{k} \circ \tilde{u}_{k}(k=1, \ldots, m) \text { are l.a.c. on } \tau \cap \Omega \\
& \left(\alpha_{5}\right) \quad N_{2} \cap \tau \text { is an } \delta_{1}-\text { null set. }
\end{aligned}
$$

Clearly, almost every line $\tau$ parallel to the $x_{i}$-axis satisfies these conditions.

Let then $\tau$ be a line as above and let $I$ be a compact subinterval of $\tau \cap \Omega$. Denote $v^{*}=g \circ \tilde{u}$ and let $x^{\prime}, x^{\prime \prime} \in \mathbf{I}-N$. Then by (2.17) and (2.19) we have:
(3.2)

$$
\begin{aligned}
& \left|v^{*}\left(x^{\prime}\right)-v^{*}\left(x^{\prime \prime}\right)\right| \leq\left|\int_{x_{i}^{\prime}}^{x_{i}^{\prime \prime}} a(x) d x_{i}\right|+(b \circ \underset{\sim}{\sim})\left(x^{\prime}\right)\left|x_{i}^{\prime}-x_{i}^{\prime \prime}\right| \\
& +\sum_{k=1}^{m}\left[a_{k}\left(x^{\prime \prime}\right)+\left(c_{k}^{(1)} \circ \underset{\sim}{\underset{\sim}{u}}\right)\left(x^{\prime}\right)\right. \\
& \left.+\left(c_{k}^{(2)} \circ \underset{\sim}{\tilde{u}}\right)\left(x^{\prime \prime}\right)\right]\left|\tilde{u}_{k}\left(x^{\prime}\right)-\tilde{u}_{k}\left(x^{\prime \prime}\right)\right| \\
& +\sum_{k=1}^{m}\left|\left(\beta_{k} \circ \tilde{u}_{k}\right)\left(x^{\prime}\right)-\left(\beta_{k} \circ \tilde{u}_{k}\right)\left(x^{\prime \prime}\right)\right| . \\
& \text { In particular, if } x^{\prime}, x^{\prime \prime} \in I-\left(N \cup N_{2}\right) \text { we have: }
\end{aligned}
$$

(3.3) $\left|v^{*}\left(x^{\prime}\right)-v^{*}\left(x^{\prime \prime}\right)\right| \leq\left|\int_{x_{i}^{\prime}}^{x_{i}^{\prime \prime}} a(x) d x_{i}\right|+(b \circ \tilde{u})\left(x^{\prime}\right)\left|x_{i}^{\prime}-x_{i}^{\prime \prime}\right|$

$$
\begin{aligned}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{\infty}}(\Omega)+\left\|c_{k} \circ{\underset{\sim}{u}}_{\sim}^{\tilde{L}}\right\|_{\infty}(\Omega)\right] \cdot\left|\tilde{u}_{k}\left(x^{\prime}\right)-\tilde{u}_{k}\left(x^{\prime \prime}\right)\right| \\
& +\sum_{k=1}^{m}\left|\left(\beta_{k} \circ \tilde{u}_{k}\right)\left(x^{\prime}\right)-\left(\beta_{k} \circ \tilde{u}_{k}\right)\left(x^{\prime \prime}\right)\right| .
\end{aligned}
$$

By (3.3), $\mathrm{v}^{*}$ restricted to $\tau \cap \Omega$, is uniformly continuous on I - ( $N \cup N_{2}$ ). Hence, by a standard argument, $v^{*}$ can be redefined on $I \cap\left(N \cup N_{2}\right)$ in such a manner that the modified function will be continuous in $I$ and will satisfy (3.3) at every point in $I$.

Modifying $v^{*}$ in this manner on all the compact subintervals of $\tau \cap \Omega$ and for all lines $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis as above, we denote the modified function by $v_{i}^{*}$. Note that this modification involves only points $x$ in $N U N_{2}$ so that $v_{i}^{*}=v^{*}$ a.e. in $\Omega$. By (3.3), $v_{i}^{*} \in A_{i}(\Omega)$. Using inequality (3.2) together with the above remarks concerning $v_{i}^{*}$ we obtain (as in the proof of Corollary 2.3):
(3.4) $\left|\frac{\partial v_{i}^{*}}{\partial x_{i}}(x)\right| \leq a(x)+(b \circ \underset{\sim}{\underset{\sim}{u}})(x)+\sum_{k=1}^{m}\left[a_{k}(x)+\left(c_{k} \circ \underset{\sim}{\sim} \underset{\sim}{\widetilde{u}}\right)(x)\right]\left|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}(x)\right|$

$$
+\sum_{k=1}^{m}\left|\frac{\partial\left(\beta_{k} \circ \tilde{u}_{k}\right)(x)}{\partial x_{i}}\right|, \quad \text { a.e. in } \Omega
$$

Hence, $\frac{\partial v_{i}^{*}}{\partial x_{i}} \in L_{l}(\Omega)$ and:
(3.5) $\left\|\frac{\partial v_{i}^{*}}{\partial x_{i}}\right\|_{L_{1}(\Omega)} \leq\|a\|_{L_{1}(\Omega)}+\|b \Delta \underset{\sim}{\tilde{u}}\|_{L_{1}(\Omega)}$

$$
\begin{aligned}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{\infty}}(\Omega)\right. \\
& \left.+\left\|c_{k} \circ \underset{\sim}{\tilde{u}}\right\|_{L_{p}(\Omega)}\right]\left\|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right\|_{L_{1}}(\Omega) \\
& +\sum_{k=1}^{m}\left\|\frac{\partial\left(\beta_{k} \circ \tilde{u}_{k}\right)}{\partial x_{i}}\right\|_{L_{1}(\Omega)} .
\end{aligned}
$$

As in the proof of Theorem 2.1, $v \in L_{1}(\Omega)$ and satisfies (2.18) (with $p=1, q_{i}=1, q_{i}^{\prime}=\infty$ ). Since $v=v_{i}^{*}$ a.e. in $\Omega$ it follows (by Lemma 1.3) that:

$$
\begin{equation*}
\partial_{x_{i}} v=\frac{\partial v_{i}^{*}}{\partial x_{i}} \quad \text { a.e. in } \Omega, \tag{3.6}
\end{equation*}
$$

so that $\partial_{x_{i}} v \in L_{1}(\Omega)$. This result holds for every $i,(i=1, \ldots, n)$. Therefore $v \in W_{1,1}(\Omega)$ and the proof is complete.

Corollary 3.1. The statements of Corollaries 2.1, 2.2 and 2.3 are valid also in the case $p=1, \tilde{q}=(1, \ldots, 1)$.

The proofs are the same as those of the above mentioned corollaries. Actually inequality (2.27) has already been obtained in the proof of the theorem (see (3.4) and (3.6)).

Corollary 3.2. Let $p=1$ and $\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ with $q_{i} \geq 1$. Let $\Omega, g$ and $\underset{\sim}{u}$ satisfy the condition of Theorem 2.1 with $p$ and $\tilde{q}$ as above. In addition suppose that:

$$
\begin{equation*}
a_{k} \in L_{\infty}^{l o c}(\Omega), \quad b_{k, j} \circ u_{j} \in L_{\infty}^{l o c}(\Omega), \quad(k, j=1, \ldots, m ; k \neq j) . \tag{3.7}
\end{equation*}
$$

Then $v=g \bullet \underset{\sim}{u} \in W_{1, l}(\Omega)$.
Proof. Since $W_{1, q_{k}}(\Omega) \subset W_{1,1}(\Omega)$, all the assumptions of the theorem are satisfied in compact subdomains of $\Omega$ (by (3.7)). Hence $\quad v \in W_{1,1}^{l o c}(\Omega)$.

By Corollary 3.1, inequality 2.17 is valid. Therefore
$\partial_{x_{i}} v \in L_{1}(\Omega),(i=1, \ldots, n)$. In fact we have:
(3.8) $\left\|\partial_{\mathbf{x}_{i}} v\right\|_{\mathbf{L}_{1}(\Omega)} \leq\|a\|_{L_{1}(\Omega)}+\|b \bullet \underset{\sim}{u}\|_{L_{1}}(\Omega)$

$$
\begin{align*}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}}^{\prime}(\Omega)}+\left\|c_{k} \circ \underset{\sim}{u}\right\|_{L_{q_{k}^{\prime}}^{\prime}(\Omega)}\right]\left\|\partial_{x_{i}} u_{k}\right\|_{L_{q_{k}}} \\
& +\sum_{k=1}^{m}\left\|\left(b_{k, k} \bullet u\right) \partial_{x_{i}} u_{k}\right\|_{L_{l}(\Omega)}, \quad(i=1, \ldots, n) .
\end{align*}
$$

As in the proof of Theorem 2.1, $v \in L_{1}(\Omega)$ and satisfies (2.18)
(with $p=1$ ). Hence $v \in W_{1,1}(\Omega)$.

Remark. Note that the statements of Corollaries 2.1, 2.2, 2.3 are valid also under the assumptions of the above corollary. The validity of Corollary 2.3 in this case follows from its validity
under the assumptions of Theorem 3.1 (and has been used in the proof above). For the other two, the proof is the same as before.

The following theorem deals with the same case as Corollary 3.2, but without the additional assumption (3.7).

Theorem 3.2. Let $p=1$ and $\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ with $q_{i} \geq 1$. Let $\Omega, g$ and $\underset{\sim}{u}$ satisfy the conditions of Theorem 2.1 with $p$ and $\tilde{q}$ as above. In addition suppose that $g$ is continuous in $\Omega \times \mathrm{R}_{\mathrm{m}}$. Then $\mathrm{v}=\mathrm{g} \bullet \underset{\sim}{u} \mathrm{~B}^{\prime}(\Omega)$ and the strong approximate derivatives $\partial_{x_{i}} v,(i=1, \ldots, n)$, belong to $L_{1}(\Omega)$. Proof. Let $\tilde{u}_{k}$ be a function in $A(\Omega)$ such that $\tilde{u}_{k}=u_{k}$ abe. in $\Omega,(k=1, \ldots, m)$. Denote $v^{*}=g \circ \underset{\sim}{\tilde{u}} ;$ then $v^{*}=v$ are. in $\Omega$.

As in the proof of Theorem 2.1 we have:
(3.9) $\quad v \in L_{1}(\Omega)$ and $\beta_{k} \circ u_{k} \in W_{1,1}(\Omega), \quad(k=1, \ldots, m)$.

Furthermore, $\beta_{k} \circ \tilde{u}_{k} \in A(\Omega)$.
Let $\tau$ be a line parallel to the $x_{i}$-axis such that $\tau$ satisfies conditions $\left(\alpha_{1}\right)-\left(\alpha_{4}\right)$ (which are stated in the proofs of Theorem 2.1 and Theorem 3.1) and in addition:

$$
\left\{\begin{array}{cl}
\left.\tilde{u}_{k}\right|_{\tau \cap \Omega} \in W_{1, q_{k}}(\tau \cap \Omega), & (k=1, \ldots, m) ; \\
\left.\beta_{k} \circ \tilde{u}_{k}\right|_{\tau \cap \Omega} \in W_{1,1}(\tau \cap \Omega), & (k=1, \ldots, m) ; \\
\left.a_{k}\right|_{\tau \cap \Omega} \in L_{q_{k}^{\prime}}(\tau \cap \Omega), & (k=1, \ldots, m) ; \\
\left.b_{k, j} \circ \tilde{u}_{j}\right|_{\tau \cap \Omega} \in L_{q_{k}^{\prime}}(\tau \cap \Omega), & (k, j=1, \ldots, m ; k \neq j) ; \\
\left.v^{*}\right|_{\tau \cap \Omega} \in L_{1}(\tau \cap \Omega) ; \\
\left.b \odot{\underset{\sim}{u}}_{\sim}^{\sim}\right|_{\tau \cap \Omega} \in L_{1}(\tau \cap \Omega) ;
\end{array}\right.
$$

We observe that, since $\tilde{u}_{k} \in W_{l, q_{r}}(\Omega) \cap A(\Omega)$, the first condition in (3.10) is satisfied by a.e. line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis. The same remark applies to the second condition in (3.10). It is clear that also the other conditions in (3.10) as well as $\left(\alpha_{1}\right)-\left(\alpha_{4}\right)$ are satisfied by a.e. line $\tau$ as above.

Let $I$ be an open interval contained in $\tau \cap \Omega$ let $I^{\prime}$ be a compact subinterval of $I$. Denote by $h_{o}$ the distance between I' and the boundary of $I$.

If $x^{\prime}, X^{\prime \prime}$ are two points in $I-N$, the difference $\left|v^{*}\left(x^{\prime}\right)-v^{*}\left(x^{\prime \prime}\right)\right|$ may be estimated as in (3.2). In particular, if $h \neq 0$ is a fixed number such that $|h|<h_{0}$, we have:
(3.11) $\left|\delta_{h}^{i} v^{*}(x)\right| \leq \frac{1}{|h|} \int_{0}^{|h|} a\left(x+\xi e^{i}\right) d \xi+(b \circ \tilde{u})\left(x+h e^{i}\right)$

$$
\begin{aligned}
+\sum_{k=1}^{m}\left[a_{k}(x)\right. & +\left(c_{k}^{(1)} \odot \underset{\sim}{\tilde{u}}\right)(x) \\
& \left.+\left(c_{k}^{(2)} \bullet \underset{\sim}{\tilde{u}}\right)\left(x+h e^{i}\right)\right]\left|\delta_{h}^{i} \tilde{u}_{k}(x)\right|
\end{aligned}
$$

$$
+\sum_{k=1}^{m}\left|\delta_{h}^{i}\left(\beta_{k} \circ \tilde{u}_{k}\right)(x)\right|
$$

for $\mathcal{S}_{1}$ - a.e. point $x \in I^{\prime}$.
Integrating over $I^{\prime}$ and using the one-dimensional version of Lemma 1.5 we obtain:
(3.12) $\left\|\delta_{h}^{i} v^{*}\right\|_{L_{1}\left(I^{\prime}\right)} \leq\|a\|_{L_{1}(I)}+\|b \bullet \underset{\sim}{\sim}\|_{L_{1}}(I)$

$$
\begin{align*}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}(I)}+\left\|c_{k} \circ \underset{\sim}{\tilde{u}}\right\|_{L_{q_{k}^{\prime}}(I)}\right]\left\|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right\|_{L_{q_{k}}}  \tag{I}\\
& +\sum_{k=1}^{m}\left\|\frac{\partial\left(\beta_{k} \circ \tilde{u}_{k}\right)}{\partial x_{i}}\right\|_{L_{1}(I)},
\end{align*}
$$

for all $0<|h|<h_{0}$.
By Lemma 1.7, $\mathrm{v}^{*}$ coincides $\mathcal{S}_{1}$ - ace. in $I$, with a function of bounded variation on $I$. Since this result holds for every subinterval of $\tau \cap \Omega, v^{*}$ coincides $\mathcal{L}_{1}$ - ace. in $\tau \cap \Omega$ with a function $v_{\tau}^{*}$ which is locally of bounded variation on $\tau \cap \Omega$. Moreover (by Lemma 1.7 and (3.12)):
(3.13) tot. var. ${ }_{\tau \cap \Omega}\left[\mathrm{v}_{\tau}^{*}\right] \leq\|\mathrm{a}\|_{\mathrm{L}_{1}(\tau \cap \Omega)}+\|\mathrm{b} \cdot \underset{\sim}{\underset{\sim}{\underset{u}{2}}}\|_{\mathrm{L}_{1}}(\tau \cap \Omega)$

$$
\left.\begin{array}{l}
+\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}}(\tau \cap \Omega)\right. \\
+\left\|c_{k} \bullet \underset{\sim}{\tilde{u}}\right\|_{L_{q_{k}^{\prime}}}(\tau \cap \Omega)
\end{array}\right]\left\|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right\|_{L_{\mathrm{q}_{k}}}(\tau \cap \Omega)
$$

Up to this point we have not made use of the continuity of $g$ in $\Omega \times \mathrm{R}_{\mathrm{m}} \cdot$ We observe now, that by this assumption, $\left.\mathrm{v}^{*}\right|_{\tau \cap \Omega}$ is continuous (because $\left.\tilde{u}\right|_{\tau \cap \Omega}$ is continuous). since $v^{*}=v_{\tau}^{*}$ $\delta_{1}$ - abe. on $\tau \cap \Omega$, it follows that $v^{*}$ is also l.b.v. on $\tau \cap \Omega$. (This is easily verified directly from the definition.) Furthermore, $\mathrm{v}_{\tau}^{*}=\left.\mathrm{v}^{*}\right|_{\tau \cap \Omega}+\mathrm{s}$, where s is a saltus function on $\tau \cap \Omega$, such that $s=0$ everywhere, except on a countable set of points, on $\tau \cap \Omega$, (see Saks [15], p. 97-98). Clearly, $\frac{d s}{d x_{i}}=0$ wherever it exists, so that $\frac{\partial v_{\tau}^{*}}{\partial x_{i}}=\frac{\partial v^{*}}{\partial x_{i}}$. $\delta_{1}$ - ace. on $\dot{\tau} \cap \Omega$. Finally, by a well-known property of functions of bounded variation (see Saks [15], pp. 119 and 121):

$$
\begin{equation*}
\int_{\tau \cap \Omega}\left|\frac{\partial v^{*}}{\partial x_{i}}\right| d x_{i}=\int_{\tau \cap \Omega}\left|\frac{\partial v_{\tau}^{*}}{\partial x_{i}}\right| d x_{i} \leq \text { tot. var. }{ }_{\tau \cap \Omega}\left[v_{\tau}^{*}\right] . \tag{3.14}
\end{equation*}
$$

Note that these results hold for a.e. line $\tau$ parallel to the $x_{i}$-axis, $(i=1, \ldots, n)$. Hence, in particular, $v^{*} \in B(\Omega)$ and the derivatives $\frac{\partial v^{*}}{\partial x_{i}},(i=1, \ldots, n)$, exist a.e. in $\Omega$ and
are measurable there. Combining (3.13) and (3.14) and using Fubini's theorem we get:
(3.15) $\left\|\frac{\partial v^{*}}{\partial x_{i}}\right\|_{L_{1}(\Omega)} \leq\|a\|_{L_{1}(\Omega)}+\|b \cdot \underset{\sim}{\underset{\sim}{u}}\|_{L_{1}}(\Omega)$

$$
\begin{aligned}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}(\Omega)}+\left\|c_{k} \circ \underset{\sim}{\tilde{u}}\right\|_{L_{q_{k}^{\prime}}^{\prime}(\Omega)}\right]\left\|\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right\|_{L_{q_{k}}}(\Omega) \\
& +\sum_{k=1}^{m}\left\|\frac{\partial\left(\beta_{k} \circ \tilde{u}_{k}\right)}{\partial x_{i}}\right\|_{L_{1}(\Omega)}, \quad(i=1, \ldots, n) .
\end{aligned}
$$

Since $v=v^{*}$ a.e. in $\Omega$, the assertion of the theorem is proved.

For the next result we introduce:

Definition 3.1. Let $g$ be a real function defined in $\Omega \times R_{m}$ and let $w_{k}$ be a function in $A(\Omega),(k=1, \ldots, m)$. We shall say that $g$ has the $\left(N^{*}\right)$ property with respect to $\underset{\sim}{w}=\left(w_{1}, \ldots, w_{m}\right)$, if for almost every line $\tau$ parallel to one of the axes in $R_{n}$, the function $g \circ \underset{\sim}{w}$, restricted to $\tau \cap \Omega$, has the ( $N$ ) property (i.e. it takes $\mathcal{E}_{1}$ - null subsets of $\tau \cap \Omega$ into null sets).

The following lemma provides sufficient conditions for a function $g$ to have the $\left(N^{*}\right)$ property.

Lemma 3.1. Let $g$ be an 1.a.c. Caratheodory function in $\Omega \times R_{m}$. Suppose that $g$ satisfies conditions I and II of Theorem 2.1. We assume also that the null set $N=N_{g}$, mentioned in Definition 2.2 (and also in Condition II), satisfies $H_{n-1}(N)=0$. The assumptions on $a, b, a_{k}, b_{k, j}$ are as follows:

$$
\begin{equation*}
0 \leq a \in L_{l}^{l o c}(\Omega) \tag{3.16}
\end{equation*}
$$

$$
\begin{equation*}
0 \leq \mathrm{b} \text { is continuous in } \mathrm{R}_{\mathrm{m}} ; \tag{3.17}
\end{equation*}
$$

(3.18) $a_{k},(k=1, \ldots, m)$ are non-negative measurable functions, finite everywhere in $\Omega$;

$$
\left\{\begin{align*}
& b_{k, j},(k, j=1, \ldots, m) \text { are non-negative Bored functions, }  \tag{3.19}\\
& \text { finite everywhere in } R_{1} ; \\
& 0 \leq b_{k, k} \in L_{l}^{l o c}\left(R_{1}\right),(k=1, \ldots, m)
\end{align*}\right.
$$

Let $w_{k} \in A(\Omega),(k=1, \ldots, m)$, and set $\underset{\sim}{w}=\left(w_{1}, \ldots, w_{m}\right)$.
Suppose that:
(3.20)

$$
\left(b_{k, k}{ }^{0} w_{k}\right) \frac{\partial w_{k}}{\partial x_{i}} \in L_{l}^{l o c}(\Omega), \quad(k=1, \ldots, m ; i=1, \ldots, n)
$$

Then $g$ has the $\left(N^{*}\right)$ property with respect to $\underset{\sim}{w}$.
Proof. Let $M$ be a countable dense subset of $R_{m}$. As in the proof of The orem 2.1 we obtain inequality (2.1)' for $(x, \underset{\sim}{t}) \in\left(\Omega-N_{1}\right) \times R_{m}$, where $N_{1}$ is a null subset of $\Omega$.

Defining $\beta_{k}$ as in Theorem 2.1, we note that by (3.20) and Lemma 1.9, $\beta_{\mathrm{k}}{ }^{\circ} \mathrm{w}_{\mathrm{k}} \in \mathrm{A}(\Omega)$.

Let $\tau$ be a line parallel to the $x_{i}$-axis (the index $i$ will be kept fixed throughout the proof) such that:

We remark that each of the conditions in (3.21) is satisfied by a.e. line $\tau$ parallel to the $x_{i}$-axis. With respect to the first condition, this follows from the fact that $H_{n-1}(N)=0$, since this implies that the projection of $N$ on the hyperplane $x_{i}=0$ is an $f_{n-1}$ null set.

Let $I$ be an open subinterval of $\tau \cap \Omega$ such that $\bar{I} \subset \tau \cap \Omega$. It is sufficient to show that $\mu=g$ © $\underset{\sim}{w}$ has the (N) property on I.

By (2.17) and (2.19) we obtain:
(3.22) $\left|\mu\left(x^{\prime}\right)-\mu\left(x^{\prime \prime}\right)\right| \leq\left|\int_{x_{i}^{\prime}}^{x_{i}^{\prime \prime}} a(x) d x_{i}\right|+(b \circ \underset{\sim}{w})\left(x^{\prime}\right)\left|x_{i}^{\prime}-x_{i}^{\prime \prime}\right|$

$$
\begin{aligned}
+\sum_{k=1}^{m}\left[a_{k}\left(x^{\prime \prime}\right)\right. & +\left(c_{k}^{(1)} \bullet \underset{\sim}{\underset{\sim}{w}}\left(x^{\prime}\right)\right. \\
& \left.+\left(c_{k}^{(2)} \bullet \underset{\sim}{w}\right)\left(x^{\prime \prime}\right)\right]\left|w_{k}\left(x^{\prime}\right)-w_{k}\left(x^{\prime \prime}\right)\right|
\end{aligned}
$$

$$
+\sum_{k=1}^{m}\left|\left(\beta_{k} \circ w_{k}\right)\left(x^{\prime}\right)-\left(\beta_{k} \circ w_{k}\right)\left(x^{\prime \prime}\right)\right|
$$

for every $x^{\prime}, x^{\prime \prime} \in I$. (Here we use the fact that $I$ does not intersect N.)

Let $Q$ be an $\mathcal{X}_{1}$-null subset of $I$. We have to show that $\mu(Q)$ is a null set.

Let:

$$
\begin{array}{r}
J_{l}=\left\{x \in I \mid a_{k}(x) \leq \ell,\left(b_{k, j} \bullet w_{j}\right)(x) \leq \ell \text { for } k, j=1, \ldots, m ;\right.  \tag{3.23}\\
k \neq j\}
\end{array}
$$

where $l=1,2, \ldots$ Then $I=U_{1}^{\infty} J_{l}$ and we set $Q_{l}=Q \cap J_{l}$.
In the next part of the proof we shall keep $l$ fixed. It is sufficient to prove that $\mu\left(Q_{l}\right)$ is a null set.

Given $\mathcal{E}>0$, let $O$ be an open subset of $I$ containing $Q_{\ell}$ such that $\boldsymbol{\chi}_{1}(0)<\boldsymbol{E}$. The set 0 may be written as a countable union of disjoint open intervals $\left\{I_{\nu}\right\}_{\nu=1}^{\infty}$. We may assume that every interval $I_{\nu}$ contains at least one point of
$Q_{\ell}$; we pick such a point in $I_{\nu}$ and denote it by $x^{\nu}$. Let $x^{\prime} \in I_{\nu} \cap Q_{l}$. Then by (3.22) and (3.23):
(3.24)

$$
\begin{aligned}
\left|\mu\left(x^{\prime}\right)-\mu\left(x^{\nu}\right)\right| \leq & \int_{I_{\nu}} a(x) d x_{i}+\mathcal{L}_{1}\left(I_{\nu}\right) \sup _{I} b \circ W \\
& +c_{1} \sum_{k=1}^{m}\left|w_{k}\left(x^{\prime}\right)-w_{k}\left(x^{\nu}\right)\right| \\
& +\sum_{k=1}^{m}\left|\beta_{k} \circ w_{k}\left(x^{\prime}\right)-\beta_{k} \circ w_{k}\left(x^{\nu}\right)\right|,
\end{aligned}
$$

where $c_{1}$ is a constant depending only on $m$. Note that $b \circ \underset{\sim}{w}$ is continuous on $\tau \cap \Omega$ so that $\sup _{\mathrm{b}} \mathrm{b} \bullet \underset{\sim}{\boldsymbol{w}}<\infty$.

Denote $s_{\nu}=\sup _{x^{\prime} \in I_{\nu} \cap Q_{l}}\left|\mu\left(x^{\prime}\right)-I^{\prime} \mu\left(x^{\nu}\right)\right|$. Then, by (3.24):

$$
\begin{align*}
\sum_{l}^{\infty} s_{\nu} & \leq \int_{0} a(x) d x_{i}+\varepsilon \cdot \sup _{I}(b a \underset{\sim}{w})+c_{1} \ell \sum_{k=1}^{m} \int_{0}\left|\frac{\partial w_{k}}{\partial x_{i}}\right| d x_{i}  \tag{3.25}\\
& +\sum_{k=1}^{m} \int_{0}\left|\frac{\partial\left(\beta_{k} \bullet w_{k}\right)}{\partial x_{i}}\right| d x_{i} .
\end{align*}
$$

All the integrals in (3.25) are integrals of functions belonging to $L_{1}(I)$. Hence, they tend to zero when $\boldsymbol{\varepsilon} \rightarrow 0$.

Obviously $\mu\left(Q_{\ell}\right)$ is covered by a countable family of closed intervals whose total length is $\begin{gathered}\infty \\ 2 \\ \\ l\end{gathered} s_{\nu}$. Hence, the outer measure of $\mu\left(Q_{\ell}\right)$ is bounded by twice the right side of (3.25), which tends to zero when $\varepsilon \rightarrow 0$. Hence $\mu\left(Q_{\ell}\right)$ is a null set. This
completes the proof of the lemma.

Theorem 3.3. Let $p=1$ and $\tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ with $q_{i} \geq 1$. Suppose that $\Omega, g$ and $\underset{\sim}{u}$ are as in Theorem 2.1 with $p$ and $\tilde{q}$ as above. In addition suppose that $g$ is continuous in $\Omega \times R_{m}$, that $f_{n-1}(N)=O$ (where $N=N_{g}$ ) and that the functions $a_{k}$, $b_{k, j},(k, j=1, \ldots, m ; k \neq j)$ are finite everywhere in $\Omega$ and $R_{1}$ respectively.

Then $v=g \bullet \underset{\sim}{u} \in W_{1,1}(\Omega)$.
Proof. By Theorem $3.2 \mathrm{v} \in \mathrm{B}^{\prime}(\Omega)$. Let $\tilde{u}_{k}$ be a function in $A(\Omega)$ such that $\tilde{u}_{k}=u_{k}$ a.e. in $\Omega$. If $v^{*}=g \bullet \underset{\sim}{\sim}$, then $v^{*}=v$ a.e. in $\Omega$. Furthermore $v^{*}$ is continuous on $\tau \cap \Omega$, for a.e. line $\tau$ parallel to one of the axes in $R_{n}$. Therefore, $v^{*} \in B(\Omega)$, (see Definition 1.1).

By Lemma 3.1, $g$ has the $\left(N^{*}\right)$ property with respect to $\underset{\sim}{\sim}$. Hence, for a.e. line $\tau$ parallel to one of the axes in $R_{n}$, $\left.v^{*}\right|_{\tau \cap \Omega}$ has the following properties: it is continuous, it has the (N) property and it is locally of bounded variation. Therefore, by a theorem of Banach-Zarecki (see Saks [15], p.227) $\left.\mathrm{v}^{*}\right|_{\tau \cap \Omega}$ is l.a.c. on $\tau \cap \Omega$. Hence $v^{*} \in A(\Omega)$.

Again by Theorem 3.2, $\frac{\partial v^{*}}{\partial \mathrm{x}_{\mathrm{i}}} \in \mathrm{L}_{1}(\Omega),(i=1, \ldots, n)$. Hence, by Lemma 1.4, $v \in W_{1,1}(\Omega)$. This completes the proof of the theorem.
§4. Demicontinuity of $G: W_{1, \tilde{q}}(\Omega) \rightarrow W_{1, p}(\Omega)$
In this section we describe first a general class of conditions on $g$ which ensure that $G$ is a demicontinuous (i.e. "strong $\longrightarrow$ weak" continuous) mapping from $\mathrm{W}_{1, \tilde{\mathrm{q}}}(\Omega)$ to $\mathrm{W}_{1, \mathrm{p}}(\Omega)$. Then in order to illustrate the scope of our theorem we give a relatively explicit result in which $g$ is assumed to satisfy power type growth conditions. The methods are based on those used in proving Theorem 2.l.

Our main result follows. Recall that a bounded transformation between normed spaces is one which maps bounded sets to bounded sets.

Theorem 4.1. Let $\Omega$ be a bounded domain in $R_{n}$ possessing the cone property and let $p>1, \tilde{q}=\left(q_{1}, \ldots, q_{m}\right), q_{i} \geq p$, be given. Suppose that $g$ is an l.a.c. Caratheodory function in $\Omega \times R_{m}$ which fulfills the estimates of Theorem 2.1 with functions $a, b$, $a_{k}, b_{k, j}$ which satisfy (2.3)-(2.7), $a_{k}$ and $b_{k, j}$ being everywhere finite. Suppose also that $b_{k, k}$ is continuous, $k=1, \ldots, m$, and that under functional composition the functions $b, b_{k, j}$, $\mathrm{k}, \mathrm{j}=1, \ldots, \mathrm{~m}$, satisfy:

$$
\begin{align*}
& \left\{\begin{array}{l}
\mathrm{b}_{\mathrm{k}, \mathrm{j}} \text { defines a mapping from } \mathrm{L}_{\mathrm{q}_{j}^{*}}(\Omega) \text { to } \mathrm{L}_{\mathrm{q}_{\mathrm{k}}^{\prime}}(\Omega), \\
\mathrm{q}_{\mathrm{j}}^{*}=\frac{n q_{j}}{n-q_{j}} ;
\end{array}\right.  \tag{4.1}\\
& \text { b defines a mapping from } \mathrm{L}_{\mathrm{q}_{1}^{*}}(\Omega) \times \ldots \times \mathrm{L}_{\mathrm{q}_{\mathrm{m}}}(\Omega) \text { to } \mathrm{L}_{\mathrm{p}}(\Omega) \text {. }
\end{align*}
$$

Then $G$ maps $W{ }_{1, \tilde{q}}^{(\Omega)}$ into $W_{1, p}(\Omega)$ and is demicontinuous. Moreover $G$ is continuous as a mapping from $W_{1, \underset{q}{\sim}}^{(\Omega)}$ to $L_{p}(\Omega)$.

Remark 4.1. It is implied by (4.1) that the following estimates hold ([7], Theorem 1 (slightly modified)):

$$
\left\{\begin{array}{l}
\left|b_{k, j}(\sigma)\right| \leq c_{k, j}+d_{k, j}|\sigma|^{q_{k}^{\prime} / q_{j}^{*}}, \quad k, j=1, \ldots, m  \tag{4.2}\\
\left|b\left(\sigma_{1}, \ldots, \sigma_{m}\right)\right| \leq c\left(1+\left|\sigma_{1}\right|^{q_{1}^{*}}+\ldots+\left|\sigma_{m}\right|^{q_{m}^{*}} 1 / p\right.
\end{array}\right.
$$

Thus all the composition mappings in (4.1) are bounded. In addition, the mappings associated with $b_{k, k}(k=1, \ldots, m)$ and with $b$ are continuous ([9],[11],[13]).

Proof. In order to prove demicontinuity we must show that for any sequence ${\underset{\sim}{u}}^{\nu}=\left(u_{1}^{\nu}, \ldots, u_{m}^{\nu}\right), \nu \geq 1$, convergent to a limit ${\underset{\sim}{u}}^{\circ}=\left(u_{1}^{\circ}, \ldots, u_{m}^{o}\right)$ in $\underset{1, \underset{q}{w}}{(\Omega)}$, the functions $v^{\nu}={\underset{\sim}{u}}^{\nu}$ converge weakly to $\mathrm{v}^{\mathrm{O}}=\mathrm{Gu}_{\sim}^{\circ}$ in $\mathrm{W}_{1, \mathrm{p}}(\Omega)$.

We show first that the sequence $v^{\nu}$ converges to $v^{0}$ in $L_{p}(\Omega)$. According to (2.17) we have for all $x \in \Omega-N$,
(4.3) $\left|g(x, \underset{\sim}{u}(x))-g\left(x, \underset{\sim}{u}{ }^{o}(x)\right)\right| \leq \sum_{k=1}^{m}\left[a_{k}(x)+c_{k}^{(1)}\left(\underset{\sim}{u}{ }^{\nu}(x)\right)\right.$

$$
\left.+c_{k}^{(2)}\left(u_{\sim}^{o}(x)\right)\right]\left|{\underset{\sim}{k}}_{\nu}^{\nu}(x)-u_{k}^{o}(x)\right|
$$

$$
+\sum_{k=1}^{m}\left|\beta_{k}\left(u_{k}^{\nu}(x)\right)-\beta_{k}\left(u_{k}^{o}(x)\right)\right|
$$

where the $\beta_{k}$ are defined as in (2.13). Now by Sobolev's imbedding theorem, $u_{k}^{\nu} \in L_{q_{k}}(\Omega), \nu \geq 0$, and the convergence of


Thus (4.1 $)$ and Corollary 1.2 give

$$
\begin{equation*}
\partial_{x_{i}}\left(\beta_{k} \circ u_{k}^{\nu}\right)=\left(b_{k, k} \circ u_{k}^{\nu}\right) \partial_{x_{i}} u_{k}^{\nu}, \quad \nu=\dot{0}, 1, \ldots \tag{4.4}
\end{equation*}
$$

Moreover by using Remark 4.1 we also deduce that

$$
b_{k, k} \circ u_{k}^{\nu} \rightarrow b_{k, k} \circ u_{k}^{\circ} \quad \text { in } \quad L_{q_{k}^{\prime}}(\Omega), \quad k=1, \ldots, m
$$

Applying this result to (4.4) we obtain:
(4.5) $\left\|\partial_{x_{i}}\left(\beta_{k} \circ u_{k}^{\nu}\right)-\partial_{x_{i}}\left(\beta_{k} \circ u_{k}^{o}\right)\right\|_{L_{p}(\Omega)} \leq\left\|b_{k, k} \circ u_{k}^{\nu}-b_{k, k} \circ u_{j k}^{o}\right\|_{L_{q_{k}^{\prime}}^{\prime}}(\Omega) \times$

$$
\begin{gathered}
\times\left\|\partial_{x_{i}} u_{k}^{\nu}\right\|_{L_{q_{k}}}(\Omega) \\
+\left\|b_{k, k} \circ u_{k}^{o}\right\|_{L_{q_{k}^{\prime}}(\Omega)}\left\|\partial_{x_{i}} u_{k}^{\nu}-\partial_{x_{i}} u_{k}^{o}\right\|_{L_{q_{k}}}(s
\end{gathered}
$$

$$
\rightarrow 0
$$

Moreover, we obtain from (4.2) the following estimate
(4.6) $\left|\beta_{k}\left(\sigma^{\prime}\right)-\beta_{k}\left(\sigma^{\prime \prime}\right)\right|=\left|\int_{\sigma^{\prime}}^{\sigma^{\prime \prime}} b_{k, k}(\sigma) d \sigma\right|$

$$
\leq\left[c_{k}+\alpha_{k}\left(\left|\sigma^{\prime \prime}\right|^{q_{k}^{*} / q_{k}^{1}}+\left|\sigma^{\prime}\right|^{q_{k}^{*} / q_{k}^{1}}\right)\right]\left|\sigma^{\prime \prime}-\sigma^{\prime}\right|
$$

This ensures that the sequence $\beta_{k} \circ u_{k}^{\nu}$ converges in $L_{p}(\Omega)$ :
where $\frac{1}{r_{k}}=\frac{1}{p}-\frac{1}{q_{k}^{*}}=\frac{1}{q_{k}^{1}}-\frac{1}{n}$.

$$
\begin{align*}
& \left\|\beta_{k} \circ u_{k}^{\nu}-\beta_{k} \circ u_{k}^{o}\right\|_{L_{p}(\Omega)} \leq\left\|c_{k}+\alpha_{k}\left(\left|u_{k}^{\nu}\right|^{q_{k}^{*} / q_{k}^{\prime}}+\left|u_{k}^{o}\right|^{q_{k}^{*} / q_{k}^{\prime}}\right)\right\|_{L_{r_{k}}(\Omega)}\left\|u_{k}^{\nu}-u_{k}^{o}\right\|_{L^{*}}(\Omega) \\
& \leq \mathscr{\mathcal { L }}_{\mathrm{n}}(\Omega)^{1 / \mathrm{n}}\left[\mathrm{c}_{\mathrm{k}} \boldsymbol{\mathcal { L }}_{\mathrm{n}}(\Omega)^{1 / \mathrm{q}_{\mathrm{k}}^{\prime}}+\right. \\
& \left.+d_{k}\left(\left\|u_{k}^{\nu}\right\|_{L_{k}^{*}(\Omega)}^{q_{k}^{*} / q_{k}^{\prime}}+\left\|u_{k}^{o}\right\|_{L_{k}^{*}(\Omega)}^{q_{k}^{*} / q_{k}^{\prime}}\right)\right]\left\|u_{k}^{\nu}-u_{k}^{o}\right\|_{L_{k}^{*}} \\
& \rightarrow 0,
\end{align*}
$$

Utilizing this fact in conjunction with ( $4.1_{1}$ ) we obtain from (4.3) the estimate
(4.7) $\left\|v^{\nu}-v^{o}\right\|_{L_{p}(\Omega)} \leq \sum_{k=1}^{m}\left[\left\|a_{k}+c_{k}^{(1)} \bullet{\underset{\sim}{u}}^{\nu}+c_{k}^{(2)} \bullet{\underset{\sim}{u}}^{o}\right\|_{L_{q_{k}^{\prime}}(\Omega)}\left\|u_{k}^{\nu}-u_{k}^{o}\right\|_{L_{q_{k}}}\right.$

$$
+\sum_{k=1}^{m}\left\|\beta_{k} \circ u_{k}^{\nu}-\beta_{k} \circ u_{k}^{o}\right\|_{L_{p}}(\Omega)
$$

$\rightarrow 0$.

In order to complete the proof it suffices, by reflexivity of $L_{p}(\Omega)$, to show that for each $i$ the functions $\partial_{x_{i}} v^{\nu}$ form a bounded set in $L_{p}(\Omega)$. For it then follows, by a standard argument, that $\partial_{x_{i}} v^{\nu} \rightarrow \partial_{x_{i}} v^{0}$ weakly in $L_{p}(\Omega)$ and hence $v^{\nu} \rightarrow v^{0}$ weakly in $W_{1, p}(\Omega)$. However, by (2.22) we have for any open subset $\Omega^{\prime}$ of $\Omega$ such that $\overline{\Omega^{\prime}} \subset \Omega$ the estimate
(4.8) $\left\|\delta_{h}^{i} v^{\nu}\right\|_{L_{p}\left(\Omega^{\prime}\right)} \leq\|a\|_{L_{p}(\Omega)}+\left\|b \bullet \underset{\sim}{u}{ }^{\nu}\right\|_{L_{p}}$

$$
\begin{aligned}
& +\sum_{k=1}^{m}\left[\left\|a_{k}\right\|_{L_{q_{k}^{\prime}}(\Omega)}+\left\|c_{k} \circ{\underset{\sim}{u}}^{\nu}\right\|_{L_{q_{k}^{\prime}}^{\prime}(\Omega)}\right]\left\|\partial_{x_{i}} u_{k}^{\nu}\right\|_{L_{q_{k}}}(\Omega) \\
& +\sum_{k=1}^{m}\left\|\partial_{x_{i}}\left(\beta_{k} \circ u_{k}^{\nu}\right)\right\|_{L_{p}(\Omega)}, \quad\left(0<|h|<h_{o}\right), \quad j=1, \ldots, h .
\end{aligned}
$$

By (4.2) and (4.5) the right side of (4.8) is bounded uniformly in $\nu$, and hence by Lemma 1.6 we have the requisite boundedness
for $\left\|\partial_{x_{i}} v^{\nu}\right\|_{L_{p}(\Omega)}, \quad i=1, \ldots, n, \nu \geq 0$.

The next result can be regarded as a corollary to Theorem 4.1. As mentioned above it is stated primarily for illustrative purposes.

Theorem 4.2. Let $\Omega$ be a bounded domain in $R_{n}$ possessing the cone property and let $p>1, \tilde{q}=\left(q_{1}, \ldots, q_{m}\right)$ with $q_{i} \geq p$, be given. Suppose that $g$ is an l.a.c. Caratheodory function in $\Omega \times R_{m}$ which satisfies the following estimates for certain functions $a \in L_{p}(\Omega), a_{k} \in L_{q_{k}^{\prime}}(\Omega), k=1, \ldots, m:$
(II) $\quad\left|\frac{\partial g(x, \underset{\sim}{t})}{\partial t_{k}}\right| \leq a_{k}(x)+b_{k} \sum_{j=1}^{m}\left|t_{j}\right|^{\nu_{k}, j} \quad$ for $\operatorname{all} \quad(x, \underset{\sim}{t}) \in(\Omega-N) \times R_{m}$ at which the left side exists, where $\nu_{k, j}=q_{j}^{*} / q_{k}^{1}$ (k = 1,..., m).

Here $N=N_{g}$ is the null set mentioned in Definition 2.1.
Then $G$ maps $W_{1, \tilde{q}^{(\Omega)}}^{(\Omega)}$ into $W_{1, p}(\Omega)$ and is demicontinuous.


## §5. Chain Rules

In the present section we describe certain results in which the mapping $G$ has the additional feature that a chain rule holds. That is, one has, for each $i=1, \ldots, n$, equality between the derivative $\partial_{x_{i}}(g \circ \underset{\sim}{u})$ and the (properly interpreted) combination $\left(\partial_{x_{i}} g\right) \bullet \underset{\sim}{u}+\left[\left(\nabla_{\sim}^{u} g\right) \circ \underset{\sim}{u}\right] \partial_{x_{i}} \underset{\sim}{u}$. Associated with the existence of such a chain rule are, as is clear, stronger continuity
properties than in previous sections.
Our first result applies to functions $g$ which are independent of $x$.

Lemma 5.1. Let $I$ be an open interval in $R_{1}$. Let $g=g\left(t_{1}, \ldots, t_{m}\right)$ be an l.a.c. Caratheodory function (i.e. $g$ is continuous in $R_{m}$ and the restriction of $g$ to any line parallel to one of the axes in $R_{m}$ is an l.a.c. function).

Suppose that the inequality:
(5.1) $\quad\left|\frac{\partial g(\underset{\sim}{t})}{\partial t_{k}}\right| \leq a_{k}+\sum_{j=1}^{m} b_{k, j}\left(t_{j}\right), \quad(k=1, \ldots, m)$,
holds at every point in $R_{m}$ at which the estimated derivative exists, where $a_{k}$ are constants and the functions $b_{k, j}$ satisfy the conditions described below.
(5.2) $0 \leq b_{k, j}$ is a real valued Borel function on $R_{1}$,

$$
(k, j=1, \ldots, m ; k \neq j)
$$

$$
\begin{equation*}
0 \leq b_{k, k} \in L_{l}^{l o c}\left(R_{1}\right), \quad(k=1, \ldots, m) \tag{5.3}
\end{equation*}
$$

Let $w_{k}: I \rightarrow R_{1}$ be an l.a.c. function such that $w_{k}^{\prime} \in L_{q}^{l o c}(I)$, $(k=1, \ldots, m)$, for some $q, \quad 1 \leq q<\infty$. Denote $\underset{\sim}{w}=\left(w_{1}, \ldots, w_{m}\right)$.

Suppose that $g$ has a differential at each point of the set $T_{w}=\underset{\sim}{W}(I) \subset R_{m}$, except for an $H_{1}-$ null set.

Finally suppose that:
(5.4) $\quad b_{k, j} \circ w_{j} \in L_{q^{\prime}}^{l o c}(I), \quad(k, j=1, \ldots, m ; k \neq j)$, where $\frac{1}{q^{\prime}}+\frac{1}{q}=1$,

$$
\begin{equation*}
\left(b_{k, k} \circ w_{k}\right) w_{k}^{\prime} \in L_{l}^{l o c}(I), \quad(k=1, \ldots, m) \tag{5.5}
\end{equation*}
$$

Then $\mu=g \circ \underset{\sim}{w}$ is l.a.c. on $I$ and the chain rule holds, i.e.

$$
\begin{equation*}
\mu^{\prime}=\sum_{k=1}^{m}\left(\frac{\partial g}{\partial t_{k}} \bullet \underset{\sim}{w}\right) w_{k}^{\prime}, \quad \mathscr{L}_{1}-\text { a.e. on } \quad I, \tag{5.6}
\end{equation*}
$$

the products on the right being interpreted as zero whenever their second factor is zero.

Proof. By Theorem 3.3 (for the case $n=1$ ), $\mu \in W_{1,1}^{l o c}(I)$. But $\mu$ is continuous on $I$; hence $\mu$ is l.a.c. on I. (Recall that every function in $W_{l, 1}^{l o c}(I)$ coincides ace. in $I$ with an 1.a.c. function.)

Denote by $\sigma$ a general point in $R_{1}$. Let $J=[a, b]$ be a compact subinterval of $I$. Let $s$ be the arc length of the absolutely continuous curve $\underset{\sim}{w}=\underset{\sim}{w}(\sigma), a \leq \sigma \leq b$, with $s(a)=0$.

Then $s$ is a monotonic increasing, absolutely continuous function
 $0 \leq s \leq s(b)$.

There exists a unique function $\underset{\sim}{\underset{\sim}{w}}=\underset{\sim}{w}(s),\left(s \in J^{*}\right)$, such that $\underset{\sim}{w}(s(\sigma))=\underset{\sim}{w}(\sigma),(\sigma \in J)$. Indeed, if $\sigma_{1}, \sigma_{2}$ are two distinct points in $J$ such that $s\left(\sigma_{1}\right)=s\left(\sigma_{2}\right)$, it follows (by monotonicity) that $s(\sigma)=$ const. in the interval between $\sigma_{1}$ and $\sigma_{2}$ and hence $s^{\prime}(\sigma)=|\underset{\sim}{w}(\sigma)|=0$ in this interval. But an absolutely continuous function whose derivative is zero a.e. in an interval is necessarily a constant in that interval. Hence $\underset{\sim}{\underset{\sim}{w}}\left(\sigma_{1}\right)=\underset{\sim}{w}\left(\sigma_{2}\right)$.

Furthermore $\left|\underset{\sim}{w}\left(s_{1}\right)-\underset{\sim}{w}\left(s_{2}\right)\right| \leq\left|s_{1}-s_{2}\right|, \forall s_{1}, s_{2} \in J^{*}$, (see Saks [13], p. 123). Hence $\underset{\sim}{w}{ }^{*}$ is absolutely continuous and in fact Lipschitz in $J^{*}$. Therefore, by Lemma 1.9, we have:
(5.7) $\quad \frac{d \underset{\sim}{w}(\sigma)}{d \sigma}=\frac{d{\underset{\sim}{w}}^{*}}{d s}(s(\sigma)) \cdot s^{\prime}(\sigma)$, a.e. in J.

Noting that by (5.4) $\left(\mathrm{b}_{\mathrm{k}, \mathrm{j}} \circ \mathrm{w}_{j}\right)\left|\underset{\sim}{w^{\prime}}(\sigma)\right| \in \mathrm{L}_{1}(J)$, we have (by a known theorem on change of variables; see for instance Federer [5], p. 245):

$$
\begin{equation*}
\int_{0}^{s(b)}\left(b_{k, j} \circ w_{j}^{*}\right)(s) d s=\int_{a}^{b}\left(b_{k, j} \circ w_{j}\right)(\sigma) s^{\prime}(\sigma) d \sigma \tag{5.8}
\end{equation*}
$$

so that $b_{k, j} \circ w_{j}^{*} \in L_{1}\left(J^{*}\right)$.
By Lemma l.8, $w_{k}^{\prime}=\left[\frac{d w_{k}^{*}}{d s} 0 \mathrm{~s}\right] s^{\prime}, \boldsymbol{L}_{1}-$ a.e. in J. Hence, by (5.5), $\left(b_{k, k} \circ w_{k}\right)\left[\frac{d w_{k}^{*}}{d s} \circ s\right] s^{\prime} \in L_{1}(J)$. Therefore, by the same theorem
on change of variables we have:

$$
\begin{equation*}
\int_{0}^{s(b)}\left(b_{k, k} 0 w_{k}^{*}\right)(s) \frac{d w_{k}^{*}(s)}{d s} d s=\int_{a}^{b}\left(b_{k, k} 0 w_{k}\right)(\sigma) \frac{d w_{k}^{*}(s(\sigma))}{d s} s^{\prime}(\sigma) d \sigma \tag{5.9}
\end{equation*}
$$

so that $\left(b_{k, k} 0 w_{k}^{*}\right) \frac{d w_{k}^{*}}{d s} \in L_{1}(J)$.
Finally $w_{k}^{*}$ is Lipschitz in $J$ and $\left|\frac{d w_{k}^{*}}{d s}\right| \leq 1 \quad \mathcal{L}_{l}-$ a.e. in $J$, so that $w_{k}^{*} \in W_{1,1}(J),(k=1, \ldots, m)$.

Hence $g$ and $\underset{\sim}{w}$ * satisfy all the assumptions of Theorem 3.3 in $J$ so that $g \circ \underset{\sim}{\underset{\sim}{w}}=\mu^{*}$ is l.a.c. in $J^{*}$.

Now, if $\sigma_{0}$ is a point in $J$ such that $\frac{d w}{d \sigma}$ exists at $\sigma_{0}$ and the differential of $g$ exists at $\underset{\sim}{y}=\underset{\sim}{w}\left(\sigma_{0}\right)$, then (5.6) holds, as can be verified by an elementary computation. Let $M$ be the set of points in $J$ where at least one of these conditions does not hold. Then $M$ consists of a null set, plus a set $M^{\prime}$ such that $\underset{\sim}{\underset{\sim}{w}}\left(M^{\prime}\right)$ is an $H_{1}-$ null set. Hence, by Lemma 1.8, dm $\frac{d w}{d \sigma}=0 \mathcal{L}_{1}$ - a.e. in M. It follows that $s^{\prime}=0 \mathcal{L}_{1}$ - a.e. in $M$, so that $s(M)$ is a null set (Saks [15], p. 227). This implies that $\mu(M)=\mu^{*}(S(M))$ is a null set. Here we use the fact that $\mu^{*}$ is 1.a.c. on $J^{*}$. Appealing once more to Lemma 1.8, and using the fact that $\mu$ is ac. in $J$, we conclude that $\frac{d \mu}{d \sigma}=0$ $\mathcal{L}_{1}$ - a.e. in M. Therefore (5.6) holds $\mathscr{L}_{1}$ - a.e. in $M$ and everywhere in $J-M$. Since $J$ was an arbitrary compact subinterval of $I$, the proof is completed.

Theorem 5.1. Let $\Omega$ be a domain in $R_{n}$. Let $g=g\left(t_{1}, \ldots, t_{m}\right)$ be an l.a.c. Caratheodory function which satisfies all the assumptions of Lemma 5.1.

Let $u_{k} \in W_{l, q}^{l o c}(\Omega)$, for some $q, 1 \leq q<\infty,(k=1, \ldots, m)$. Denote $\underset{\sim}{u}=\left(u_{1}, \ldots, u_{m}\right)$.

Letting $S_{g}$ denote the set of points in $R_{m}$ where $g$ does not possess a differential, suppose that $S_{g}$ intersects every absolutely continuous curve in $R_{m}$, on an $H_{1}$-null set.

Finally suppose that:

$$
\begin{gather*}
b_{k, j} \circ u_{j} \in L_{q^{\prime}}^{l o c}(\Omega), \quad(k, j=1, \ldots, m ; k \neq j), \text { where } \frac{1}{q^{\prime}}+\frac{1}{q}=1,  \tag{5.10}\\
\left(b_{k, k} \circ u_{k}\right) \frac{\partial u_{k}}{\partial x_{i}} \in L_{l}^{l o c}(\Omega), \quad(k=1, \ldots, m)
\end{gather*}
$$

Then $v=g \circ \underset{\sim}{u}$ is in $W_{l, l}^{l o c}(\Omega)$ and the chain rule holds:

$$
\begin{equation*}
\partial_{x_{i}} v=\sum_{k=1}^{m}\left(\frac{\partial g}{\partial t_{k}} \bullet \underset{\sim}{u}\right) \partial_{x_{i}} u_{k}, \quad \text { a.e. in } \Omega \tag{5.12}
\end{equation*}
$$

the products on the right being interpreted as zero whenever their second factor is zero.

Proof. By Theorem 3.3, $v \in W_{l, l}^{l o c}(\Omega)$. If $\tilde{u}_{k}$ is a function in $A(\Omega)$ such that $\tilde{u}_{k}=u_{k}$ abe. in $\Omega$ then $v^{*}=g \circ \underset{\sim}{\tilde{u}}$ is continuous on $\tau \cap \Omega$ for ace. line $\tau$ parallel to one of the axes in $R_{n}$. Furthermore $\mathrm{v}^{*}=\mathrm{v}$ a.e. in $\Omega$. Therefore, by Lemma 1.4, $v^{*} \in A(\Omega)$.

Let $\tau$ be a line parallel to the $x_{i}$-axis such that $\underset{\sim}{\underset{\sim}{u}}$ iss J.a.c. on $\tau \cap \Omega$ and such that:
(5.13)

$$
\begin{cases}\left.\frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right|_{\tau \cap \Omega} ^{\in L_{q}^{l o c}(\tau \cap \Omega),} \\ \left.b_{k, j} \circ \tilde{u}_{j}\right|_{\tau \cap \Omega} \in L_{q^{\prime}}^{l o c}(\tau \cap \Omega), & (k=1, \ldots, m) ; \\ {\left[\left.\left.\left(b_{k, k} \circ \tilde{u}_{k}\right) \frac{\partial \tilde{u}_{k}}{\partial x_{i}}\right|_{\tau \cap \Omega}\right|_{l} ^{l o c}(\tau \cap \Omega),\right.} & (k=1, \ldots, m) .\end{cases}
$$

Since $\frac{\partial \widetilde{u}_{k}}{\partial x_{i}}=\partial_{x_{i}} u_{k}$ a.e. in $\Omega,(k=l, \ldots, m)$, it is clear that these conditions are satisfied by a.e. line $\tau$ parallel to the $x_{i}$-axis.

By Lemma 1.5, $\mathrm{v}^{*}$ is 1.a.c. on $\tau \cap \Omega$ and:

$$
\begin{equation*}
\frac{\partial v^{*}}{\partial x_{i}}=\sum_{k=1}^{m}\left(\frac{\partial g}{\partial t_{k}} \circ \underset{\sim}{\tilde{u}}\right) \frac{\partial \widetilde{u}_{k}}{\partial x_{i}}, \quad \mathscr{L}_{1}-\text { a.e. on } \tau \cap \Omega . \tag{5.14}
\end{equation*}
$$

As $g$ is continuous on every line parallel to one of the axes in $R_{m}, g$ is a Bore function (see Caratheodory [4]). Hence $\frac{\partial g}{\partial t_{k}}$ is a Bored function (Marcus and Mizel [12], Lemma 4.1). Therefore, the right side of (5.14) is a measurable function in $S$, and of course, the same is true of the left side of (5.14) (by Lemma 1.2). Since (5.14) holds $\mathcal{X}_{1}$ - abe. on $\tau \cap \Omega$ for ace. line $\tau$ parallel to the $\mathrm{x}_{\mathrm{i}}$-axis, it follows
that it holds a.e. in $\Omega$.
Finally, since $\frac{\partial v^{*}}{\partial x_{i}}=\partial_{x_{i}} v$ a.e. in $\Omega$ (Lemma 1.4), (5.12) follows from (5.14). This completes the proof of the theorem.

Remark. Other cases in which the chain rule holds, for composition of functions of the form discussed above, are presented in Marcus and Mizel [12]. As noted in the Introduction, the methods used there are quite different from those of the present paper. We mention in particular that if $g$ depends not only on $\underset{\sim}{t}$ but also on $x$ and if it is a locally Lipschitz function in $\Omega \times R_{m}$, then under a hypothesis on $S_{g}$ as above, the chain rule holds for $v=g \circ \underset{\sim}{u}$ with $u_{k} \in W_{l, 1}^{l o c}(\Omega),(k=1, \ldots, m)$ ([12], Theorem 2.1).

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[^0]:    DEPARTMENT OF MATHEMATICS
    CARNEGIE-MELLON UNIVERSITY
    PITTSBURGH, PENNSYLVANIA 15213

