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SOME FUNCTION-THEORETIC ASPECTS
OF DISCONJUGANCY OF
LINEAR-DIFFERENTIAL SYSTEMS

by

Meira Lavie

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1. Introduction.

In this paper we consider linear differential systems of the form

$$(1.1) \quad \underline{y}'(z) = P(z)\underline{y}(z)$$

where $\underline{y}(z)$ is the column vector $(y_1(z), \dots, y_n(z))$ and $P(z)$ is the $n \times n$ matrix $[p_{ik}(z)]_1^n$, where the n^2 analytic functions $p_{ik}(z)$ are regular in the domain D . Following Schwarz [8], we shall say that (1.1) is disconjugate in D if for every choice of n (not necessarily distinct) points z_1, z_2, \dots, z_n in D , the only solution of (1.1), which satisfies $y_i(z_i) = 0$ $i = 1, 2, \dots, n$ is the trivial one $\underline{y}(z) \equiv 0$.

Various aspects and applications of systems disconjugancy were considered by Nehari [6], Schwarz [8], London and Schwarz [3], and Kim [1]. Considering disfocality of second-order differential equations Nehari pointed out that following principle [6, Theorem 1.1] which we state here as a necessary and sufficient condition for disconjugancy of the differential system

$$(1.2) \quad y_1' = p(z)y_2, \quad y_2' = q(z)y_1,$$

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where $p(z)$ and $q(z)$ are regular functions in the domain D .

Let

$$(1.3) \quad f(z) = \frac{u_1(z)}{v_1(z)}, \quad g(z) = \frac{u_2(z)}{v_2(z)}$$

where $\underline{u} = (u_1, u_2)$ and $\underline{v} = (v_1, v_2)$ are linearly independent solutions of (1.2). The system (1.2) is disconjugate in D if and only if $f(z)$ and $g(z)$ are 'relatively schlicht' in D , i.e. if

$$(1.4) \quad f(z_1) \neq g(z_2)$$

for every choice of $z_1, z_2 \in D$.

If \underline{u} and \underline{v} are replaced by a different set of two linearly independent solutions of (1.2), then, according to (1.3), f and g are replaced by Tf and Tg , where T is given by

$$(1.5) \quad Tf = \frac{Af + B}{Cf + D}, \quad AD - BC \neq 0.$$

It is therefore necessary, that any relation between the coefficients $p(z)$ and $q(z)$ of (1.2) and the functions $f(z)$ and $g(z)$ will remain invariant under the mapping $f \rightarrow Tf$, $g \rightarrow Tg$. Two combinations of f and g with this invariance property are

$$(1.6) \quad \Phi[f, g] = \frac{f'g'}{(f-g)^2},$$

and

$$(1.7) \quad \Psi[f,g] = \frac{f''}{f'} - \frac{g''}{g'} - \frac{2(f' + g')}{f-g} .$$

The relations between the coefficients $p(z)$ and $q(z)$ of (1.2) and the functions $\Phi[f,g]$ and $\Psi[f,g]$ are given by

$$(1.8) \quad -p(z)q(z) = \Phi[f,g]$$

and

$$(1.9) \quad \frac{p'(z)}{p(z)} - \frac{q'(z)}{q(z)} = \Psi[f,g] .$$

Now, for functions $f(z)$ and $g(z)$ which are 'relatively schlicht' in $|z| < 1$ it is known [5, p.281, 6, Theorem 7.1] that

$$(1.10) \quad |\Phi[f,g]| = \frac{|f'(z)g'(z)|}{|f(z) - g(z)|^2} \leq \frac{1}{(1 - |z|^2)^2}, \quad |z| < 1 .$$

Utilizing this result one obtains the following necessary condition. If (1.3) is disconjugate in $|z| < 1$ then

$$(1.11) \quad |p(z)q(z)| \leq \frac{1}{(1 - |z|^2)^2}, \quad |z| < 1 .$$

Our principal aim in this paper is to generalize these results of Nehari to differential systems with $n \geq 3$. The ideas are also related to a recent paper by the author [2], where some function-theoretic aspects of disconjugacy of n -th order linear differential equations were considered.

2. Mappings onto domains with empty intersection.

Let $Y_k(z) = (Y_{1k}(z), Y_{2k}(z), \dots, Y_{nk}(z))$ $k = 1, 2, \dots, n$, be n linearly independent solutions of (1.1), then the matrix $Y(z) = [y_{ik}(z)]_1^n$ is a fundamental solution of the matrix differential equation

$$(2.1) \quad Y'(z) = P(z)Y(z)$$

corresponding to (1.1), i.e. the determinant $\det[y_{ik}(z)]_1^n \neq 0$ for all $z \in D$. Without loss of generality we may assume that $Y_{in}(z) \neq 0$ $i = 1, 2, \dots, n$, and define the functions

$$(2.2) \quad f_{ik}(z) = \frac{Y_{ik}(z)}{Y_{in}(z)}, \quad i, k = 1, 2, \dots, n$$

which are meromorphic in D . Furthermore

$$(2.3) \quad \det[y_{ik}(z)]_1^n = \prod_{i=1}^n Y_{in}(z) \det[f_{ik}(z)]_1^n.$$

Hence, $\det[f_{ik}(z)]_1^n \neq 0$ for all $z \in D$.

Let

$$H_i(z; a_1, \dots, a_{n-1}) = \sum_{k=1}^{n-1} a_k f_{ik}(z), \quad i = 1, 2, \dots, n$$

and denote by $D_i(a_1, \dots, a_{n-1})$ the image of D given by $H_i(z; a_1, \dots, a_{n-1})$. We state now:

Theorem 1.

(1.1) is disconjugate in D if and only if for every choice of complex constant a_1, \dots, a_{n-1} , such that $0 < \sum_{k=1}^{n-1} |a_k| < \infty$,

$$(2.5) \quad \bigcap_{i=1}^n D_i(a_1, \dots, a_{n-1}) = \emptyset$$

holds.

As pointed out by Schwarz [8, Theorem 3], disconjugancy of (1.1) in D is equivalent to the fact that for any fundamental solution $[y_{ik}(z)]_1^n$ of (2.1), we have $\det[y_{ik}(z_i)]_1^n \neq 0$ for every choice of n (not necessarily distinct) points $z_1, z_2, \dots, z_n \in D$. According to (2.3) it follows now that disconjugancy of (1.1) in D is equivalent to

$$\prod_{i=1}^n y_{in}(z_i) \det[f_{ik}(z_i)]_1^n \neq 0$$

for every choice of $z_1, \dots, z_n \in D$. Thus if $y_{in}(z) \neq 0$ ($i=1, 2, \dots, n$) for all $z \in D$, the functions $f_{ik}(z)$ defined in (2.2) are regular in D and Theorem 1 follows from [8, Theorem 3]. But if we do not assume that $y_{in}(z) \neq 0$ the result does not follow immediately, and it is exactly the zeros of $y_{in}(z)$ that cause the difficulty in the proof of Theorem 1. To handle this we shall require the following two lemmas.

Lemma 1.

Given a set of n points z_1, z_2, \dots, z_n of D there always exists a solution $y(z)$ of (1.1) such that $y_i(z_i) \neq 0$, $i = 1, 2, \dots, n$.

Proof.

By the existence theorem there exists a solution $\underline{u}(z)$ such that $u_1(z_1) = 1$. Suppose $u_2(z_2) = 0$, then by the same argument there exists a solution $\underline{v}(z)$ such that $v_2(z_2) = 1$. If $v_1(z_1) = 0$ then $\underline{y}(z) = \underline{u}(z) + t\underline{v}(z)$, $t \neq 0$, is a solution

of (1.1) which satisfies $y_1(z_1) \neq 0$, $y_2(z_2) \neq 0$. Assume now that $\underline{u}(z)$ and $\underline{v}(z)$ are solutions of (1.1) which satisfy $u_i(z_i) = \alpha_i \neq 0$ $i = 1, 2, \dots, j < n$, $u_{j+1}(z_{j+1}) = 0$, $v_1(z_1) = 0$, $v_i(z_i) = \beta_i \neq 0$ $i = 2, \dots, j+1$. If $t \neq -\alpha_i \beta_i^{-1}$, $i = 2, \dots, j+1$, then $\underline{y}(z) = \underline{u}(z) + t\underline{v}(z)$ will be a solution of (1.1) which satisfies $y_i(z_i) \neq 0$ $i = 1, 2, \dots, j+1$.

Lemma 2.

If (1.1) is not disconjugate in D , and if $y_{in}(z) \neq 0$ $i = 1, 2, \dots, n$, then there exists a non-trivial solution $\underline{y}^*(z)$ of (1.1), such that $y_i^*(z_i^*) = 0$ for $z_i^* \in D$, and $y_{in}(z_i^*) \neq 0$, $i = 1, 2, \dots, n$.

Proof.

Since (1.1) is not disconjugate in D , there exists a non-trivial solution $\underline{y}(z)$, such that $y_i(z_i) = 0$ for $z_i \in D$ $i = 1, 2, \dots, n$. If $y_{jn}(z_j) = 0$ for some $1 \leq j \leq n$, then apply a perturbation $\underline{y}_\epsilon(z) = \underline{y}(z) + \epsilon \underline{u}(z)$, where $\underline{u}(z)$ is a solution of (1.1) which satisfies $u_i(z_i) \neq 0$ $i = 1, 2, \dots, n$, and ϵ is a complex parameter. By making a proper choice of ϵ , say $\epsilon = \epsilon^*$, we obtain $\underline{y}^*(z) = \underline{y}_{\epsilon^*}(z)$, and $y_i^*(z_i^*) = 0$, where $z_i^* \in D$, $i = 1, 2, \dots, n$. Furthermore, ϵ^* is chosen in such a way to guarantee that $y_{in}(z_i^*) \neq 0$.

We are ready now to prove Theorem 1.

Proof of Theorem 1.

(i) Suppose $b \in \bigcap_{i=1}^n D_i(a_1, \dots, a_{n-1})$ for some choice of a_1, \dots, a_{n-1} , such that $0 < \sum_{k=1}^{n-1} |a_k| < \infty$, then there exist n points $z_1, z_2, \dots, z_n \in D$ such that

$$H_i(z_i; a_1, \dots, a_{n-1}) = \sum_{k=1}^{n-1} a_k f_{ik}(z_i) = b \quad i = 1, 2, \dots, n.$$

If $b = \infty$ then $y_{in}(z_i) = 0$ and (1.1) is not disconjugate.

If $b \neq \infty$ then

$$y_i(z_i) = \sum_{k=1}^{n-1} a_k y_{ik}(z_i) - b y_{in}(z_i) = 0.$$

Indeed, if $y_{in}(z_i) \neq 0$ then evidently $y_i(z_i) = 0$, and if $y_{in}(z_i) = 0$, then it follows from $b \neq \infty$ that $\sum_{k=1}^{n-1} a_k y_{ik}(z_i) = 0$ and we have again $y_i(z_i) = 0$. Hence, disconjugacy of (1.1) in D implies (2.5).

(ii) Assume (1.1) is not disconjugate in D , i.e. there exists a non-trivial solution $\tilde{y}^*(z) = \sum_{k=1}^n a_k y_k(z)$ of (1.1) such that $y_i^*(z_i^*) = 0$ for $z_i^* \in D$ $i = 1, 2, \dots, n$. By Lemma 2 we may assume that $y_{in}(z_i^*) \neq 0$. Hence

$$\frac{y_i^*(z_i^*)}{y_{in}(z_i^*)} = \sum_{k=1}^{n-1} a_k f_{ik}(z_i^*) + a_n = 0, \quad i = 1, \dots, n,$$

and $-a_n \in \bigcap_{i=1}^n D_i(a_1, \dots, a_{n-1})$. This completes the proof of Theorem 1.

3. Relations between the coefficients $p_{ik}(z)$ and the functions $f_{ik}(z)$.

Replacement of $y_k(z)$ ($k = 1, 2, \dots, n$) by another set of fundamental solutions $w_k(z)$ ($k = 1, 2, \dots, n$) results in a transformation

$$(3.1) \quad f_{ik}(z) \rightarrow F_{ik}(z) = \frac{w_{ik}(z)}{w_{in}(z)} = \frac{\sum_{j=1}^n \alpha_{jk} f_{ij}(z)}{\sum_{j=1}^n \alpha_{jn} f_{ij}(z)}, \quad i, k=1, 2, \dots, n, \quad \det[\alpha_{st}]_1^n \neq 0$$

applied to the matrix $[f_{ik}(z)]_1^n$. Hence, any relation between the entries of the matrices $[p_{ik}(z)]_1^n$ and $[f_{ik}(z)]_1^n$ must remain invariant under mappings of the type (3.1).

Without loss of generality we may assume that

$$(3.2) \quad p_{ii}(z) \equiv 0 \quad i = 1, 2, \dots, n,$$

since this can be achieved by means of a transformation [8, p.489]

$$(3.3) \quad u_i(z) = \tau_i(z) y_i(z), \quad \tau_i(z) = c_i \exp \int_{z_0}^z p_{ii}(\zeta) d\zeta, \quad i=1, 2, \dots, n,$$

which leaves $f_{ik}(z)$ unchanged. Assuming (3.2) it is still possible to apply (3.3) with $\tau_i(z) = c_i \neq 0$ where c_i are arbitrary constants. This results in

$$(3.4) \quad \underline{u}'(z) = R(z) \underline{u}(z), \quad R(z) = [r_{ik}(z)]_1^n$$

where

$$(3.5) \quad r_{ik}(z) = p_{ik}(z) \frac{c_k}{c_i} \quad i, k = 1, 2, \dots, n.$$

Therefore, the coefficients $p_{ik}(z)$ can be determined by the functions $f_{ik}(z)$ up to a relation of the type (3.5). It is easily verified by (3.5) that

$$(3.6) \quad \sigma_{ij}(z) = p_{ij}(z)p_{ji}(z), \quad i \neq j, \quad i, j, = 1, 2, \dots, n$$

and

$$(3.7) \quad \eta_{ij}(z) = \frac{p'_{ij}(z)}{p_{ij}(z)}, \quad i \neq j, \quad i, j = 1, 2, \dots, n$$

are independent of the constants c_i . Next we prove that $\sigma_{ij}(z)$ and $\eta_{ij}(z)$ can be expressed in terms of the functions $f_{ik}(z)$, and therefore remain invariant under the group of transformations of the type (3.1). According to (2.2) we have $y_{ik}(z) = f_{ik}(z)y_{in}(z)$. Differentiating and using (1.1) we obtain

$$(3.8) \quad \sum_{j=1}^n p_{ij} \frac{y_{jn}}{y_{in}} [f_{jk} - f_{ik}] = f'_{ik} \quad k = 1, 2, \dots, n-1.$$

Thus for every fixed $1 \leq i \leq n$ we have $(n-1)$ linear equations for the $(n-1)$ unknown $p_{ij} \frac{y_{jn}}{y_{in}}$ $j \neq i, j = 1, 2, \dots, n$. The $(n-1) \times (n-1)$ matrix $m_{jk}(i, z) = f_{jk}(z) - f_{ik}(z)$ $j = 1, 2, \dots, i-1, i+1, \dots, n, k = 1, 2, \dots, n-1$, satisfies $\det[m_{jk}(i, z)] = (-1)^{n+i} \det[f_{jk}(z)]_1^n \neq 0$ for all $z \in D$. Solving (3.8) we get

$$(3.9) \quad p_{ij} \frac{y_{jn}}{y_{in}} = \frac{\det[h_{sk}(i, j, z)]_1^n}{\det[f_{sk}(z)]_1^n} \quad i \neq j, \quad i, j = 1, 2, \dots, n$$

where

$$\left. \begin{aligned} h_{sk}(i, j, z) &= f_{sk}(z) & s \neq j, \\ h_{jk}(i, j, z) &= f'_{ik}(z) & j \neq i, \end{aligned} \right\} \begin{aligned} s, k &= 1, 2, \dots, n \\ i, j &= 1, 2, \dots, n. \end{aligned}$$

Setting now

$$(3.10) \quad B_{ii}(z) = 0, \quad B_{ij}(z) = \frac{\det[h_{sk}(i, j, z)]}{\det[f_{sk}(z)]}, \quad i \neq j, \quad i, j = 1, 2, \dots, n$$

it follows from (3.9) that

$$(3.11) \quad \begin{aligned} \sigma_{ij}(z) &= p_{ij}(z)p_{ji}(z) = B_{ij}(z)B_{ji}(z) \\ &= \frac{\det[h_{sk}(i,j,z)]\det[h_{sk}(j,i,z)]}{(\det[f_{sk}(z)])^2}, \quad i \neq j, \quad i, j=1, 2, \dots, n, \end{aligned}$$

and

$$(3.12) \quad \eta_{ij}(z) = \frac{p'_{ij}(z)}{p_{ij}(z)} = \frac{B'_{ij}(z)}{B_{ij}(z)} + \sum_{k=1}^n [B_{ik}(z) - B_{jk}(z)], \quad i \neq j, \quad i, j=1, \dots, n.$$

By Theorem 1, any condition for the functions $f_{ik}(z)$ $k = 1, 2, \dots, n$ to satisfy (2.5), which may be expressed in terms of $\sigma_{ij}(z)$ and $\eta_{ij}(z)$, is equivalent to conditions for disconjugacy of (1.1). For $n=2$, a known result in the theory of functions, namely inequality (1.10), was applied to yield the necessary condition for disconjugacy (1.11). Yet, for $n > 2$, we do not know of any necessary condition for the functions $f_{ik}(z)$ to satisfy (2.5). Conversely, in Section 7 a condition of this type will be deduced from necessary conditions for disconjugacy obtained in Theorem 5.

4. A family of 'relatively schlicht' functions.

Another way to generalize Nehari's principle [6, Theorem 1.1] is by generating a family of 'relatively schlicht' functions.

Let

$$(4.1) \quad g_j(z) = \frac{u_j(z)}{v_j(z)}, \quad g_k(z) = \frac{u_k(z)}{v_k(z)}, \quad j \neq k, \quad j, k = 1, 2, \dots, n$$

where $\underline{u} = (u_1, \dots, u_n)$ and $\underline{v} = (v_1, \dots, v_n)$ are linearly independent solutions of (1.1), which satisfy

$$(4.2) \quad u_i(z_i) = v_i(z_i) = 0, \quad i \neq j, k \quad i = 1, 2, \dots, n, \quad z_i \in D.$$

Denote by S_t the set of common zeros of $u_t(z)$ and $v_t(z)$ $t = 1, 2, \dots, n$. We assume that

$$(4.3) \quad S_t \subset D, \quad S_t \neq D \quad t = j, k.$$

In case $S_t = D$, $1 \leq t \leq n$, we do not define $g_t(z)$.

Evidently there always exists at least two linearly independent solutions of (1.1) which satisfy (4.2). (This is an immediate consequence of the existence of a fundamental set of n linearly independent solutions.) Moreover, if $z_i = a \in D$, $i \neq j, k$, $i = 1, 2, \dots, n$, then there exist exactly two linearly independent solutions such that $u_i(a) = v_i(a) = 0$, $i \neq j, k$ $i = 1, 2, \dots, n$. But in the general case, where some of the z_i may be distinct, it does not follow from the existence theorem that any three solutions of (1.1) which satisfy $y_i(z_i) = 0$ $i \neq j, k$ $i = 1, 2, \dots, n$, are linearly dependent. In Lemma 3, we discuss this situation.

Theorem 2.

Let $g_j(z)$ and $g_k(z)$ be defined by (4.1), where u and v are any two linearly independent solutions of (1.1) which satisfy (4.2) and (4.3). In order that the system (1.1) be disconjugate in D , it is necessary and sufficient that for every choice of n points (not necessarily distinct) z_1, z_2, \dots, z_n of D , and every pair of functions $g_j(z)$ and $g_k(z)$

$$(4.4) \quad g_j(z_j) \neq g_k(z_k), \quad j \neq k, \quad j, k = 1, 2, \dots, n$$

will hold i.e. disconjugancy of (1.1) is equivalent to the 'relatively schlichtness' of all pairs of functions $g_j(z)$ and $g_k(z)$, $j \neq k$.

For the proof of Theorem 2 we require some preliminary propositions which we state as a lemma.

Lemma 3.

Suppose there exist three linearly independent solutions $y(z)$, $v(z)$ and $w(z)$, which satisfy $y_i(z_i) = v_i(z_i) = w_i(z_i) = 0$ $i = 1, 2, \dots, n-2$, $z_i \in D$ then

(i) (1.1) is not disconjugate in D .

(ii) There exists a pair of functions $g_j(z)$ and $g_k(z)$ $j \neq k$ which are not 'relatively schlicht' in D . i.e. $g_j(\zeta_j) = g_k(\zeta_k)$ for some $\zeta_j, \zeta_k \in D$.

Proof.

(i) Let $z_{n-1}, z_n \in D$. There always exists a non-trivial solution $u(z) = \alpha_1 x(z) + \alpha_2 v(z) + \alpha_3 w(z)$ which satisfies $u_{n-1}(z_{n-1}) = u_n(z_n) = 0$. Hence (1.1) is not disconjugate in D , since $u_i(z_i) = 0$ $i = 1, 2, \dots, n$.

(ii) We first make the following remark. Since $\underline{y}(z)$ and $\underline{v}(z)$ are linearly independent solutions, then at least one component of each solution, say $y_s(z)$, and $v_m(z)$, $1 \leq s$, $m \leq n$, $s \neq m$ are not identically zero. Hence, we may assume that at least two components of $\underline{y}(z)$ are not identically zero. Suppose now that

$$(4.5) \quad v_{n-1}(z) \neq 0, \quad v_n(z) \neq 0, \quad z \in D$$

and let $z_{n-1}, z_n \in D$ be such that $v_{n-1}(z_{n-1}) \neq 0$ and $v_n(z_n) \neq 0$, then the functions $g_{n-1}(z)$ and $g_n(z)$, where $g_t(z) = \frac{u_t(z)}{v_t(z)}$ $t = n-1, n$ are not 'relatively schlicht' in D since $g_{n-1}(z_{n-1}) = g_n(z_n) = 0$.

In case (4.5) is false and $y_{n-1}(z) \equiv v_{n-1}(z) \equiv w_{n-1}(z) \equiv 0$ we assume that $v_1(z) \neq 0, v_n(z) \neq 0$. Let $\zeta_1, \zeta_n \in D$ be such that $v_1(\zeta_1) \neq 0, v_n(\zeta_n) \neq 0$. Proceeding as before there exists a non-trivial solution $\underline{u}(z) = \alpha_1 \underline{y}(z) + \alpha_2 \underline{v}(z) + \alpha_3 \underline{w}(z)$ such that $u_1(\zeta_1) = 0, u_i(z_i) = 0, i = 2, \dots, n-2, u_{n-1}(z) \equiv 0, u_n(\zeta_n) = 0$, and $g_1(\zeta_1) = g_n(\zeta_n) = 0$. If $y_t(z) \equiv v_t(z) \equiv w_t(z) \equiv 0$ for $t = n-1, n$ we may assume that $v_1(z) \neq 0, v_2(z) \neq 0$ and proceed as before.

Proof of Theorem 2.

(i) Necessary. Suppose $g_j(z_j) = g_k(z_k) = \beta \alpha^{-1}$, then $\underline{y}(z) = \alpha \underline{u}(z) - \beta \underline{v}(z)$ satisfies $y_i(z_i) = 0$ $i = 1, 2, \dots, n$.

(ii) Sufficient. Suppose there exists a solution $\underline{u}(z)$ such that $u_i(z_i) = 0$ $i = 1, 2, \dots, n, z_i \in D$. Let $\underline{v}(z)$ be a solution of (1.1), which is linearly independent on $\underline{u}(z)$ and

satisfies $v_i(z_i) = 0$ $i = 1, 2, \dots, n-2$. Now if

$$(4.6) \quad v_{n-1}(z_{n-1}) \neq 0, \quad v_n(z_n) \neq 0$$

then $g_{n-1}(z_{n-1}) = g_n(z_n) = 0$. So suppose (4.6) is false and $v_{n-1}(z_{n-1}) = 0$. Assume $S_n \neq D$, where S_n denotes the set of common zeros of $u_n(z)$ and $v_n(z)$ and let $\zeta_n \notin S_n$. There exists a non-trivial solution $\underline{y}(z) = \alpha_1 \underline{u}(z) + \alpha_2 \underline{v}(z)$ such that $y_n(\zeta_n) = 0$ and $y_i(z_i) = 0$ $i = 1, 2, \dots, n-1$. Moreover there exists another solution $\underline{w}(z)$, which is linearly independent of $\underline{y}(z)$ and satisfies $w_i(z_i) = 0$ $i=3, 4, \dots, n-1$, $w_n(\zeta_n) = 0$. Now $w_t(z_t) \neq 0$ $t = 1, 2$. Because, if $w_2(z_2) = 0$ then $u_i(z_i) = v_i(z_i) = w_i(z_i) = 0$ $i = 2, \dots, n-1$ and by Lemma 3, it follows from the 'relatively schlichtness' in D of every pair of functions $g_j(z)$ and $g_k(z)$ that $\underline{w}(z) = \beta_1 \underline{u}(z) + \beta_2 \underline{v}(z)$. But since $\underline{w}(z)$ and $\underline{y}(z)$ are linearly independent it follows now from $w_n(\zeta_n) = y_n(\zeta_n) = 0$ that $u_n(\zeta_n) = v_n(\zeta_n) = 0$, which contradicts our assumption that $\zeta_n \notin S_n$. So $w_2(z_2) \neq 0$ and similarly $w_1(z_1) \neq 0$. Considering now the functions $g_t(z) = \frac{y_t(z)}{w_t(z)}$ $t = 1, 2$, it follows that $g_1(z_1) = g_2(z_2) = 0$. If $S_n = D$, we may assume that $S_1 \neq D$ and proceed as before.

5. Quantities invariant under the mapping $f \rightarrow Tf, g \rightarrow Tg$.

Our next goal is to establish relations between the coefficients $p_{ik}(z)$ of the system (1.1) and the functions $g_j(z)$ and $g_k(z)$ defined by (4.1). As has become by now a standard procedure, we have to find out first what kind of transformations may be applied to g_j and g_k without affecting their relations with the coefficients p_{ik} . If $\underline{u}(z)$ and $\underline{v}(z)$ are replaced by the linearly independent solutions $A\underline{u}(z) + B\underline{v}(z)$ and $C\underline{u}(z) + D\underline{v}(z)$ respectively, then according to (4.1), g_j and g_k are replaced by Tg_j and Tg_k , where T is the linear transformation (1.5). Therefore any relation between the coefficients p_{ik} and the functions g_j and g_k should be expressed by quantities which remain invariant under the transformation $g_t \rightarrow Tg_t$ $t = j, k$.

This brings up the following question. Given two meromorphic functions, $f(z)$ and $g(z)$, in a domain D , what combinations of $f(z)$ and $g(z)$ and their derivatives remain invariant under the transformation $f \rightarrow Tf, g \rightarrow Tg$. Two combinations of this type were given by Nehari, namely $\Phi[f, g]$ and $\Psi[f, g]$ which are defined by (1.6) and (1.7). By differentiating $\Psi[f, g]$ and $\Phi[f, g]$ it is possible to derive more quantities with this invariance property. One combination of this type which will be of interest later is

$$(5.1) \quad \Theta[f, g] = \frac{f''}{f'} - \frac{2f'}{f-g} = \frac{1}{2} \frac{\Phi'[f, g]}{\Phi[f, g]} + \Psi[f, g] \quad .$$

In the following theorem we shall prove that with some restrictions on the functions $f(z)$ and $g(z)$, every combination

of $f(z)$ and $g(z)$ with the desired invariance property can be derived from $\Phi[f,g]$ and $\Theta[f,g]$.

Denote by $RC(D)$ the restricted class in D (see [7], p. 159), namely the class of functions $\{f(z)\}$ which are meromorphic in D with simple poles at most and which satisfy $f'(z) \neq 0$ for all $z \in D$. Note that if f belongs to $RC(D)$ so does Tf .

Theorem 3.

Let $f(z) \in RC(D)$, and let $g(z)$ be a meromorphic function in D such that

$$(5.2) \quad f(z) \neq g(z), \quad z \in D.$$

Let $E[f(z),g(z)] = E(f(z), \dots, f^{(n)}(z), g(z), \dots, g^{(n)}(z))$ be a combination of $f(z)$ and $g(z)$ and their derivatives up to order n . If $E[f(z),g(z)]$ remains invariant under the trans- formaton $f \rightarrow Tf, g \rightarrow Tg$, i.e.,

$$(5.3) \quad E[Tf(z), Tg(z)] = E[f(z), g(z)] = I(z)$$

where T is defined by (1.5), then $E[f(z),g(z)]$ may be derived from $\Phi[f(z),g(z)] = \varphi(z)$ and $\Theta[f(z),g(z)] = \theta(z)$, and

$$(5.4) \quad I(z) = E[f(z), g(z)] = E^*[\varphi(z), \theta(z)]$$

where E^* is a combination of $\varphi(z)$ and $\theta(z)$ and their derivatives up to order $n-1$.

Proof.

Let $z_0 \in D$. Without loss of generality we may assume that

$f(z_0) = 0$, $f'(z_0) = 1$, $f''(z_0) = 0$, since this situation may be achieved by means of a transformation $f \rightarrow Tf$, $g \rightarrow Tg$, [2, Th. 2] which, according to (5.3), leaves $I(z)$ unchanged. It follows now from (5.2) that $g(z_0) = \gamma \neq 0$. If $\gamma \neq \infty$, then by applying the transformation $f \rightarrow [1-\gamma^{-1}f]$, $g \rightarrow [1-\gamma^{-1}g]$, we obtain

$$(5.5) \quad f(z_0) = 1, \quad g(z_0) = 0, \quad f'(z_0) \neq 0, \quad f''(z_0) = 0.$$

Setting now $z = z_0$ in (5.1) and (1.6), it follows from (5.5) that

$$(5.6) \quad f'(z_0) = -\frac{\theta(z_0)}{2} \neq 0, \quad g'(z_0) = -\frac{2\varphi(z_0)}{\theta(z_0)}.$$

Differentiation of (1.6) and (5.1) gives us

$$(5.7) \quad \varphi^{(m)}(z) = \frac{g^{(m+1)}(z)f'(z)}{[f(z) - g(z)]^2} + \frac{M_m[f(z), g(z)]}{[f(z) - g(z)]^{m+2}}, \quad m=0,1,2,\dots,$$

and

$$(5.8) \quad \theta^{(m)}(z) = \frac{f^{(m+2)}(z)}{f'(z)} + \frac{N_m[f(z), g(z)]}{[f(z) - g(z)]^{m+1} [f'(z)]^{m+1}}, \quad m=1,2,\dots,$$

where M_m and N_m are polynomials of $f(z)$, $f'(z_0), \dots, f^{(m+1)}(z)$, and $g(z), g'(z), \dots, g^{(m)}(z)$. By elimination and induction it follows now from (5.5), (5.6), (5.7) and (5.8) that

$$(5.9) \quad g^{(m+1)}(z_0) = -\frac{2\varphi^{(m)}(z_0)}{\theta(z_0)} + R_m[\theta(z_0), \dots, \theta^{(m)}(z_0), \varphi(z_0), \dots, \varphi^{(m-1)}(z_0)]$$

$m=0,1,2,\dots,$

and

$$(5.10) \quad f^{(m+2)}(z_0) = -\frac{2\theta^{(m)}(z_0)}{\theta(z_0)} + \tilde{R}_m[\theta(z_0), \dots, \theta^{(m-1)}(z_0), \varphi(z_0), \dots, \varphi^{(m-1)}(z_0)]$$

$m=1,2,\dots,$

where R_m and \tilde{R}_m are rational functions whose denominators are powers of $\theta(z_0)$. Insertion of (5.6), (5.9) and (5.10) in $E[f(z), g(z)]$ yields

$$(5.11) \quad I(z_0) = E[f(z_0), g(z_0)] = E^*[\theta(z_0), \dots, \theta^{(n-1)}(z_0), \varphi(z_0), \dots, \varphi^{(n-1)}(z_0)].$$

In case we have $f(z_0) = 0$, $f'(z_0) = 1$, $f''(z_0) = 0$, $g(z_0) = \infty$ for $z_0 \in D$, then by applying the transformation $f(z) \rightarrow [1-f(z)]^{-1}$ $g(z) \rightarrow [1-g(z)]^{-1}$ we obtain

$$(5.12) \quad f(z_0) = 1, \quad f'(z_0) = 1, \quad f''(z_0) = 2, \quad g(z_0) = 0.$$

Setting now $z = z_0$ in (5.1) and (1.6) we obtain according to

$$(5.12)$$

$$(5.6') \quad \theta(z_0) = 0, \quad \varphi(z_0) = g'(z_0).$$

The derivatives of $f(z)$ and $g(z)$ at the point $z = z_0$, may be eliminated successively from (5.7) and (5.8) as before.

This leads us now to

$$(5.9') \quad g^{(m+1)}(z_0) = \varphi^{(m)}(z_0) + \tilde{M}_m[\theta(z_0), \varphi(z_0)], \quad m=1, 2, \dots,$$

and

$$(5.10') \quad f^{(m+2)}(z_0) = \theta^{(m)}(z_0) + \tilde{N}_m[\theta(z_0), \varphi(z_0)], \quad m=1, 2, \dots,$$

where \tilde{M}_m and \tilde{N}_m are polynomials of the arguments $\theta^{(s)}(z_0)$ and $\varphi^{(s)}(z_0)$ $s = 0, 1, \dots, n-1$. Insertion of (5.12), (5.6'), (5.9') and (5.10') in $E[f(z), g(z)]$ yields a relation of the type (5.11).

Remark.

It is easily confirmed that for $f(z)$ and $g(z)$ satisfying the assumptions of Theorem 3, $\varphi(z) = \Phi[f(z), g(z)]$ and $\theta(z) = [f(z), g(z)]$ are regular functions in D . Moreover, $\varphi(z) \neq 0$ for $z \in D$, if and only if in addition to the assumptions of the theorem we have $g(z) \in RC(D)$. For $f(z), g(z) \in RC(D)$ satisfying (5.2), the function $\psi(z) = \Psi[f(z), g(z)]$ is also regular in D and a theorem similar to Theorem 3 may be established with $\theta[f, g]$ replaced by $\Psi[f, g]$.

6. A subfamily of 'relatively schlicht' functions.

For the applications it is useful to consider only a subfamily of functions of the type (4.1); namely:

$$(6.1) \quad g_j(z, a) = \frac{u_j(z)}{v_j(z)}, \quad g_k(z, a) = \frac{u_k(z)}{v_k(z)}, \quad j \neq k,$$

where u and v are linearly independent solutions of (1.1), satisfying

$$(6.2) \quad u_i(a) = v_i(a) = 0, \quad i \neq j, k \quad i = 1, 2, \dots, n, \quad a \in D.$$

Before taking the problem of establishing relations between the functions (6.1) and the coefficients $p_{ik}(z)$ of (1.1), we first make the following remarks.

(i) As already discussed in Section 4, there exists exactly two linearly independent solutions satisfying (6.2). Therefore any other solution of (1.1) which satisfy $y_i(a) = 0$ $i \neq j, k$, $i = 1, \dots, n-2$ is a linear combination of u and v . Hence, replacement of u and v by another set of two linearly independent solutions y, w satisfying $y_i(a) = w_i(a) = 0$ $i \neq j, k$ $i = 1, 2, \dots, n$, results in a transformation $g_t(z, a) \rightarrow Tg_t(z, a)$ $t = j, k$, where T is defined by (1.5). It follows that the relations between the functions (6.1) and the coefficients $p_{ik}(z)$ must stay invariant under the transformation $g_t \rightarrow Tg_t$ $t = j, k$.

(ii) Since the transformation (3.3) leaves the functions (6.1) unchanged we may assume that $p_{ii}(z) \equiv 0$ $i = 1, 2, \dots, n$. In this case the coefficients $p_{ik}(z)$ can be determined by the functions (6.1) only up to a relation of the type (3.5).

Theorem 4.

Let $p_{ik}(z)$ $i, k = 1, 2, \dots, n$ be regular functions in D and assume

$$(3.3) \quad p_{ii}(z) \equiv 0 \quad i = 1, 2, \dots, n.$$

Let the functions $g_j(z, a)$ and $g_k(z, a)$ be defined by (6.1) where u and v are linearly independent solutions of (1.1) satisfying (6.2). If

$$(6.3) \quad \varphi_{jk}(z, a) = \Phi[g_j(z, a), g_k(z, a)] = \frac{g'_j g'_k}{(g'_j - g'_k)^2}$$

and

$$(6.4) \quad \theta_{jk}(z, a) = \Theta[g_j(z, a), g_k(z, a)] = \frac{g'_j}{g'_j} - \frac{2g'_j}{g'_j - g'_k}$$

where $g'_t = \frac{d}{dz} [g_t(z, a)]$, $t = j, k$ then

$$(6.5) \quad \varphi_{jk}(a, a) = -p_{jk}(a)p_{kj}(a), \quad j \neq k, \quad j, k = 1, 2, \dots, n, \quad a \in D$$

and if $p_{jk}(a) \neq 0$, then

$$(6.6) \quad \theta_{jk}(a, a) = \frac{p'_{jk}(a)}{p_{jk}(a)} + \frac{\sum_{i=1}^n p_{ji}(a)p_{ik}(a)}{p_{jk}(a)}, \quad j \neq k, \quad j, k = 1, 2, \dots, n, \quad a \in D.$$

Proof.

Let $u(z)$ and $v(z)$ satisfy

$$(6.7) \quad u_i(a) = \delta_{ik}, \quad v_i(a) = \delta_{ij}, \quad j \neq k, \quad i = 1, 2, \dots, n, \quad 1 \leq j, k \leq n.$$

According to (1.1) and (6.1) we have

$$(6.8) \quad g'_t(z, a) = \frac{\sum_{i=1}^n p_{ti}(z) [u_i(z)v_t(z) - u_t(z)v_i(z)]}{v_t^2(z)}.$$

Therefore,

$$(6.9) \quad \varphi_{jk}(z, a) = \frac{\sum_{i=1}^n p_{ji} [u_i v_j - u_j v_i] \sum_{s=1}^n p_{ks} [u_s v_k - u_k v_s]}{[u_j v_k - u_k v_j]^2},$$

and (6.5) follows now from (6.9) and (6.7). By setting $t=j$ and $z=a$ in (6.8) we obtain $g_j^j(a, a) = p_{jk}(a)$. Hence if $p_{jk}(a) \neq 0$ for $a \in D$, $g_j(z, a)$ belongs to the restricted class of functions in some neighborhood $N(a) \subset D$ of the point a . Obviously both $g_j(z, a)$ and $g_k(z, a)$ are meromorphic functions in D . So, we conclude now that $\theta_{jk}(z, a)$ is regular in $N(a)$. By differentiating (6.8) and using (6.7) we obtain (6.6).

Since any solution of (1.1) which satisfies $y_i(a) = 0$ $i \neq j, k$ $i=1, 2, \dots, n$, is a linear combination of the normalized solutions $\underline{u}(z)$ and $\underline{v}(z)$ which satisfy (6.7), a different choice of the two solutions would replace g_t by Tg_t , ($t=j, k$) where T is of the form (1.5). But $\varphi(z, a)$ and $\theta(z, a)$ are not affected by this transformation, hence (6.5) and (6.6) hold for any choice of the solutions $\underline{u}(z)$ and $\underline{v}(z)$ regardless of the normalization (6.7).

Remarks.

1. Note that (6.5) holds even without the assumption (3.3), but in this case $p_{ii}(z)$ are not determined by the functions (6.1).

2. If $p_{jk}(z) \neq 0$ for all $z \in D$, $j \neq k$, $j, k=1, 2, \dots, n$, then (6.5) and (6.6) are the 'fundamental relations' between the functions $g_j(z, a)$ and $g_k(z, a)$ and the coefficients $p_{jk}(z)$ of (1.1).

7. Necessary conditions for disconjugacy in the unit disk.

Theorem 5.

Let $p_{jk}(z)$ $j,k=1,2,\dots,n$ be regular for $|z| < 1$. If
the system (1.1) is disconjugate in $|z| < 1$, then

$$(7.1) \quad |p_{jk}(z)p_{kj}(z)| \leq \frac{1}{(1-|z|^2)^2}, \quad |z| < 1.$$

Proof.

By Theorem 2 disconjugacy of (1.1) in $|z| < 1$ implies the 'relatively schlichtness' in $|z| < 1$ of every pair of functions $g_j(z)$ and $g_k(z)$ defined by (4.1). In particular $g_j(z,a)$ and $g_k(z,a)$ defined by (6.1) are 'relatively schlicht'. Applying (1.10), it follows that

$$(7.2) \quad |\varphi_{jk}(z,a)| = |\Phi[g_j(z,a), g_k(z,a)]| \leq \frac{1}{(1-|z|^2)^2}, \quad |z| < 1$$

holds for every $j,k=1,2,\dots,n$ $j \neq k$, and any $|a| < 1$. Setting $z=a$ in (7.2) we obtain by (6.5)

$$|p_{jk}(a)p_{kj}(a)| = |\varphi_{jk}(a,a)| \leq \frac{1}{(1-|a|^2)^2}, \quad |a| < 1.$$

We add the following remarks.

(i) Since $\Theta[g_j(z,a), g_k(z,a)]$ cannot be bounded without the further assumption that $g_j(z,a)$ is univalent in z for $|z| < 1$, (6.6) does not yield a necessary condition for disconjugacy. Moreover, in order to obtain a bound for $\Psi[g_j(z,a), g_k(z,a)]$, one has to assume that both $g_j(z,a)$ and $g_k(z,a)$ are univalent in $|z| < 1$, besides being 'relatively schlicht' there [6, Th. 7.2].

(ii) Let $\pi_{ik}(\zeta)$ $i,k=1,2,\dots,n$ be regular in the domain Δ ,

and consider the differential system

$$(7.3) \quad \omega'(\zeta) = \prod(\zeta) \omega(\zeta)$$

where $\omega(\zeta) = [\omega_1(\zeta), \omega_2(\zeta), \dots, \omega_n(\zeta)]$ and $\prod(\zeta) = [\pi_{ik}(\zeta)]_1^n$.

If Δ is conformally equivalent to D , i.e., if there exists an one-to-one regular function $\zeta(z)$ which maps D onto Δ , then (7.3) may be transformed by $y_j(z) = \omega_j[\zeta(z)]$ $j=1, \dots, n$ into the system (1.1) and

$$(7.4) \quad p_{jk}(z)p_{kj}(z) = \pi_{jk}[\zeta(z)]\pi_{kj}[\zeta(z)] \left(\frac{d\zeta}{dz}\right)^2$$

holds. Furthermore, (7.3) is disconjugate in Δ if and only if the transformed system (1.1) is disconjugate in D . Thus, in view of (7.4), Theorem 5 yields a necessary condition for disconjugacy in any domain Δ which is conformally equivalent to the unit disk.

We conclude this section with the following corollary.

Let $f_{ik}(z)$ $i, k=1, 2, \dots, n$ be regular functions in the unit disk D , such that $f_{in}(z) \equiv 1$ $i=1, \dots, n$, and $\det[f_{ik}(z)]_1^n \neq 0$ for $z \in D$. Let $H_i(z; a_1, \dots, a_{n-1})$ be defined as in (2.4), and denote by $D_i(a_1, \dots, a_{n-1})$ the image of D given by $H_i(z; a_1, \dots, a_{n-1})$. If

$$(2.5) \quad \bigcap_{i=1}^n D_i(a_1, \dots, a_{n-1}) = \emptyset$$

for every choice of the constants a_1, \dots, a_{n-1} , such that

$$0 < \sum_{k=1}^{n-1} |a_k| < \infty, \text{ then}$$

$$(7.5) \quad |B_{ij}(z)B_{ji}(z)| \leq \frac{1}{(1-|z|^2)^2}, \quad i \neq j, \quad i, j=1, \dots, n, \quad |z| < 1,$$

where $B_{ij}(z)$ are defined by (3.10).

Proof.

By Theorem 1, (2.5) implies the disconjugacy of the corresponding system (1.1). According to (3.11) and (6.5) the result follows.

Remarks. (i) (7.5) is a generalization of (1.10) for the case $n > 2$. (ii) Since $B_{ij}(z)B_{ji}(z)$ remains invariant when $f_{ik}(z)$ is subject to a transformation of the type (3.1), our result may be generalized to meromorphic functions $F_{ik}(z)$, $i, k=1, \dots, n$, which are obtained from $f_{ik}(z)$ by means of (3.1).

8. Disfocality of n-th order differential equations.

In the special case where

$$(8.1) \quad P(z) = \begin{bmatrix} 0 & 1 & 0 & \cdot & \cdot & \cdot & \cdot & 0 & 0 \\ 0 & 0 & 1 & 0 & \cdot & \cdot & \cdot & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot & \cdot & \cdot & \cdot & 0 & 1 \\ -q_n & -q_{n-1} & \cdot & \cdot & \cdot & \cdot & \cdot & -q_2 & -q_1 \end{bmatrix}$$

the column vector $\underline{y}(z) = [y_1(z), \dots, y_n(z)]$ of (1.1) becomes $[w(z), w'(z), \dots, w^{(n-1)}(z)]$ and (1.1) is equivalent to the differential equation

$$(8.2) \quad w^{(n)}(z) + q_1(z)w^{(n-1)}(z) + \dots + q_n(z)w(z) = 0.$$

In this case disconjugacy of (1.1) in D is equivalent to disfocality of (8.2) in the same domain D . (8.2) is called disfocal in D if for every choice of n (not necessarily distinct) points z_1, \dots, z_n of D , the only solution of (8.2) satisfying $w(z_1) = w'(z_2) = \dots = w^{(n-1)}(z_n) = 0$, is the trivial one $w(z) \equiv 0$. (See [6]).

Let $q_k(z)$ $k=1, 2, \dots, n$ be regular functions in $|z| < 1$. If (8.2) is disfocal in $|z| < 1$, it follows from (6.5) and (8.1) that

$$(8.3) \quad |q_2(z)| \leq \frac{1}{(1-|z|^2)^2}, \quad |z| < 1.$$

But (6.5) does not yield bounds for the other coefficients of (8.2), since by (8.1) $p_{in}(z) \equiv 0$ for $i=1, 2, \dots, n-2$. Yet such bounds may be obtained by slight modifications of Theorem 4 and 5.

Theorem 6.

Let $q_k(z)$ $k=1,2,\dots,n$ be regular in the domain D , and let $u(z)$ and $v(z)$ be linearly independent solutions of (8.2) which satisfy

$$(8.4) \quad u^{(s)}(a) = v^{(s)}(a) = 0, \quad s=0,1,\dots,n-1, \quad s \neq j-1, j \quad 1 \leq j \leq n-1, \quad a \in D.$$

Let

$$(8.5) \quad g_j(z, a) = \frac{u^{(j-1)}(z)}{v^{(j-1)}(z)}, \quad g_{j+1}(z, a) = \frac{u^{(j)}(z)}{v^{(j)}(z)}, \quad j=1,2,\dots,n-1.$$

If

$$(8.6) \quad \varphi_{j,j+1}(z, a) = \Phi[g_j(z, a), g_{j+1}(z, a)] = \frac{g_j' g_{j+1}'}{(g_j - g_{j+1})^2} \quad j=1,2,\dots,n-1$$

and

$$(8.7) \quad \theta_{n-1,n}(z, a) = \Theta[g_{n-1}(z, a), g_n(z, a)] = \frac{g_{n-1}'}{g_{n-1}} - \frac{2g_{n-1}'}{g_{n-1} - g_n}$$

then

$$(8.8) \quad \varphi_{j,j+1}(a, a) = \varphi_{j,j+1}'(a, a) = \dots = \varphi_{j,j+1}^{(n-j-2)}(a, a) = 0, \quad \left. \vphantom{\varphi_{j,j+1}} \right\} \quad j=1,2,\dots,n-1$$

$$(8.9) \quad \varphi_{j,j+1}^{(n-j-1)}(a, a) = q_{n-j+1}(a)$$

and

$$(8.10) \quad \theta_{n-1,n}(a, a) = -q_1(a).$$

All derivatives are with respect to z .

Proof.

Since (8.6) and (8.7) remain invariant under the transformation $g_t \rightarrow Tg_t$ $t=j,j+1$, where T is given by (1.5), we may assume that

$$(8.11) \quad u(z) = w_j(z), \quad v(z) = w_{j+1}(z), \quad 1 \leq j \leq n-1$$

where $w_t(z)$ $t=1,2,\dots,n$ is a fundamental set of solutions of (8.2) which satisfy

$$(8.12) \quad w_t^{(s-1)}(a) = \delta_{st}, \quad s,t=1,2,\dots,n.$$

This assumption results in simplification of the calculations.

According to (8.5) and (8.11) we obtain now

$$g_j'(z,a) = \frac{w_j^{(j)}(z)w_{j+1}^{(j-1)}(z) - w_j^{(j-1)}(z)w_{j+1}^{(j)}(z)}{[w_{j+1}^{(j-1)}(z)]^2} = \frac{L_j(z)}{[w_{j+1}^{(j-1)}(z)]^2}$$

$$g_{j+1}'(z,a) = \frac{w_j^{(j+1)}(z)w_{j+1}^{(j)}(z) - w_j^{(j)}(z)w_{j+1}^{(j+1)}(z)}{[w_{j+1}^{(j)}(z)]^2} = \frac{K_j(z)}{[w_{j+1}^{(j)}(z)]^2}.$$

Hence

$$(8.13) \quad \varphi_{j,j+1}(z,a) = \frac{K_j(z)}{L_j(z)}.$$

By (8.12) we obtain for $z=a$

$$(8.14) \quad L_j(a) = -1, \quad K_j(a) = K_j'(a) = \dots = K_j^{(n-j-2)}(a) = 0, \quad j=1,2,\dots,n-1$$

and

$$(8.15) \quad K_j^{(n-j-1)}(a) = w_j^{(n)}(a) = -q_{n-j+1}(a), \quad j=1,2,\dots,n-1.$$

(8.8) and (8.9) follow now from (8.13), (8.14) and (8.15).

In a similar way, it is easily verified that

$$\theta_{n-1,n}(z,a) = \frac{L_{n-1}'(z)}{L_{n-1}(z)}.$$

Setting $z=a$, (8.10) follows.

We apply now Theorem 6 in order to obtain necessary conditions for disfocality of (8.2) in the unit disk.

Theorem 7.

Let $q_k(z)$ $k=1,2,\dots,n$ be regular in the unit disk. If
equation (8.2) is disfocal in $|z| < 1$, then

$$(8.16) \quad |q_k(z)| \leq \frac{A_k}{(1-|z|^2)^k} \quad k=2,3,\dots,n, \quad |z| < 1$$

where

$$(8.17) \quad A_2 = 1, \quad A_k = (k-2)! \left(\frac{k+2}{4}\right)^2 \left(\frac{k+2}{k-2}\right)^{\frac{k-2}{2}}, \quad k=3,4,\dots,n.$$

We require the following elementary result for the proof of Theorem 7.

Lemma 4.

Let $h_k(z)$, $k=1,2,\dots$, be a regular function in $|z| < 1$.

If

$$(8.18) \quad |h_k(z)| \leq \frac{1}{(1-|z|^2)^k}, \quad |z| < 1,$$

then

$$(8.19) \quad |h_k^{(s)}(z)| \leq \frac{C(s,k)}{(1-|z|^2)^{s+k}}, \quad |z| < 1, \quad s=1,2,\dots,$$

where $C(s,k)$ are constants depending only on s and k .

Proof.

Let $h_k(z) = \sum_{j=0}^{\infty} b_j z^j$, then by Cauchy inequality

$$|b_j| \leq r^{-j} M(r), \quad M(r) = \max_{|z|=r < 1} |h_k(z)|.$$

By (8.18) $M(r) \leq (1-r^2)^{-k}$, therefore

$$(8.20) \quad |b_j| \leq \min_{0 < r < 1} r^{-j} (1-r^2)^{-k} = m(j,k) = \left(\frac{2k+j}{2k}\right)^k \left(\frac{2k+j}{j}\right)^{j/2}, \quad j=1,2,\dots$$

Set

$$(8.21) \quad \eta_k(\zeta) = h_k[z(\zeta)] \left(\frac{dz}{d\zeta}\right)^k, \quad z(\zeta) = \frac{\zeta+a}{1+\bar{a}\zeta}, \quad |a| < 1.$$

$z(\zeta)$ is a mapping of $|\zeta| < 1$ onto $|z| < 1$, and therefore $\eta_k(\zeta) = \sum_{j=0}^{\infty} \beta_j \zeta^j$ is regular in $|\zeta| < 1$. Moreover, since

$$\left|\frac{dz}{d\zeta}\right| = \frac{1-|z|^2}{1-|\zeta|^2}$$

it follows from (8.18) that

$$(8.22) \quad |\eta_k(\zeta)| \leq \frac{1}{(1-|\zeta|^2)^k}, \quad |\zeta| < 1.$$

Consequently

$$(8.23) \quad |\beta_j| \leq m(j,k), \quad j=1,2,\dots$$

Differentiation of (8.21) leads us to

$$(8.24) \quad h'_k(z) = \eta'_k(\zeta) \left(\frac{d\zeta}{dz}\right)^{k+1} + k\eta_k(\zeta) \left(\frac{d\zeta}{dz}\right)^{k-1} \frac{d^2\zeta}{dz^2}.$$

It is easily confirmed that

$$|\zeta''(z)| \leq \frac{2|z|}{(1-|z|^2)^2}, \quad |z| < 1,$$

and by setting now $\zeta=0$ in (8.24) we obtain

$$(8.25) \quad |h'_k(a)| \leq \frac{|\eta'_k(0)| + 2k|a||\eta_k(0)|}{(1-|a|^2)^{k+1}} \leq \frac{m(1,k) + 2k}{(1-|a|^2)^{k+1}} = \frac{C(1,k)}{(1-|a|^2)^{k+1}}.$$

To obtain a bound for $|h''_k(z)|$, one can either apply (8.19) to $h'_k(z)$ or differentiate (8.21) twice. Higher derivatives may be obtained in a similar way.

Remark.

If

$$(8.26) \quad h_k(a) = h'_k(a) = \dots = h_k^{(s-1)}(a) = 0, \quad s=1,2,\dots,$$

then for $z=a$ we have

$$(8.27) \quad |h_k^{(s)}(a)| \leq \frac{|\eta_k^{(s)}(0)|}{(1-|a|^2)^{s+k}} \leq \frac{s!m(s,k)}{(1-|a|^2)^{s+k}}.$$

Proof of Theorem 7.

Since (8.2) is disfocal in $|z| < 1$, it follows from Theorem 2 (and may easily be verified directly) that for every $1 \leq j \leq n-1$ and any $|a| < 1$, the functions $g_j(z,a)$ and $g_{j+1}(z,a)$, defined by (8.5), are 'relatively schlicht' in $|z| < 1$. Consequently,

$$(8.28) \quad |\varphi_{j,j+1}(z,a)| = |\Phi[g_j(z,a), g_{j+1}(z,a)]| \leq \frac{1}{(1-|z|^2)^2}, \quad |z| < 1.$$

We utilize now the relations between the functions $\varphi_{j,j+1}$ and the coefficients q_{n-j+1} , established in Theorem 6. For $j=n-1$, it follows immediately from (8.9) and (8.28) that

$$|q_2(a)| = |\varphi_{n-1,n}(a,a)| \leq \frac{1}{(1-|a|^2)^2}, \quad |a| < 1.$$

For $1 \leq j \leq n-2$ we apply Lemma 4 to $\varphi_{j,j+1}(z,a)$ with $k=2$ and $s=n-j-1$. By (8.9) and (8.19) we conclude that

$$|q_{n-j+1}(a)| = |\varphi_{j,j+1}^{(n-j-1)}(a,a)| \leq \frac{A_{n-j+1}}{(1-|z|^2)^{n-j+1}}, \quad j=1,2,\dots,n-2.$$

Moreover, according to (8.8) and to the remark following Lemma 4,

$$A_{n-j+1} \leq (n-j-1)!m(n-j-1,2) = (n-j-1)! \left(\frac{n-j+3}{4}\right)^2 \left(\frac{n-j+3}{n-j-1}\right)^{\frac{n-j-1}{2}},$$

which completes the proof of the theorem.

We add the following remarks:

(i) (8.10) cannot be utilized to yield a bound for $|q_1(z)|$, since a bound for $\theta_{n-1,n}(z,a)$ may be obtained only if

$g_{n-1}(z,a)$ is univalent in $|z| < 1$, which is more than we can conclude from our assumptions.

(ii) The technique of differentiating the functions ϕ , may also be applied in the general case when the matrix $P(z)$ does not take the special form (8.1). Assume now that (1.1) is conjugate in $|z| < 1$ and that (3.3) holds. By differentiating (6.9) once and setting $z=a$, we obtain

$$(8.29) \quad \phi'_{jk}(a,a) = -p'_{jk}(a)p_{kj}(a) - p_{jk}(a)p'_{kj}(a) \\ - \sum_{i=1}^n [p_{ji}(a)p_{ik}(a)p_{kj}(a) + p_{ki}(a)p_{ij}(a)p_{jk}(a)].$$

According to (7.1) and (7.2) we may apply Lemma 4 to $p_{jk}(z)p_{kj}(z)$ as well as to $\phi_{jk}(z,a)$. It follows now from (8.19) that

$$|\phi'_{jk}(a,a)| \leq \frac{C(1,2)}{(1-|a|^2)^3}, \quad |a| < 1$$

$$|p'_{jk}(a)p_{kj}(a) + p_{jk}(a)p'_{kj}(a)| \leq \frac{C(1,2)}{(1-|a|^2)^3}, \quad |a| < 1$$

which by (8.29) yields

$$(8.30) \quad \left| \sum_{i=1}^n [p_{jk}(a)p_{ik}(a)p_{ki}(a) + p_{ki}(a)p_{ij}(a)p_{jk}(a)] \right| \leq \frac{2C(1,2)}{(1-|a|^2)^3}, \\ |a| < 1.$$

For $n=3, j=1, k=2$ (8.30) reduces to

$$|\det[P(a)]| \leq \frac{2C(1,2)}{(1-|a|^2)^3}, \quad |a| < 1.$$

By taking the second derivative of (6.9) at the point $z=a$, it is possible to obtain sums of products of 4 coefficients of the matrix $P(z)$ ($n \geq 4$), and similar results for higher derivatives. The actual calculation is somewhat cumbersome.

We end with the following corollary for second order equations.

If $q_2(z)$ is regular in $|z| < 1$ and if the differential equation

$$(8.31) \quad w''(z) + q_2(z)w(z) = 0$$

is disfocal in $|z| < 1$, then it is also disconjugate in $|z| < 1$.

We recall that a second-order differential equation is called disconjugate in a domain D , if the only solution that vanishes twice in D is the trivial one. As for the proof of the corollary, since (8.31) is disfocal in $|z| < 1$, it follows from (8.16) that

$$|q_2(z)| \leq \frac{1}{(1-|z|^2)^2}, \quad |z| < 1$$

which is sufficient to guarantee the disconjugacy of (8.31) in $|z| < 1$. (See [4]).

We note that this result holds only if $q_1(z) \equiv 0$ and is not true in the general case of second order differential equations of the type (8.2). Considering the differential equation

$$y''(z) - (m+1)y'(z) + my(z) = 0, \quad m > 1$$

London and Schwarz [3] showed that, in general, disfocality neither implies disconjugacy nor is implied by it.

In view of the fact that disconjugacy of (8.31) is equivalent to univalence of $f(z) = \frac{w_1(z)}{w_2(z)}$, where $w_1(z)$ and $w_2(z)$ are linearly independent solutions of (8.31), our last corollary may be stated as a univalence criterion.

Theorem 8.

Denote by D the disk $|z-b| < R$, $0 < R < \infty$, and let $f(z)$

be a meromorphic function in D. If

$$(8.32) \quad f(z_1) - \frac{2[f'(z_1)]^2}{f''(z_1)} \neq f(z_2)$$

for every pair of points (not necessarily distinct) $z_1, z_2 \in D$, then $f(z)$ is univalent in D and

$$|\{f(z), z\}| \leq \frac{2}{(R^2 - |z-b|^2)^2}, \quad z \in D$$

where

$$\{f(z), z\} = \frac{f'''(z)}{f'(z)} - \frac{3}{2} \left[\frac{f''(z)}{f'(z)} \right]^2$$

is the Schwarzian derivative.

Proof.

Without loss of generality we may assume that D is the unit disk, since this situation may be achieved by means of a transformation $\zeta(z) = \frac{z-b}{R}$, which does not violate (8.32).

Consider now the second order differential equation

$$(8.33) \quad w''(z) + q_1(z)w'(z) + q_2(z)w(z) = 0.$$

According to (8.9) and (8.10) we have

$$-q_1(z) = \Theta[f(z), g(z)], \quad q_2(z) = \Phi[f(z), g(z)]$$

where

$$(8.34) \quad f(z) = \frac{w_1(z)}{w_2(z)}, \quad g(z) = \frac{w_1'(z)}{w_2'(z)}$$

and $w_1(z)$ and $w_2(z)$ are linearly independent solutions of

(8.33). If $q_1(z) \equiv 0$, it follows from (5.1) that

$$(8.35) \quad g(z) = f(z) - \frac{2[f'(z)]^2}{f''(z)}$$

and

$$\Phi[f(z), g(z)] = \frac{1}{2}\{f(z), z\}.$$

In view of (8.35), formula (8.32) takes the form $g(z_1) \neq f(z_2)$, which by (8.34) is equivalent to the disfocality of the differential equation

$$(8.36) \quad w''(z) + \frac{1}{2}\{f(z), z\}w(z) = 0.$$

By Theorem 6, disfocality of (8.36) in the unit disk implies

$$(8.37) \quad |\{f(z), z\}| \leq \frac{2}{(1-|z|^2)^2}, \quad |z| < 1,$$

which is a sufficient condition for disconjugacy of (8.36) in $|z| < 1$. Since disconjugacy of (8.36) is equivalent to the univalence of $f(z)$ [4], our proof is accomplished.

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